Leuze

Original operating instructions

RSL 420
RSL 425
Safety Laser Scanner



The Sensor People

We reserve the right to make technical changes
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ПРОМЭЛЕКТРОНИКА / sales@prom-elec.com

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Leuze electronic GmbH + Co. KG
In der Braike 1
73277 Owen / Germany
Phone: +49 7021 573-0
Fax: +49 7021 573-199
www.leuze.com
info@leuze.com

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1 About this document

1.1 Other applicable documents

The information on the safety sensor is distributed over several documents to make working with the documents easier. You will find the documents and software for the safety sensor in the following table:

Purpose and target group of the document	Document/software title	Source
Software for users of the machine [a] for safety sensor diagnostics if a fault occurs and for machine design engineers for configuring the safety sensor	Sensor Studio DTM RSL 400	Supplied with the safety sensor on data carrier
Notes for the machine design engineer [a]	"Safe implementation and operation" (this document)	PDF, supplied with the safety sensor on data carrier
Notes for the machine design engineer [a] for configuring the safety sensor (software instructions)	Online help for software	Supplied with the safety sensor on data carrier
Notices regarding mounting, alignment and connection of the safety sensor	"Quick Start Guide RSL 400"	Print document, supplied with the safety sensor

a) Machine identifies the product that the safety sensor is installed in.

1.2 Downloading configuration software from the Internet

- Call up the Leuze home page: **www.leuze.com**.
- Enter the type designation or part number of the device as the search term.
- The configuration software can be found on the product page for the device under the Downloads tab.

1.3 Used symbols and signal words

Tab. 1.1: Warning symbols and signal words

	Symbol indicating dangers to persons
	Symbol indicating dangers from harmful laser radiation
	Symbol indicating possible property damage
NOTE	Signal word for property damage Indicates dangers that may result in property damage if the measures for danger avoidance are not followed.
CAUTION	Signal word for minor injuries Indicates dangers that may result in minor injury if the measures for danger avoidance are not followed.
WARNING	Signal word for serious injury Indicates dangers that may result in severe or fatal injury if the measures for danger avoidance are not followed.
DANGER	Signal word for life-threatening danger Indicates dangers with which serious or fatal injury is imminent if the measures for danger avoidance are not followed.

Tab. 1.2: Other symbols

	Symbol for tips Text passages with this symbol provide you with further information.
	Symbol for action steps Text passages with this symbol instruct you to perform actions.
	Symbol for action results Text passages with this symbol describe the result of the preceding action.

Tab. 1.3: Terms and abbreviations

CS	Switching signal from a control (**C**ontroller **S**ignal)
DTM	Software device manager of the safety sensor (**D**evice **T**ype **M**anager)
EDM	Contactor monitoring (**E**xternal **D**evice **M**onitoring)
FDT	Software frame for management of device managers (DTM) (**F**ield **D**evice **T**ool)
Field pair	A protective field with an associated warning field
AGV	**A**utomated **G**uided **V**ehicle
LED	LED, display element in the safety sensor (**L**ight **E**mitting **D**iode)
OSSD	Safety-related switching output (**O**utput **S**ignal **S**witching **D**evice)
PFH_d	Probability of a dangerous failure per hour (**P**robability of dangerous **F**ailure per **H**our)
PL	**P**erformance **L**evel
Quad	Two field pairs (four fields) that are monitored simultaneously in four field mode
TSS	**T**ransverse **S**ide-tracking **S**kate
RES	Start/restart interlock (Start/**RES**tart interlock)
SIL	**S**afety **I**ntegrity **L**evel
State	ON: device intact, OSSDs switched on OFF: device intact, OSSDs switched off Locking: device, connection or actuation/operation faulty, OSSDs switched off (lock-out)

1.4 Checklists

The checklists serve as a reference for the machine manufacturer or supplier (see chapter 11 "Testing"). They replace neither testing of the complete machine or system prior to the initial start-up nor their periodic testing by a competent person. The checklists contain minimum testing requirements. Depending on the application, other tests may be necessary.

2 Safety

Before using the safety sensor, a risk assessment must be performed according to valid standards (e.g. EN ISO 12100, EN ISO 13849-1, IEC 61508, EN IEC 62061). The result of the risk assessment determines the required safety level of the safety sensor (see chapter 15.1 "Safety-relevant technical data"). For mounting, operating and testing, this document as well as all applicable national and international standards, regulations, rules and directives must be observed. Relevant and supplied documents must be observed, printed out and handed to affected persons.

↳ Before working with the safety sensor, completely read and observe the documents applicable to your task.

In particular, the current version of the following national and international legal regulations apply for commissioning, technical tests and handling of safety sensors:

- Machinery Directive
- Low Voltage Directive
- Electromagnetic Compatibility Directive
- Use of Work Equipment Directive
- Directive on the restriction of the use of certain hazardous substances in electrical and electronic equipment
- OSHA
- Safety regulations
- Accident-prevention regulations and safety rules
- Ordinance on Industrial Safety and Health and employment protection act
- Product Safety Law (ProdSG)

	NOTICE
	For safety-related information you may also contact local authorities (e.g., industrial inspectorate, employer's liability insurance association, labor inspectorate, occupational safety and health authority).

2.1 Intended use

The safety sensor protects persons or body parts at points of operation, danger zones or access points of machines and systems.

	⚠ WARNING
	**A running machine may result in serious injury!** ↳ Make certain that the safety sensor is correctly connected and that the protective function of the protective device is ensured. ↳ Make certain that, during all conversions, maintenance work and inspections, the system is securely shut down and protected against being restarted.

- The safety sensor may only be used after it has been selected in accordance with the respectively applicable instructions and relevant standards, rules and regulations regarding labor protection and safety at work, and after it has been installed on the machine, connected, commissioned, and checked by a competent person (see chapter 2.3 "Competent persons").
- When selecting the safety sensor it must be ensured that its safety-related capability meets or exceeds the required Performance Level PL_r ascertained in the risk assessment (see chapter 15.1 "Safety-relevant technical data").
- The safety sensor may only be used in North America in applications that satisfy the requirements specified by NFPA 79.
- With the “access guarding” function, the safety sensor detects persons only when they enter the danger zone but cannot tell whether there are any persons inside the danger zone. For this reason, a start/restart interlock in the safety chain is essential in this case.
- The construction of the safety sensor must not be altered. When manipulating the safety sensor, the protective function is no longer guaranteed. Manipulating the safety sensor also voids all warranty claims against the manufacturer of the safety sensor.

- The safety sensor must be inspected regularly by a competent person to ensure proper integration and mounting (see chapter 15.1 "Safety-relevant technical data").
- The safety sensor must be exchanged after a maximum of 20 years. Repairs or the exchange of wear parts do not extend the mission time.

CAUTION

Observe intended use!

The protection of personnel and the device cannot be guaranteed if the device is operated in a manner not complying with its intended use.

- Only operate the device in accordance with its intended use.
- Leuze electronic GmbH + Co. KG is not liable for damages caused by improper use.
- Read these operating instructions before commissioning the device. Knowledge of the operating instructions is an element of proper use.

NOTICE

Comply with conditions and regulations!

- Observe the locally applicable legal regulations and the rules of the employer's liability insurance association.

2.1.1 Vapors, smoke, dust, particles

Vapors, smoke, dust and all particles visible in the air can cause the machine to switch off unintentionally. This can mislead the user into bypassing the safety devices.

- Do not use the safety sensor in environments in which heavy vapors, smoke, dust or other visible particles occur at the beam level.

2.1.2 Stray light

Light sources can impair the safety sensor's availability. Interfering light sources are:

- Infrared light
- Fluorescent light
- Strobe light

- Ensure that there are no interfering light sources at beam level.
- Prevent reflective surfaces at beam level.
- Where applicable, take protective field addition distances into account.
- Implement all additional measures to ensure that any special application of any effected beam types does not impair the safety sensor's operation.

2.1.3 Obstructions in the protective field

- Do not bring any additional window materials into the area monitored by the safety sensor.

NOTICE

No screen between optics cover and monitoring area!

- Between the optics cover of the safety sensor and the monitored area, no further screen may be mounted to protect the safety sensor.

2.2 Foreseeable misuse

Any use other than that defined under "Intended use" or which goes beyond that use is considered improper use.

In principle, the safety sensor is **not** suitable as a protective device for use in the following cases:

- Danger posed by ejected objects or the spraying of hot or hazardous liquids from within the danger zone.
- Applications in explosive or easily flammable atmospheres.
- Use for outdoor applications or under extreme temperature fluctuations.

  Humidity, condensation and other weather influences can impair the protective function.
- Use on vehicles with combustion engines.

  Alternators and ignition systems can cause EMC interferences.

	NOTICE
	**Do not modify or otherwise interfere with the safety sensor!** ↳ Do not carry out modifications or otherwise interfere with the safety sensor. The safety sensor must not be tampered with and must not be changed in any way. ↳ The safety sensor must not be opened. There are no user-serviceable parts inside. ↳ The construction of the safety sensor must not be altered. When manipulating the safety sensor, the protective function is no longer guaranteed. ↳ Manipulating the safety sensor voids all warranty claims against the manufacturer of the safety sensor. ↳ Repairs must only be performed by Leuze electronic GmbH + Co. KG.

2.3 Competent persons

Connecting, mounting, commissioning and adjustment of the safety sensor must only be carried out by competent persons.

Prerequisites for competent persons:

- They have a suitable technical education.
- They know the rules and regulations for labor protection, safety at work and safety technology and can assess the safety of the machine.
- They know the operating instructions for the safety sensor and the machine.
- They have been instructed by the responsible person on the mounting and operation of the machine and of the safety sensor.
- They perform a task related to the subject matter shortly thereafter and keep their knowledge up to date through continuous further training.

Certified electricians

Electrical work must be carried out by a certified electrician.

Due to their technical training, knowledge and experience as well as their familiarity with relevant standards and regulations, certified electricians are able to perform work on electrical systems and independently detect possible dangers.

In Germany, certified electricians must fulfill the requirements of accident-prevention regulations DGUV (German Social Accident Insurance) provision 3 (e.g. electrician foreman). In other countries, there are respective regulations that must be observed.

2.4 Disclaimer

Leuze electronic GmbH + Co. KG is not liable in the following cases:

- The safety sensor is not used as intended.
- Safety notices are not adhered to.
- Reasonably foreseeable misuse is not taken into account.
- Mounting and electrical connection are not properly performed.
- Proper function is not tested (see chapter 11 "Testing").
- Changes (e.g., constructional) are made to the safety sensor.

2.5 Laser safety notices – Laser class 1 for wavelength range outside 400 - 700 nm

NOTICE

Additional measures for shielding the laser radiation are not necessary (safe for eyes).

ATTENTION

LASER RADIATION – CLASS 1 LASER PRODUCT

The device satisfies the requirements of IEC/EN 60825-1:2014 safety regulations for a product of **laser class 1** and complies with 21 CFR 1040.10 except for conformance with IEC 60825-1 Ed. 3., as described in Laser Notice No. 56, dated May 8, 2019.

- Observe the applicable statutory and local laser protection regulations.
- The device must not be tampered with and must not be changed in any way.
  There are no user-serviceable parts inside the device.
  Repairs must only be performed by Leuze electronic GmbH + Co. KG.

2.6 Responsibility for safety

Manufacturer and operator must ensure that the machine and implemented safety sensor function properly and that all affected persons are adequately informed and trained.

The type and content of all imparted information must not lead to unsafe actions by users.

The manufacturer of the machine is responsible for:

- Safe machine construction and information on any residual risks
- Safe implementation of the safety sensor, verified by the initial test performed by a competent person
- Imparting all relevant information to the operating company
- Adhering to all regulations and directives for the safe commissioning of the machine

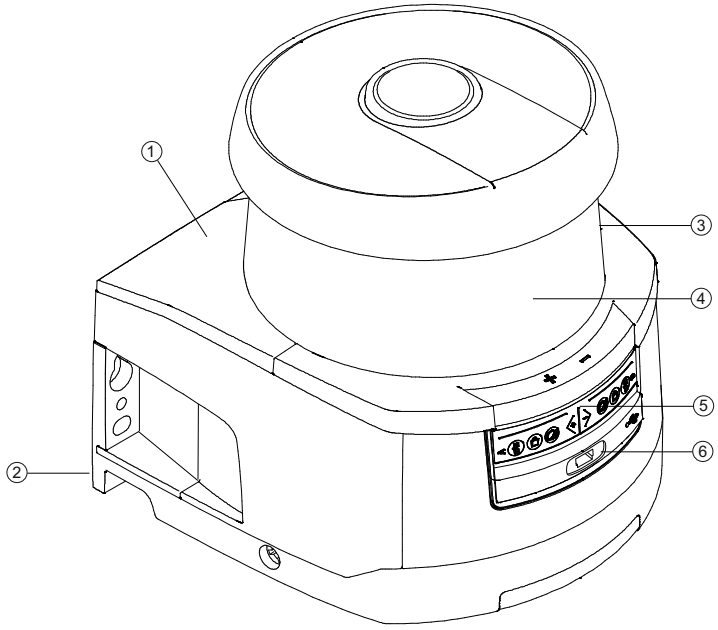
The operator of the machine is responsible for:

- Instructing the operator
- Maintaining the safe operation of the machine
- Adhering to all regulations and directives for labor protection and safety at work
- Regular testing by competent persons

3 Device description

The safety sensors from the RSL 400 series are optoelectronic, two-dimensional measuring safety laser scanners. They satisfy the following standards:

	RSL 400
Type in accordance with IEC 61496	3
Category in accordance with ISO 13849	3
Safety Integrity Level (SIL) in accordance with IEC 61508	2
SILCL in accordance with IEC 62061	2
Performance Level (PL) in accordance with ISO 13849-1	d



1 Scanner unit
2 Connection unit
3 Optics cover
4 Alphanumerical display (displayed)
5 LED indicators
6 Mini-B USB connection (behind protective cap)

Fig. 3.1: Device overview of RSL 400 safety laser scanners

All safety sensors of the RSL 420 and RSL 425 series are equipped as follows:

- Laser scanner with the range class **S**, **M**, **L** or **XL**:

Operating range class	Operating range [m]
S	3.00
M	4.5
L	6.25
XL	8.25

  - 24-digit alphanumerical display
  - Integrated electronic spirit level for aligning the safety sensor
  - LED indicator
  - USB interface

NOTICE



- Use the USB connection only temporarily for configuration or diagnosis of the safety sensor.
- For permanent connection, connect the safety sensor to the Ethernet connection of the connection unit.

- Connection unit:
  - Configuration memory
  - Ethernet connection for communication and configuration with the PC/laptop
  - Electrical connection to the machine via connection cable

3.1 Device overview

The following table provides an overview of the possible uses, features and functions of the RSL 400 safety sensors.

Tab. 3.1: Device overview

	RSL 410	RSL 420 RSL 425	RSL 430	RSL 440 RSL 445
Stationary danger zone guarding	x	x	x	x
Mobile danger zone guarding	x	x	x	x
Access guarding	x	x	x	x
Point of operation guarding	x	x	x	x
Safety-related switching outputs	1 OSSD pair	1 OSSD pair	2 OSSD pairs	2 OSSD pairs
Protective function A	x	x	x	x
Protective function B	-	-	x	x
Signal outputs	Up to 3	Up to 4	Up to 9	Up to 9
Configurable signal outputs	x	x	x	x
Number of changeover-capable protective/warning field pairs	1	10	10 + 10	100
E-stop linkage	-	x	x	x
Four field mode (quads)	x	x	x	x
Internal safe time delay	-	-	x	x
Measurement data output optimized for vehicle navigation	-	Only RSL 425	-	Only RSL 445
USB interface	-	x	x	x

3.1.1 Protective function of RSL 400 safety sensors

The safety sensor transmits periodic light pulses via a rotating deflection unit. The light pulses are scattered in all directions by obstacles, e.g. persons. A part of the light pulses is received again by the safety sensor and evaluated. The safety sensor calculates the precise position of the object from the propagation time of the radiated light and the current angle of the deflection unit at that time. If the object is within a predefined area, the protective field, the safety sensor performs a safety-related switching function. It switches the safety-related switching outputs off.

Only when the protective field is free again does the safety sensor reset the safety-related switching function, either automatically or following acknowledgment, depending on the operating mode.

The safety sensor can even detect people when they are wearing very dark clothes, which have a very weak diffuse reflectance.

3.1.2 Parameters for protective function

The following parameters for switching off the safety-related switching outputs of the safety sensor are taken into consideration for the protective function:

- Configurable protective fields
- Reference contour of protective fields
- Configurable field pair changeover
- Selectable resolution for hand, leg or body detection
- Safety sensor response time
- Selectable start-up behavior

The following non-safety-oriented functions and signals also belong to the protective function:

- Configurable warning fields
- Configurable indication signals

Additional functions of the protective function

- Warning field evaluation
- Selectable dynamic contactor monitoring (EDM)
- E-Stop

3.1.3 Device and monitoring functions

- Monitoring and release of field pair changeover

3.2 USB connection

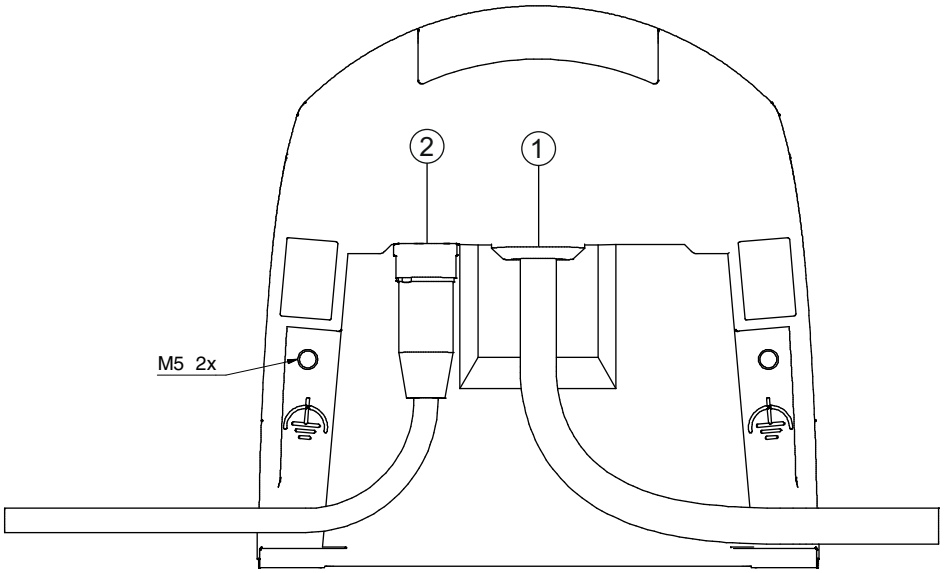
The safety sensor features a Mini-B type USB socket as a service interface for configuration and diagnosis.

	NOTICE
	↳ Use the USB connection only temporarily for configuration or diagnosis of the safety sensor. ↳ For permanent connection, connect the safety sensor to the Ethernet connection of the connection unit.

	NOTICE
	↳ After use, seal the USB connection using a protection cap. Make sure that the protection cap is felt to engage when sealing. The IP degree of protection specified in the technical data is only achieved when the protection cap is closed.

3.3 Connection unit

The safety sensor is mounted, connected and aligned using the connection unit.



1	Connection cable, connection to the machine
2	M12 socket, D-coded, Ethernet communication connection
M5	Connection for functional earth with M5 x 10 self-cutting/self-tapping (gas tightness) and ground strap

Fig. 3.2: Device overview, connection unit

Functions of connection unit:

- Attachment point for mounting, either directly or using an optional mounting system.
  When devices are swapped out, the connection unit remains mounted and aligned.
- EMC wiring for signal inputs/outputs and supply using connection cable

Safety sensor	Connection unit	Connection
RSL 420	CU416-y y=5000, 10000, 25000	Connection cable, 16-wire 5 m, 10 m, 25 m

- Connector bushing and EMC for the Ethernet TCP/IP communication and configuration interface to the PC/laptop
- Memory for the configuration files and automatic parameter transfer in the event of device swap-out
- Quick-release connection to the scanner unit (see Quick Start Guide) for easy device swap-out

NOTICE	
	To ensure the IP protection and leak tightness of the devices, the supplied protection caps must always be placed on unused connections.

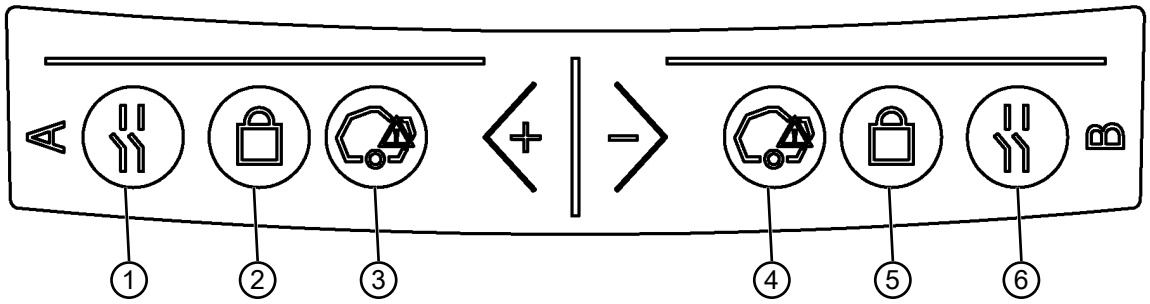
3.4 Display elements

The display elements of the safety sensors simplify start-up and fault analysis.

3.4.1 LED indicator

Located on the connection unit are the LEDs for displaying the operating state.

- Protective function A: LEDs 1, 2, 3



1 LED 1, red/green
2 LED 2, yellow
3 LED 3, blue
4 LED 4, blue
5 LED 5, yellow
6 No function

Fig. 3.3: LED indicators

Tab. 3.2: Meaning of the LEDs

LED	Color	State	Description
1	Red/green	OFF	Device switched off
		Red	OSSD off
		Red, flashing	Error
		Green	OSSD on
2	Yellow	OFF	RES deactivated RES activated and enabled
		Flashing	Protective field occupied
		ON	RES activated and blocked but ready to be unlocked Protective field free and linked sensor enabled (if applicable)
3	Blue	OFF	Free warning field
		ON	Warning field interrupted
4	Blue	OFF	Four field mode: warning field 3 free
		ON	Four field mode: warning field 3 interrupted
5	Yellow	Flashing	Four field mode: warning field 2 interrupted

3.4.2 Alphanumerical display

In normal operation, the 24-digit alphanumerical display of the safety sensor shows the monitored protective and warning field pairs. It also provides assistance during detailed error diagnostics (see chapter 12 "Diagnosis and troubleshooting").

Tab. 3.3: Alphanumerical displays

Display	Description	Example
Upon startup without configuration/upon initial commissioning		
Sensor type	Sensor type	420M
Software version	Software version of the device	V5.1
Sensor serial number	Sensor serial number	SN: 21513123456
Sensor name / Network name	Name of the sensor / network	A123456789
IP: DHCP/FIX	DHCP or permanent IP address	IP: DHCP IP: 10.25.45.2
Bluetooth on/off	Bluetooth detection ON/OFF	Bluetooth ON
Configuration necessary	Configuration required	CONFIG REQUESTED
Repeated until end of booting phase / start phase, then		
Spirit level permanent	Horizontal alignment in degrees: H Vertical alignment in degrees: V	H -3° V +9°
Upon startup with configuration		
Sensor type	Sensor type	410XL
Software version	Software version of the device	V5.1
Sensor serial number	Sensor serial number	SN: 21513123456
Sensor name / Network name	Name of the sensor / network	A123456789
IP: DHCP/FIX	DHCP or permanent IP address	IP: DHCP IP: 10.25.45.2
Bluetooth on/off	Bluetooth detection ON/OFF	Bluetooth ON
Date of configuration	Date of configuration	11/13/2014 08:15
Signature	Signature of configuration	DG45L8ZU
Level	Horizontal alignment in degrees: H Vertical alignment in degrees: V	H-3° V+9°
Repeated until end of booting phase / start phase, then		
Display following configuration of normal operation e.g. display of active field pair		 A1.1
Transfer of the configuration data		
AWAITING CONFIG	Until downloading of configuration data is confirmed	
DOWNLOAD CONFIG	During transfer of configuration data	
Level		
H +/- ..° V +/- .. °	Horizontal alignment in degrees: H Vertical alignment in degrees: V	H -3° V +9°

Display	Description	Example
Sensor detection		
PING received	Display for identification by device name	PING received *Device name*
Message		
	Message via a signal output or diagnosis ID	ProtF A: E123 Device: P007 - wrong Config
Error diagnostics		
F…	**F**ailure, internal device error	
E…	**E**rror, external error	
U…	**U**sage info, application error	
I…	**I**nformation	
P…	**P**arameter, inconsistency in the configuration	

For error diagnostics, the error's respective letter is displayed first followed by the number code. An AutoReset is carried out after 10 seconds for errors that do not cause locking, with an unauthorized restart being impossible. In the case of blocking errors, the voltage supply must be separated and the cause of the error must be eliminated. Before switching on again, the steps taken before initial commissioning must be repeated (see chapter 10 "Starting up the device").

When the protective field has been free for about 5 seconds, the device switches back to the display in normal operation.

Displays in normal operation

The display in normal operation depends on the operating state of the safety sensor. The display can be switched off or rotated by 180° by means of the software.

3.4.3 Field-of-view display

The upper and lower limit of the safety sensor's field of view can be displayed by means of horizontal lines on the optics cover.

↳ Make sure that the safety sensor's field of view is always completely unobstructed.

	NOTICE
	**Always check the protective field configuration!** ↳ Check all defined protective fields each time the configuration is changed. The field-of-view display is a comfort function and is not intended as a substitute for checking the protective field configuration. ↳ The safety sensor's field of view must be completely unobstructed on the application side.

3.5 Mounting system (optional)

Mounting systems and mounting brackets simplify mounting and alignment of the safety sensor. Mounting systems and mounting brackets are available as accessories (see chapter 17 "Order guide and accessories").

3.6 Loop guard (optional)

The loop guard for the optics cover prevents damage to the safety sensor caused by light contact with foreign objects. The loop guard is available as an accessory (see chapter 17 "Order guide and accessories").

4 Configuration and diagnostic software Sensor Studio

To start up a safety sensor in your application, the safety sensor must be set up according to its specific use using the configuration and diagnostic software. The software is used to set up the safety configuration of the safety sensor, to change the communication and diagnostics settings and to perform diagnostic routines. Communication takes place via the PC.

The software is designed according to the FDT/DTM concept:

- You make the individual configurations for the safety sensor in the Device Type Manager (DTM).
- The individual DTM configurations of a project can be called up via the frame application of the Field Device Tool (FDT).
- Each device DTM has a communication DTM that sets up and monitors the communication connections to the sensor.

	NOTICE
	Only use the software for safety sensors manufactured by **Leuze.**

4.1 System requirements

To use the software, you need a PC or laptop with the following specifications:

Hard disk space	At least 250 MB free memory If you want to save the protective field or configuration values, you will need more memory.
Screen display	Color
External drive	DVD drive
Input device	Keyboard and mouse or touchpad
Output device	Printer (black-white or color)
Interfaces	RJ45 Ethernet network Bluetooth (optional) - If the PC does not have integrated Bluetooth technology, use an appropriate USB or PCMCIA adapter if necessary.
Operating system	Microsoft® Windows 7 or higher

	NOTICE
	Only the term "PC" is used below.

4.2 Installing software

Prerequisites:

- You do **not** need the safety sensor to install the software on the PC.
- All Windows applications are closed.

	NOTICE
	The software is installed in two steps: ↳ Installing the *Sensor Studio* FDT frame. ↳ Installing *LeSafetyCollection* device manager (DTM).

Installing the Sensor Studio software

NOTICE
If FDT frame software is already installed on your PC, you do not need the *Sensor Studio* installation. You can install the device manager (DTM) in the existing FDT frame.

- Insert the data carrier.
- ⇨ The installation will start automatically.
- If installation does not start automatically, double-click the file *SensorStudioSetup.exe*.
- If you want to call up the menu of the CD, double-click the file *start.exe*.
- Select a language for the interface text in the installation wizard and software and confirm with [OK].
- ⇨ The installation wizard starts.
- Click [Next].
- ⇨ The installation wizard opens the software license agreement.
- If you want to accept the license agreement, select the appropriate option field and click [Next].
- If the suggested installation path is OK, click [Next].
  If you want to specify a different path, click the [Browse] button. Select a different path, confirm with [OK] and click [Next].
- Click the [Install] button to start installation.
- ⇨ The wizard installs the software and places a shortcut on the desktop ( ).
- Click the [Finish] button to complete installation.

Installing *LeSafetyCollection* device manager (DTM)

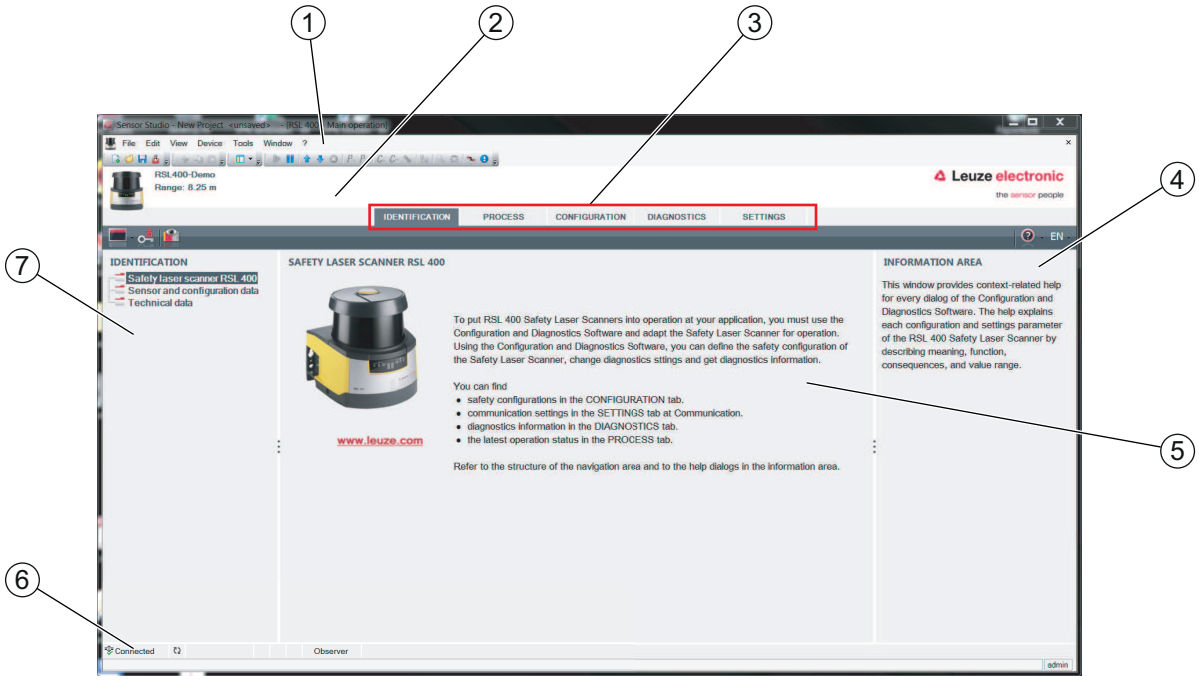
Prerequisites:

- The *Sensor Studio* software is installed on the PC.
- Data carrier inserted.

- Double-click the file *LeSafetyCollectionSetup.exe*.
- Select a language for the interface text in the installation wizard and software and confirm with [OK].
- ⇨ The installation wizard starts.
- Click [Next].
- ⇨ The installation wizard opens the software license agreement.
- If you want to accept the license agreement, select the appropriate option field and click [Next].
- If the suggested installation path is OK, click [Next].
  If you want to specify a different path, click the [Browse] button. Select a different path, confirm with [OK] and click [Next].
- Click the [Install] button to start installation.
- ⇨ The wizard installs the software.
- Click the [Finish] button to complete installation.

NOTICE
During installation of the software, a user *admin* (without password query) is created so that you can start the software without user identification. If other users are registered (**Tools > User management** in the FDT frame menu), you must log in at the software with a user name and password. This setting allows you to connect to the safety sensor and to read out, upload, enter or change the safety configuration and all settings using the RSL 400 device DTM. The password for the safety sensor only needs to be entered (i.e. the access level only needs to be changed) when the changes are downloaded to the safety sensor (see chapter 4.5.1 "Selecting access level").

4.3 User interface



1 FDT frame menu with toolbar
2 RSL 400 device manager (DTM)
3 Navigation tabs
4 Information area
5 Dialog box
6 Status line
7 Navigation area

Fig. 4.1: User interface of the software

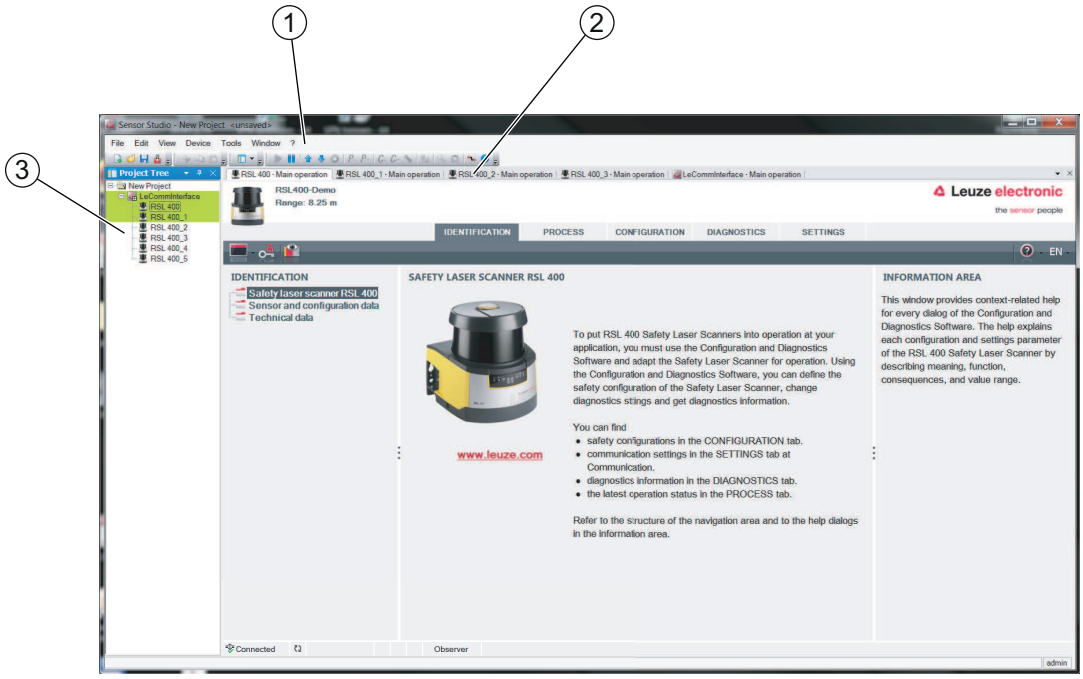
FDT frame menu

The device managers (DTM) of the safety sensors are created and managed in the FDT frame menu.

Device manager DTM

Configuration projects for setting up the selected safety sensor are created and managed in the device managers (DTM) of the safety sensors.

Project tree view



1 FDT frame menu
2 Device manager (DTM) tabs
3 Project tree view

Fig. 4.2: User interface with project tree view

The project tree view shows the structure of the currently installed device managers (DTM). In the project tree view you can, for example, add copies of an already configured device manager (DTM) quickly and easily to the DTM structure if you want to operate multiple safety sensors with the same configuration settings.

Example: AGV with safety sensors on front and rear side

4.4 FDT frame menu

NOTICE
You can find complete information on the FDT frame menu in the online help system. Select the **Help** menu item in the menu [?].

4.4.1 Project wizard

Using the Project Wizard you can create and change configuration projects for setting up the safety sensor (see chapter 4.5 "Using configuration projects").

↳ Start the Project Wizard in the FDT frame menu by clicking the  button.

NOTICE
Information on the Project Wizard can be found in the online help for the FDT frame menu under **Sensor Studio Options**.

4.4.2 DTM change

The *DTM Change* function makes it easier for you to call up the communication DTM of a device or change from device DTM to communication DTM.

↳ Start the *DTM change* function in the FDT frame menu by clicking the button.

NOTICE
Information on *DTM change* can be found in the online help for the FDT frame menu under **Sensor Studio Options**.

4.4.3 User management

Using the user management in the FDT frame menu, you can create users, log users in/out and manage passwords.

Creating users

When creating a user in the user management via **Tools > User management** in the software frame menu, select the access level for the user. For information on access permissions and access levels (see chapter 5.1 "Authorization concept of safety sensor").

↳ In the FDT frame menu, click **Tools > User management > Create user**.

Logging users in/out

Prerequisites:

- Users have been created

↳ In the FDT frame menu, click **Tools > Log in/log out**.

Managing passwords

Prerequisites:

- Users have been created

↳ In the FDT frame menu, click **Tools > Change password**.

NOTICE
Password management via the FDT frame menu applies to all installed device managers (DTM) of the project. Whenever write access occurs, the safety sensors of the RSL 400 series always check the access level (*Engineer*, *Expert*) and the password defined via the device manager (DTM) (**SETTINGS > Passwords**) independently of the password management via the FDT frame menu.

4.4.4 Exiting Sensor Studio

When you have finished making the configuration settings, close the configuration and diagnostics software.

↳ Exit the program via **File > Exit**.

↳ Save the configuration settings as a configuration project on the PC.

You can open the configuration project again at later time via **File > Open** or with the *Sensor Studio* Project Wizard ( ).

4.5 Using configuration projects

Configuration projects are created and managed in the device manager (DTM) of the selected safety sensor.

	NOTICE
	During installation of the software, a user *admin* (without password query) is created so that you can start the software without user identification. If other users are registered (**Tools > User management** in the FDT frame menu), you must log in at the software with a user name and password. This setting allows you to connect to the sensor and to read out, upload, enter or change the safety configuration and all settings using the RSL 400 device DTM. The password for the sensor only needs to be entered (i.e. the access level only needs to be changed) when the changes are downloaded to the safety sensor (see chapter 4.5.1 "Selecting access level").

↳ Start the configuration and diagnostics software on the PC by double-clicking the button.

⇨ The **mode selection** of the Project Wizard is displayed.

⇨ If the **mode selection** is not shown, start the Project Wizard in the FDT frame menu by clicking the [Project Wizard] button ( ).

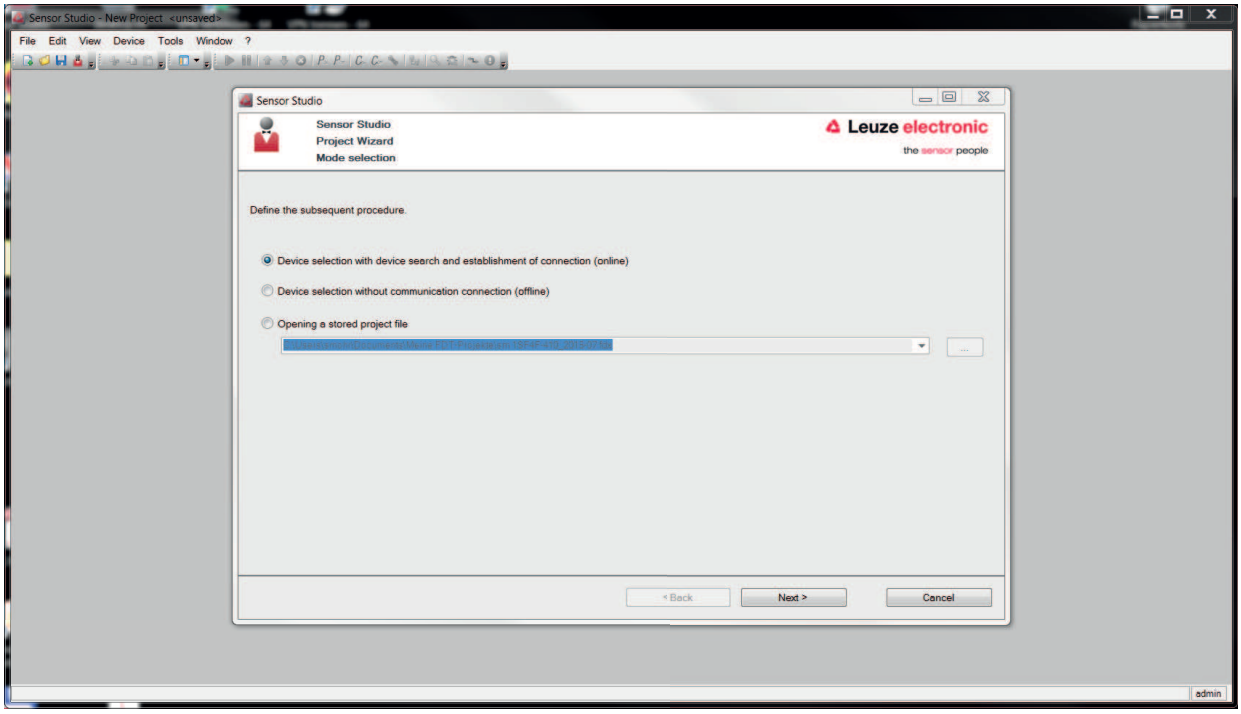


Fig. 4.3: Project wizard

↳ Select the configuration mode and click [Next].

⇨ Automatic connection to a connected safety sensor (**Online**)

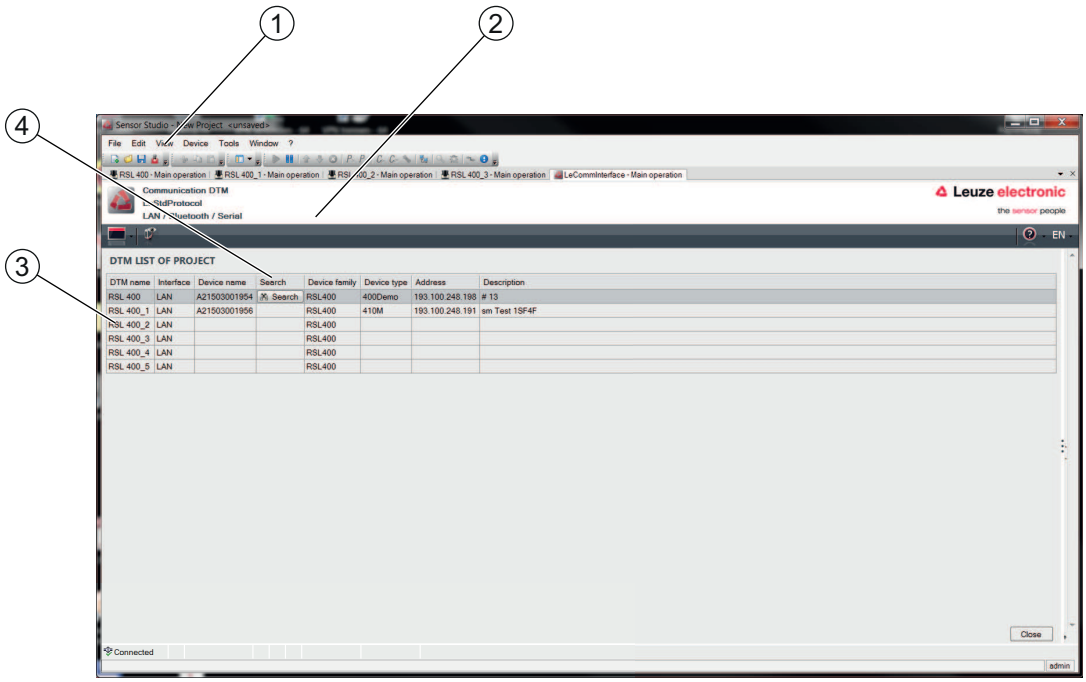
⇨ Device selection without communication connection (**offline**)

⇨ Load a saved project again

⇨ The project wizard displays the **SEARCH DEVICES** dialog box.

↳ Select the interface and click the [Start] button.

↳ Find the safety sensor for your configuration project using the search function of the communication DTM.



1 FDT frame menu
2 Communication DTM
3 Device list
4 Search function

Fig. 4.4: Communication DTM with search function

⇨ The project wizard displays the device list of configurable safety sensors in the **SEARCH DEVICES** dialog box.

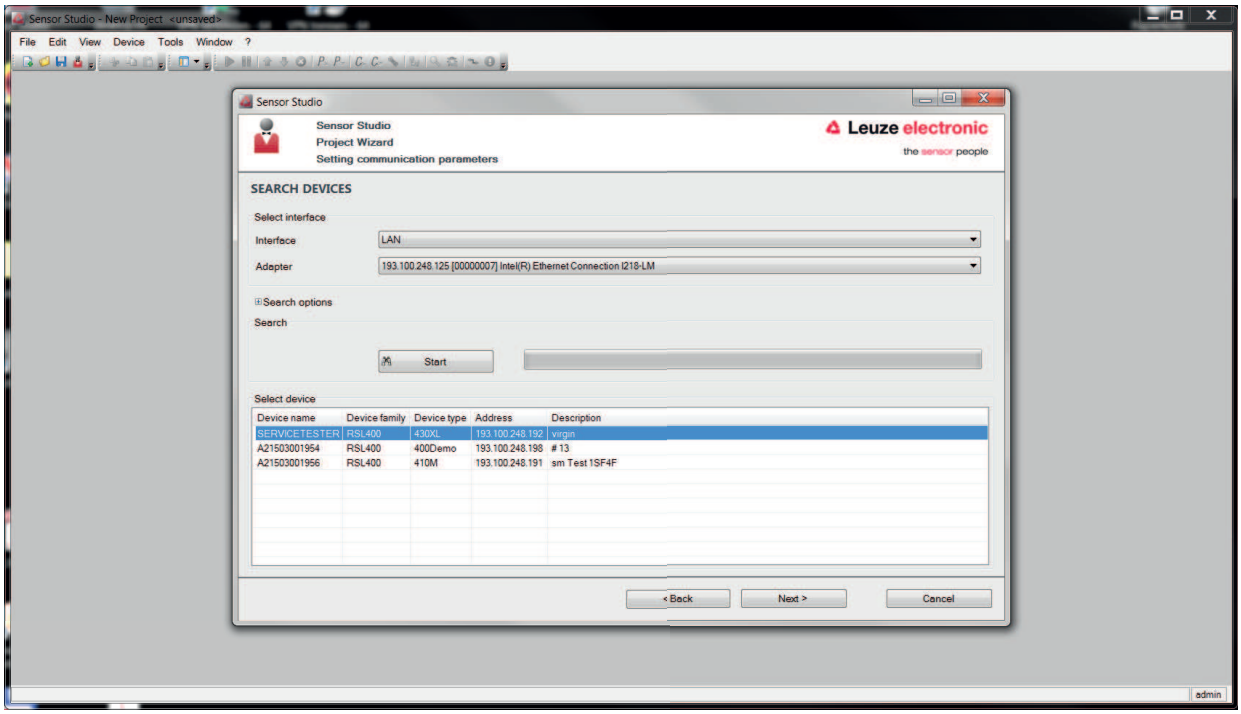


Fig. 4.5: Device selection in project wizard

↳ Select the safety sensor from the device selection list and click [Next].

⇨ The device manager (DTM) of the safety sensor shows the initial screen for the configuration project.

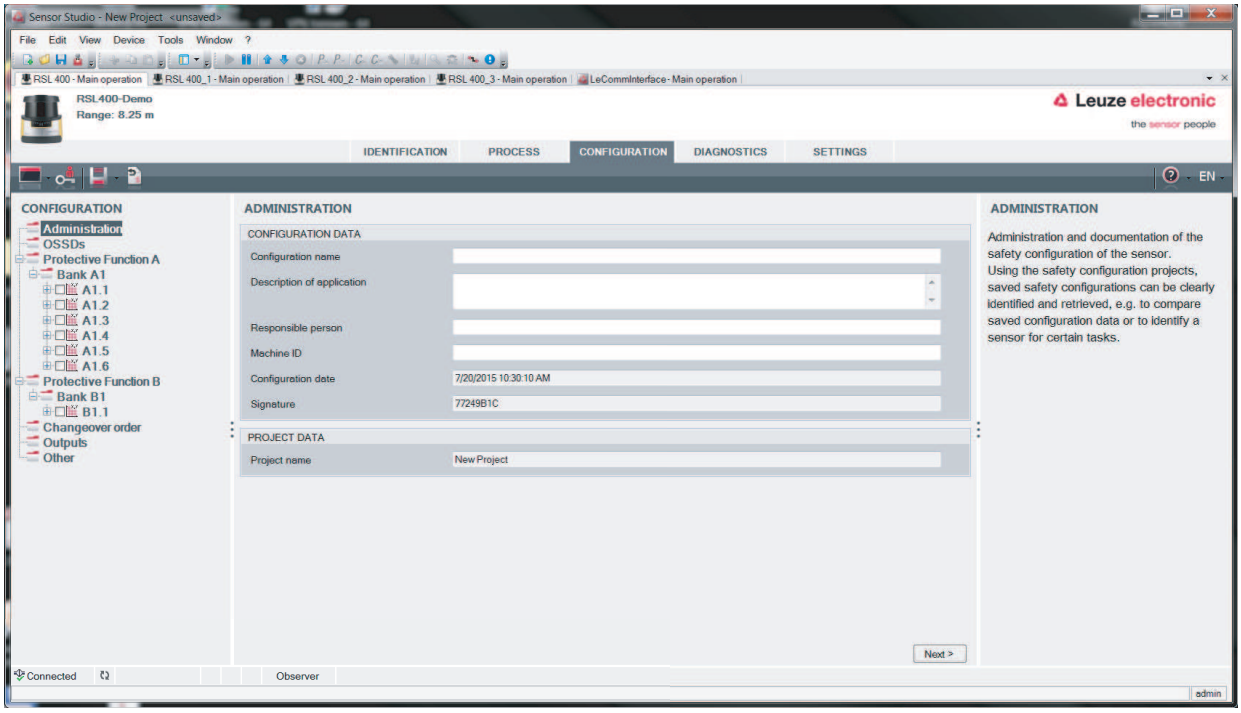


Fig. 4.6: Initial screen for safety configuration

NOTICE
The device manager (DTM) starts without querying the access level of the user. During communication with the safety sensor, the safety sensor does however query the access level of the user. To change the access levels (see chapter 4.5.1 "Selecting access level").

Setting device manager

Using the menus of the device manager (DTM) you can set the parameters of the safety configuration. The online help system provides information on the menu items and adjustment parameters. Select the **Help** menu item in the menu [?].

4.5.1 Selecting access level

Using the device manager you can change the access level of the user if necessary.
For the authorization concept of the software, see chapter see chapter 5.1 "Authorization concept of safety sensor".

↳ Click in the DTM menu bar on the [Change access level] button ( ).

⇨ The **Change access level** dialog box opens.

↳ In the *Access level* list, select the item *Expert*, *Engineer* or *Observer* and enter the default password or the password defined for the individual user.

The following access levels are available:

- *Observer* can read everything (no password)
- *Expert* can change communication and diagnostics settings (default password = **comdiag**)
- *Engineer* can additionally change the safety configuration (default password = **safety**)

The password is case-sensitive (i.e. a distinction is made between upper-case and lower-case letters).

↳ Confirm with [OK].

4.5.2 IDENTIFICATION

Detailed information on the menu items and setting parameters can be found in the information area and in the online help. Select the **Help** menu item in the menu [?].

- RSL 400 safety laser scanner
- Sensor and configuration data
- Technical data

4.5.3 PROCESS

Detailed information on the menu items and setting parameters can be found in the information area and in the online help. Select the **Help** menu item in the menu [?].

- Sensor display
  Device display in the DTM menu
  - SENSOR DISPLAY
  - STATE OF THE ACTIVE PROTECTIVE AND WARNING FIELDS
  - SENSOR DATA
- Measurement contour
- Inputs / outputs
  - SENSOR DISPLAY
  - CONNECTIONS AND SIGNALS
- Simulation – only with access level *Engineer*
  - Measurement contour
  - Inputs / outputs

4.5.4 CONFIGURATION

see chapter 9 "Configuring the safety sensor"

	NOTICE
	You can only transfer changes made in the **CONFIGURATION** menu to the safety sensor if you are logged in with the access level *Engineer*.

4.5.5 DIAGNOSIS

Adjustment / Alignment

Display of safety sensor alignment using the integrated electronic spirit level

Prerequisites: The software and safety sensor are connected.

↳ In the **DIAGNOSIS** menu, click the [Align sensor mechanically] button ( ).

⇨ The safety sensor display shows the horizontal and vertical alignment in degrees.

Visually identify device

If you have installed multiple safety sensors, identify the safety sensor that is connected to the currently open device manager (DTM).

Prerequisites: The software and safety sensor are connected.

↳ In the **DIAGNOSIS** menu, click the [Visually identify sensor] button ( ).

⇨ In the display of the safety sensor connected to the device manager (DTM), the message "PING received" flashes for ten seconds.

Reset sensor

Acknowledge messages and faults

Set safety sensor to safety mode

Create and save service file

The service file contains all available information on the safety sensor as well as configuration and settings.

When requesting support, send the service file to the Leuze customer service (see chapter 14 "Service and support").

Sensor display

Device display in the DTM menu

- SENSOR DISPLAY
- STATE OF THE ACTIVE PROTECTIVE AND WARNING FIELDS
- SENSOR DATA

Diagnostics list

Access list

EventLog

4.5.6 SETTINGS

	NOTICE
	You can only transfer changes made in the **SETTINGS** menu to the safety sensor if you are logged in with the access level *Engineer*.

Communication

- LAN
  - DHCP
  - CONNECTION SETTINGS
  - MAC address
- USB
  - DHCP
  - CONNECTION SETTINGS
  - Sensor data
- Bluetooth
  - Activate Bluetooth module
  - Activate device scan
  - Bluetooth address

EventLog

Trigger signals output when certain events occur, are recorded and shown in the event list of the safety sensor.

Information on the monitored signals can be found in the *Sensor Studio* configuration software in the information area and in the online help. Select the **Help** menu item in the menu [?].

Sensor display

Activation of the safety sensor alphanumerical display.

Information on the display options can be found in the *Sensor Studio* configuration software in the information area and in the online help. Select the **Help** menu item in the menu [?].

Passwords

	NOTICE
	If a user has forgotten his password for login at the safety sensor or has repeatedly entered the password incorrectly, he cannot log in at the safety sensor. The **CHANGE PASSWORD** function is therefore not available. To reset the password, a user must generate a reset password and have it confirmed by the manufacturer.

CHANGE PASSWORD

↳ Define individual passwords for the access levels *Engineer* and *Expert*. These passwords replace the default passwords set by the manufacturer.
The password is case-sensitive (i.e. a distinction is made between upper-case and lower-case letters).

Reset password

Prerequisites:

- The software is connected to the safety sensor.

↳ Generate a one-time password.
Note down the generated reset password.

↳ Send the reset password to the Leuze customer service for confirmation (see chapter 14 "Service and support").
The device can now be switched off and the connection can be terminated.

↳ Enter the confirmed reset password and create a new password.

Optics cover

- Monitoring of optics cover
- Dialog box for calibrating a replacement optics cover

Field editor display options

Display settings for the field editor when defining protective/warning fields.

- CONTOUR ALIGNMENT
- COORDINATE DISPLAY
- EDITOR BEHAVIOR

Information on the display options can be found in the *Sensor Studio* configuration software in the information area and in the online help. Select the **Help** menu item in the menu [?].

5 Functions

The functions of the safety sensor must be matched to the respective application and its safety requirements. You can activate/deactivate the functions and adapt them using parameters. You configure the functions with the help of the configuration and diagnostics software (see chapter 9 "Configuring the safety sensor").

- You configure the functions of the safety sensor in the software as configuration projects.
- In each configuration project you determine the protective function and the configurable field pairs via the selected function mode.
- The changeover-capable protective/warning field pairs for the selected function mode are defined in configuration banks.
- You determine the resolution, the start-up behavior, the response time and, where applicable, the vehicle speed together for all protective/warning field pairs of a configuration bank.

5.1 Authorization concept of safety sensor

User management allows target-group-oriented communication between the software and the safety sensor. Which functions are available depends on the selected **access level** of the user. For information on the software and on user management (see chapter 4 "Configuration and diagnostic software Sensor Studio").

- Changing the safety configuration as well as the communication and diagnostics settings of the sensor is only permitted for certain access levels.
- Installation and operation of the software do not depend on the access level of the user.

The following access levels are available:

Tab. 5.1: Access levels and functions available

Access level	Functions
Observer	• Display the measurement contour • Upload and display configuration data from the safety sensor • Display status information from the safety sensor • Display diagnostics list • Customize display • Display and evaluate the measurement contour • Load configuration data from the safety sensor • Load status information from the safety sensor • Display diagnostics list • Create service file • Reset password
Expert	In addition to the functions of the *Observer* • Load the signed safety configuration from a file and transfer/download to the safety sensor • Transfer changed communication and diagnostics settings from the PC to the safety sensor • Print configuration data incl. protective/warning fields • Calibrate optics cover

Access level	Functions
Engineer	In addition to the functions of the *Expert*, full access to all user-relevant functions and parameters: Create and change a safety configuration: • Save configuration data to file • Change all parameters of configuration • Reset safety sensor to default values • Define and change protective/warning fields • Set reference contour in protective field • Print and delete protective/warning fields • Load protective/warning field data from file • Save protective/warning field data • Transfer protective/warning field data from the PC to the safety sensor • Change passwords

	NOTICE
	The software saves individual passwords in the connected safety sensor, thereby ensuring that only authorized users can change the existing configuration.

Determining access level

When creating a user in the user management via **Tools > User management** in the FDT frame menu, select the access level for the user. In the user management you can also create and change passwords for the users.

Using the device manager (DTM) you can change the access level of the user (see chapter 4.5.1 "Selecting access level").

↳ Click in the DTM menu bar on the [Change access level] button ().

5.2 Function modes of safety sensor

You configure the functions of the safety sensor in configuration projects with the help of the configuration and diagnostics software. In each configuration project you determine the protective function and the configurable field pairs via the selected function mode.

You select the function mode of the safety sensor in the software device manager (DTM) with **CONFIGURATION > OSSDs** (see chapter 9 "Configuring the safety sensor").

You use the protective function to define the criteria for switching off the safety-related switching outputs (see chapter 3.1.2 "Parameters for protective function").

The changeover-capable protective and warning field pairs for the selected function mode are defined in the configuration banks, e.g. **CONFIGURATION > Protective function A > Bank A1**.

Overview of the function modes

Tab. 5.2: Function modes

Function mode	Field pairs (FP) Protective fields (PF) Warning fields (WF)	Field pair activation
One protective function	1 FP / 1 PF + 1 WF	Fixed selection of one field pair
	5 FP / 5 PF + 5 WF	Selection by signal input: • Overlapped monitoring
	10 FP / 10 PF + 10 WF	Selection by signal input: • Fixed changeover moment

Function mode	Field pairs (FP) Protective fields (PF) Warning fields (WF)	Field pair activation
One protective function – four field mode	1 FP / 1 PF + 3 WF	Fixed selection of one field pair
	10 FP+ 10 FP / 10 PF + 30 WF	Selection by signal input: • Fixed changeover moment

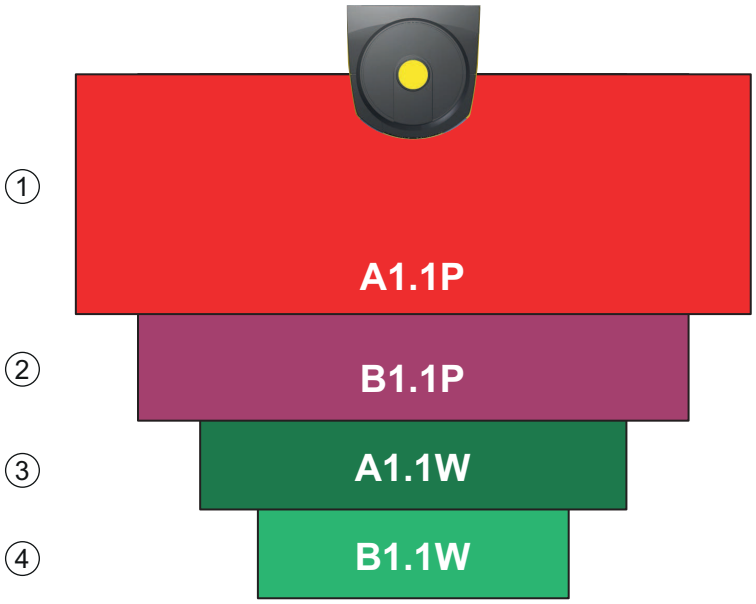
5.2.1 One protective function

Ten changeover-capable field pairs for safety-related switching outputs OSSD-A. For the field pair changeover, see chapter 5.7 "Field pair changeover".

5.2.2 One protective function – four field mode

The safety sensor monitors one protective field and three warning fields.

Monitoring is performed together for the field pairs of protective function A and protective function B. If, for example, the control system is monitoring field pair A1.1 for protective function A, field pair B1.1 for protective function B is also monitored.



1 Protective function A: protective field
2 Protective function B: protective field
3 Protective function A: warning field
4 Protective function B: warning field

Fig. 5.1: Four field mode

If the protective field of protective function A is violated, safety-related switching outputs OSSD-A switch.

If the protective field of protective function B is violated, the indication signal B-CLEAR is generated – the safety-related switching outputs do not switch.

The signals are assigned to the switching outputs via the configuration and diagnostics software (**CONFIGURATION > Outputs**; see chapter 9 "Configuring the safety sensor").

Tab. 5.3: Example: Assignment of signals to switching outputs

Logic signal	Electrical switching output	Description
OSSD A	Safety-related switching outputs OSSD A	Protective function A: protective field violation
B-CLEAR	Switching output MELD – not safe	Protective function B: protective field violation
A-WF-VIO	Switching output A1	Protective function A: Violation of warning field
B-WF-VIO	Switching output EA1	Protective function B: Violation of warning field

5.3 Selectable resolution for hand, leg and body detection

The application-specific resolution of the safety sensor is defined in the configuration project together for all protective/warning field pairs of a configuration bank.

Tab. 5.4: Resolution of the safety sensor depending on the function

Safety sensor resolution [mm]	Function	Application(s)
30	Hand detection	Point of operation guarding
40	Arm detection	Point of operation guarding
50	Leg detection with the safety sensor mounted close to floor level	Danger zone safeguarding
60	• Leg detection with the safety sensor mounted at a height of 150 mm • Leg detection and detection of lying persons in the case of mounting on vehicles, mounting height approx. 200 mm	Stationary danger zone safeguarding Mobile danger zone safeguarding
70	• Leg detection with the safety sensor mounted at a height of 300 mm	Stationary danger zone safeguarding Mobile danger zone safeguarding
150	Body detection	Access guarding Mobile side guarding
Mounting height = Height of the scan level above floor level		

5.4 Speed-dependent protective function for vehicles

For object detection in the case of mobile applications, the safety sensor evaluates the relative speed of the object. If the safety sensor is mounted on vehicles or on moving parts of machines, the maximum speed of the vehicle must be entered during configuration of the protective function.

The maximum vehicle speed (*Max. AGV speed*) is selected in the configuration project together for all protective/warning field pairs of a configuration bank.

5.5 Response time

The response time is the maximum time from a protective field violation to switch-off of the safety-related switching outputs.

The response time is selected in the configuration project together for all protective/warning field pairs of a configuration bank.

5.6 Configurable start-up behavior

The start-up behavior is selected in the configuration project together for all protective/warning field pairs of a configuration bank.

5.6.1 Automatic start/restart

The machine starts automatically as soon as the machine is switched on or the supply voltage returns and when the protective field is free again.

Using automatic start/restart

You can use the *automatic start/restart* function under the following prerequisites:

- The *start/restart interlock* function is taken over by a downstream safety-related component of the machine control system.

  or:

- It is not possible to walk behind or go around the effective protective field.

↳ Allow for an optical and/or acoustic start warning.

Automatic start-up

The *automatic start-up* function starts the machine automatically as soon as the supply voltage is present.

Automatic restart

The *automatic restart* function starts the machine automatically as soon as the protective field is free again.

5.6.2 Start interlock/automatic restart

With start interlock/automatic restart, the safety sensor remains in the OFF state when, following a power supply interruption, the voltage supply is restored. After violation of the protective field, the system restarts when the protective field is free again.

The *start/restart interlock* has two functions:

- Start interlock
- Automatic restart

Using start interlock/automatic restart

- In addition to the safety sensor you must also install the reset button. The machine operator starts the machine with this reset button.
- Position the reset button outside the danger zone so that it cannot be activated from the protective fields and danger zones. The operator must be able to see all danger zones from this position.
- Identify the area to be released on the reset button so that its meaning is clear and easy to understand.
- Ensure that nobody is in the danger zone **before** pressing the reset button.
- Hold down the reset button for between 0.12 s and 4 s to enable the safety-related switching outputs.

	DANGER
	Risk of death if start-up is operated unintentionally! - Ensure that the reset button for unlocking the start interlock cannot be reached from the danger zone. - Before unlocking the start interlock, make certain that no people are in the danger zone.

Start interlock

The *start interlock* function prevents the machine from starting automatically after switching on or after the supply voltage returns.

The machine only starts when you press the reset button.

Automatic restart

The *automatic restart* function starts the machine automatically as soon as the protective field is free again.

5.6.3 Start/restart interlock (RES)

When accessing the protective field, the start/restart interlock ensures that the safety sensor remains in the OFF state after the protective field has been cleared. It prevents automatic release of the safety circuits and automatic start-up of the system, e.g. if the protective field is again clear or if an interruption in the voltage supply is restored.

The *start/restart interlock* has two functions:

- Start interlock
- Restart interlock

	NOTICE
	For access guarding, the start/restart interlock function is mandatory. The protective device may only be operated without start/restart interlock in certain exceptional cases and under certain conditions acc. to ISO 12100.

Using start/restart interlock

- In addition to the safety sensor you must also install the reset button. The machine operator starts the machine with this reset button.
- Position the reset button outside the danger zone so that it cannot be activated from the protective fields and danger zones. The operator must be able to see all danger zones from this position.
- Identify the area to be released on the reset button so that its meaning is clear and easy to understand.
- Ensure that nobody is in the danger zone **before** pressing the reset button.
- Hold down the reset button for between 0.12 s and 4 s to enable the safety-related switching outputs.

	DANGER
	Risk of death if start/restart is operated unintentionally! - Ensure that the reset button for unlocking the start/restart interlock cannot be reached from the danger zone. - Before unlocking the start/restart interlock, make certain that no people are in the danger zone.

Start interlock

The *start interlock* function prevents the machine from starting automatically after switching on or after the supply voltage returns.

The machine only starts when you press the reset button.

Restart interlock

The *restart interlock* function prevents the machine from starting automatically, as soon as the protective field is free again. The *restart interlock* function always includes the *start interlock* function.

The machine only starts again when you press the reset button.

5.7 Field pair changeover

The safety sensor has ten field pairs. Switchover between the field pairs is possible at all times, provided the operating situation allows this.

Use the field pair changeover when the danger zones vary depending on the activity of the machine or the operating state, e.g. automated guided vehicles (AGVs), to control the field pair changeover for straight and curved stretches.

If the rules for field pair changeover are not complied with, the safety sensor signals a fault and the safety-related switching outputs are switched off.

The safety sensor has the following modes for field pair activation and field pair changeover:

- **Fixed selection of one field pair**
- **Selection by signal inputs** with the changeover mode **Overlapped monitoring**
- **Selection by signal inputs** with the changeover mode **Fixed changeover moment**

Field pair activation and field pair changeover are configured via the protective function, e.g. **CONFIGURATION > Protective function A > MODE FOR FIELD PAIR ACTIVATION AND CHANGEOVER.**

The field pair changeover can be monitored by means of configurable measures (see chapter 5.8 "Monitoring of field pair changeover").

During the changeover process, the safety sensor monitors the field pair active before the field pair changeover, according to the configured changeover mode and changeover time.

Using field pair changeover

You can configure and switch over the field pairs according to the different requirements. The field pairs are changed over via the corresponding control inputs.

The rules for field pair changeover depend on the changeover mode and changeover time. The activated field pair must correspond with the respective operating mode. The time of the field pair changeover must correspond with the machine's risk assessment. You must take the lead time, braking distances, response times and machine stopping times, e.g. influenced by overlapping protective fields, into account.

If the rules are not observed, the safety-related switching outputs switch off and a message is displayed (see chapter 12 "Diagnosis and troubleshooting").

The following rules apply for the field pair changeover:

- The field pair changeover performed by the control system must agree with the safety sensor's configuration. This configuration is specified with the configuration and diagnostics software (see chapter 9.4 "Configuring protective function").
- With field pair changeover to an occupied protective field, the safety sensor only switches off the safety-related switching outputs after the set response time plus a synchronization time of 40 ms.

NOTICE	
	**Take the lead time into consideration!** ↳ Take the lead time of the changeover time and response time into consideration before operating the machine in its new operating situation.

5.7.1 Fixed selection of one field pair

If **Fixed selection of one field pair** is set as the mode for field pair activation, field pair A1.1 is monitored irrespective of how the control inputs are connected.

5.7.2 Changeover of five field pairs in changeover mode Overlapped monitoring

Changeover mode **Overlapped monitoring**: This changeover mode is only permitted for up to five field pairs.

The field pair changeover must take place within a configurable time period of the changeover time. Two field pairs can be monitored simultaneously during the changeover time.

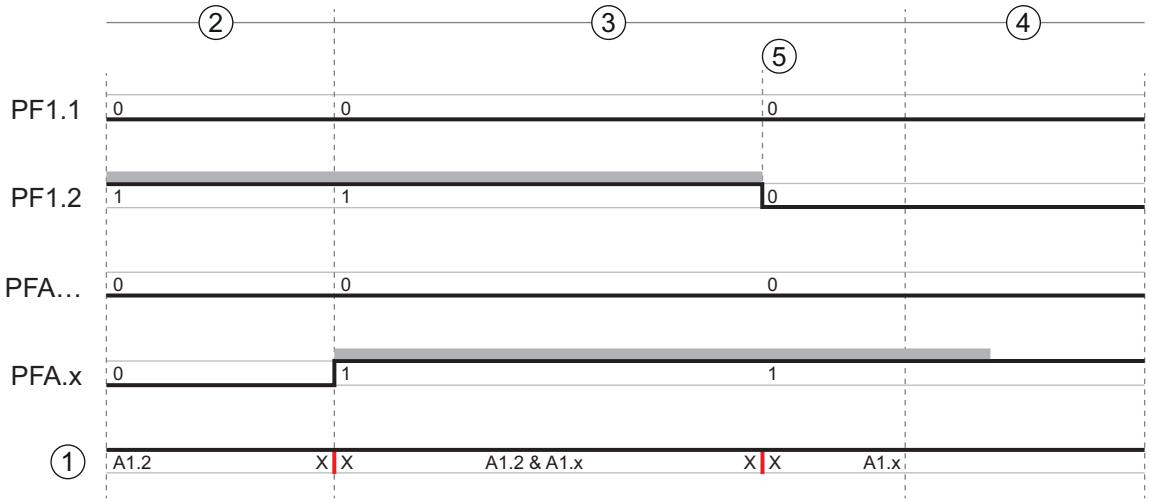
- First the control unit must switch to a new field pair before it switches off the previously active one.
- A maximum of two field pairs are active.

  Each field pair is then only active if it is selected by the control unit.
- The changeover time starts when the second field pair is connected. When the changeover time has expired, only one field pair should still be active.
- The changeover time is specified with the configuration and diagnostics software (see chapter 9.4.4 "Creating and configuring protective/warning field pairs").

Tab. 5.5: Connection of control inputs F1 to F5 with activation of field pairs A1.1 to A1.5 for protective function A

Field pair	Control input					Description
	F1	F2	F3	F4	F5	
A1.1	1	0	0	0	0	Field pair A1.1 is active
A1.2	0	1	0	0	0	Field pair A1.2 is active
A1.3	0	0	1	0	0	Field pair A1.3 is active
A1.4	0	0	0	1	0	Field pair A1.4 is active
A1.5	0	0	0	0	1	Field pair A1.5 is active

In the case of two protective functions, connection of control inputs F6 to F10 applies analogously for activation of field pairs B1.1 to B1.5 for protective function B.



1 Active protective field
2 An old protective field is active
3 Set changeover time
4 A new protective field is active
5 Changeover complete
PF Field pair or quad
X X Field pair changeover

Fig. 5.2: Signal/time diagram: Overlapped monitoring

5.7.3 Changeover of ten field pairs in changeover mode Fixed changeover moment

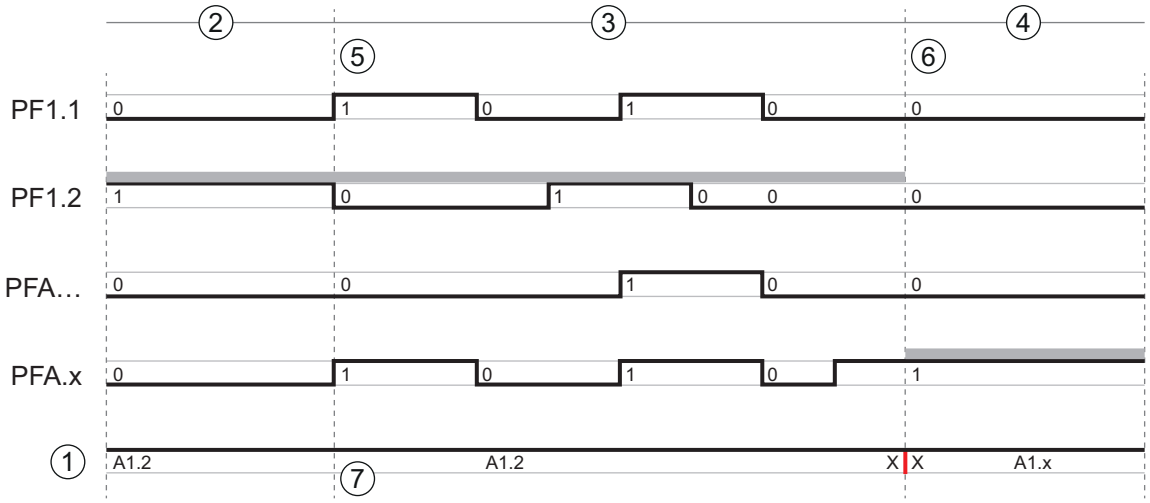
Changeover mode **Fixed changeover moment**: The field pair changeover must take place within the configurable changeover time, i.e. after the changeover time has expired, a valid and stable input connection must be present. The old field pair is monitored during the changeover time.

- The previously active field pair is monitored during the changeover time.
- The changeover time starts when the safety sensor registers a change at control inputs F1 to F5. When the changeover time has expired, only one field pair should still be active.
- Monitoring of the newly activated field pair starts when the changeover time has expired.
- The changeover time is specified with the configuration and diagnostics software (see chapter 9.4.4 "Creating and configuring protective/warning field pairs").

Tab. 5.6: Connection of control inputs F1 to F5 with activation of field pairs A1.1 to A1.10 for protective function A

Field pair	Control input					Description
	F1	F2	F3	F4	F5	
A1.1	1	0	0	0	0	Field pair A1.1 is active
A1.2	0	1	0	0	0	Field pair A1.2 is active
A1.3	0	0	1	0	0	Field pair A1.3 is active
A1.4	0	0	0	1	0	Field pair A1.4 is active
A1.5	0	0	0	0	1	Field pair A1.5 is active
A1.6	1	1	1	1	0	Field pair A1.6 is active
A1.7	1	1	1	0	1	Field pair A1.7 is active
A1.8	1	1	0	1	1	Field pair A1.8 is active
A1.9	1	0	1	1	1	Field pair A1.9 is active
A1.10	0	1	1	1	1	Field pair A1.10 is active

In the case of two protective functions, connection of control inputs F6 to F10 applies analogously for activation of field pairs B1.1 to B1.10 for protective function B.



1	Active protective field
2	An old protective field is active
3	Set changeover time
4	A new protective field is active
5	Initiation of the field pair changeover caused by a change in the signal – the old protective field is monitored until the end of the changeover time
6	Fixed end – field pair changeover complete
7	… Only one field pair change
PF	Field pair or quad
X X	Field pair changeover

Fig. 5.3: Signal/time diagram: Overlapped monitoring

5.8 Monitoring of field pair changeover

The *Changeover order* function determines the permissible field pair changeovers, e.g. if field pair A1.3 must be changed over to field pair A2.5. If the *Changeover order* function is active, the safety-related switching outputs (OSSDs) switch off in the following cases:

- the control initiates an impermissible field pair changeover.
- the field pair to which the system is changed over has been deactivated.

Activating the function

↳ The *Changeover order* is defined using the configuration and diagnostics software (see chapter 9.5 "Defining permissible field pair changeovers").

5.9 Reference contour monitoring

The *reference contour monitoring* function prevents unintentional misalignment and deliberate manipulation of the safety sensor. If a protective field contains an area with reference contour, the safety sensor not only monitors interruptions of the protective field, it also monitors the concurrence of the measured area contour with the set reference contour. If the measurement values of the area contour deviate from the defined reference contour by more than the tolerance zone of 200 mm, i.e., if no object is detected in the area with reference contour, the safety sensor switches off and the safety-related switching outputs (OSSDs) switch to *off*.

Activation of the function

↳ Activate the *Reference contour monitoring* function together with the definition of the protective field boundaries using the configuration and diagnostics software (see chapter 9.4.4 "Creating and configuring protective/warning field pairs").

5.10 Field pair monitoring

The *Field pair monitoring* function is used to set the monitoring mode for the selected field pair.

The *Standby request* monitoring mode is used to switch off field pair monitoring and the safety-related switching outputs (OSSDs). This is advisable when parking vehicles, for example.

Activation of the function

↳ Activate field pair monitoring in the configuration and diagnostics software (see chapter 9.4.5 "Configuring field pair monitoring").

5.11 EDM contactor monitoring

The *EDM contactor monitoring* function dynamically monitors the contactors, relays or valves connected downstream of the safety sensor. Prerequisite for this are switching elements with positive-guided feedback contacts (normally closed contacts).

Activation of the function

↳ Activate the contactor monitoring function using the configuration and diagnostics software (see chapter 9.4 "Configuring protective function").

If contactor monitoring is activated, it operates dynamically, i.e., in addition to monitoring the closed feedback circuit every time before the OSSDs are switched on, it also checks whether the feedback circuit has opened within 500 ms after release and whether it has closed again within 500 ms after the OSSDs switched off. If this is not the case, the OSSDs return to the OFF state after being switched on briefly.
A message is displayed on the alphanumerical display and the safety sensor switches to the fault interlock state:

- With the OSSDs switched off, +24 V must be present at the EDM input.
- With the OSSDs switched on, the EDM circuit must be open (high impedance).

5.12 E-Stop linkage

Through linkage, the behavior of the safety sensor can be controlled via a two-channel safety circuit.

The upstream safety devices and operational controls perform safety-relevant switch-off of the safety-related switching outputs of the safety sensor.

The following upstream sensors and operational controls are possible regarding the linkage:

- Safety device with two-channel contact-based switching output (normally closed contact), e.g. safety switch, E-Stop rope switch, safety position switch and the like (see chapter 5.12.1 "Contact-based safety circuit").
- Safety device with two-channel electronic OSSD switching output (see chapter 5.12.2 "Linkage of electronic safety-related switching outputs").

E-Stop buttons connected to the safety sensor act only on the safety circuit to which the AOPD is assigned. Thus, it can be considered to be an area E-Stop. The regulations for E-Stops apply to it, including those in accordance with EN 60204-1 and EN ISO 13850, among others.

↳ In this case, observe the regulations for E-Stops.

If linkage is utilized, the response time of the linked device is extended by 20 ms.

↳ Take the extended response time into account when calculating the safety distance.

5.12.1 Contact-based safety circuit

This function switches off the safety-related switching outputs of the safety sensor by means of an upstream 2-channel contact-based safety circuit, e.g. by means of safety switches with separate actuators.

The safety sensor only switches on if the following conditions have been fulfilled:

- The protective field is free.
- The safety circuit is closed or both contacts have been closed simultaneously within 0.5 s.

Activation of the function

↳ Activate the linkage using the configuration and diagnostics software (see chapter 9.4.3 "Activating protective function and contactor monitoring").

5.12.2 Linkage of electronic safety-related switching outputs

This function is used to construct a serial connection of devices with electronic safety OSSD switching outputs. The OSSDs of an upstream safety device switch off the safety-related switching outputs of the safety sensor as a central safety device. Regarding the downstream safety circuit, a linked system behaves like a single device, i.e. only inputs are necessary in the downstream safety relay.

The following conditions have to be fulfilled for the OSSDs to switch on:

- The protective field must be free.
- The OSSDs of the upstream device must be switched on or have been switched on simultaneously within 0.5 s.

	NOTICE
	A contact-based safety sensor, e.g. a safety switch with two positive-guided normally closed contacts, can be switched in the safety circuit when linking electronic safety-related switching outputs. ↳ If this switch opens, it must close both circuits again simultaneously within a time tolerance of 0.5 s. A message will otherwise be displayed on the safety sensor.

Activation of the function

↳ Activate the linkage using the configuration and diagnostics software (see chapter 9.4.3 "Activating protective function and contactor monitoring").

5.13 Signaling functions

The device and monitoring functions of the safety sensor deliver indication signals for the following function groups:

- Protective functions, e.g.
  - Protective field violated
  - Warning field violated
  - Field pair changeover active
- Device functions
- Error messages
- Warnings
- Diagnosis

The assignment of the individual functions within the function groups to the indication signals is defined using the configuration and diagnostics software (see chapter 9.6 "Configuring signal outputs").

For an overview of all logic and electrical signals of the safety sensor, see chapter 15.4 "Representation of safety sensor status".

6 Applications

The following chapters essentially describe the safety sensor's usage possibilities.

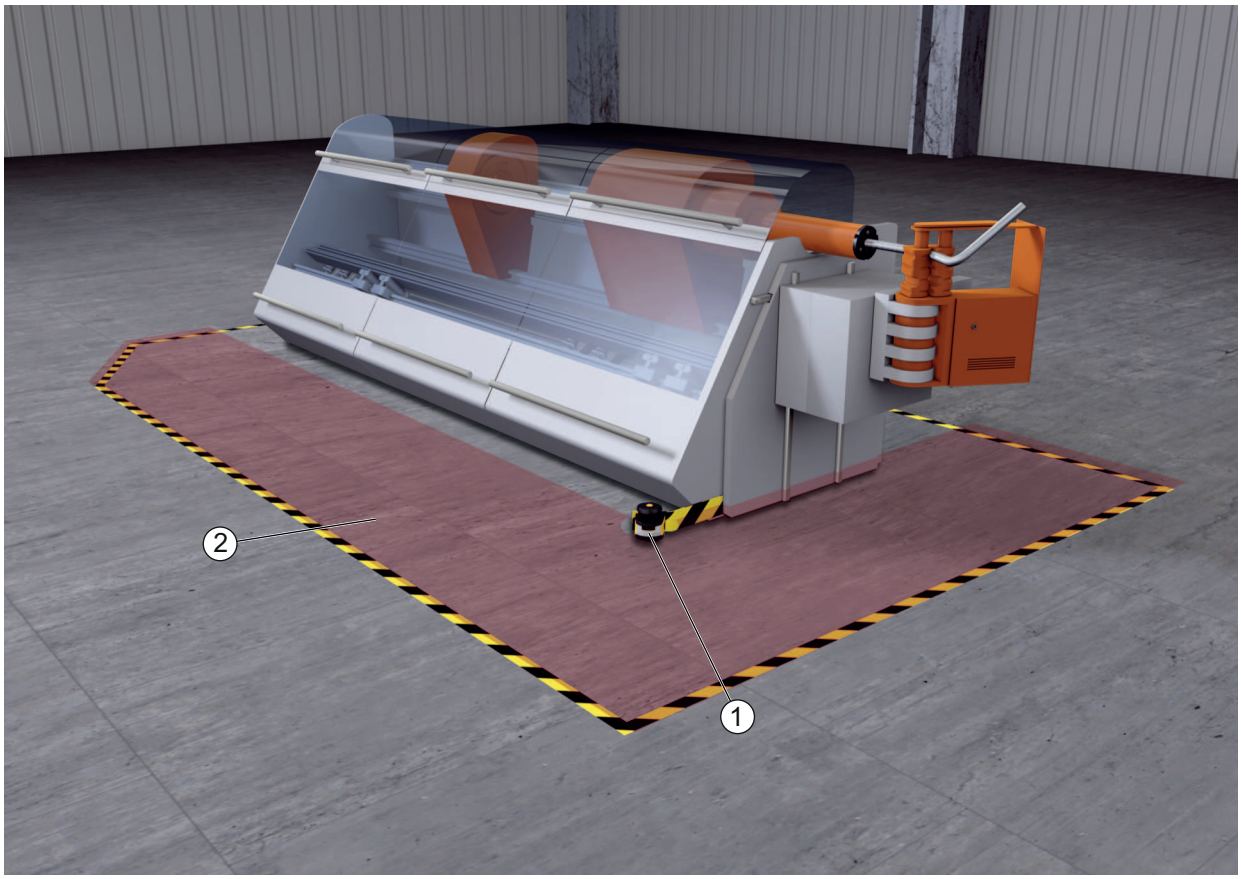
- To safely mount the safety sensor for the respective application, see chapter 7 "Mounting".
- For the electrical connection of the safety sensor, see chapter 8 "Electrical connection".
- To safely configure the safety sensor for the respective application, see chapter 9 "Configuring the safety sensor".

6.1 Stationary danger zone guarding

Stationary danger zone guarding enables a very spacious protection of people on machines that are to remain as accessible as much as possible. The safety sensor is applied as a stop-activating and presence-detecting protective device. The safety sensor's protective field is set up horizontally in front of the machine or system's point of operation.

You can also use the stationary danger zone guarding if you do have to guard areas under the machine or at the rear that are not visible.

If the danger zone changes during operation, the respective danger zone is guarded by means of a field pair changeover while the working area is accessible.



1 Safety sensor
2 Danger zone, protective function activated

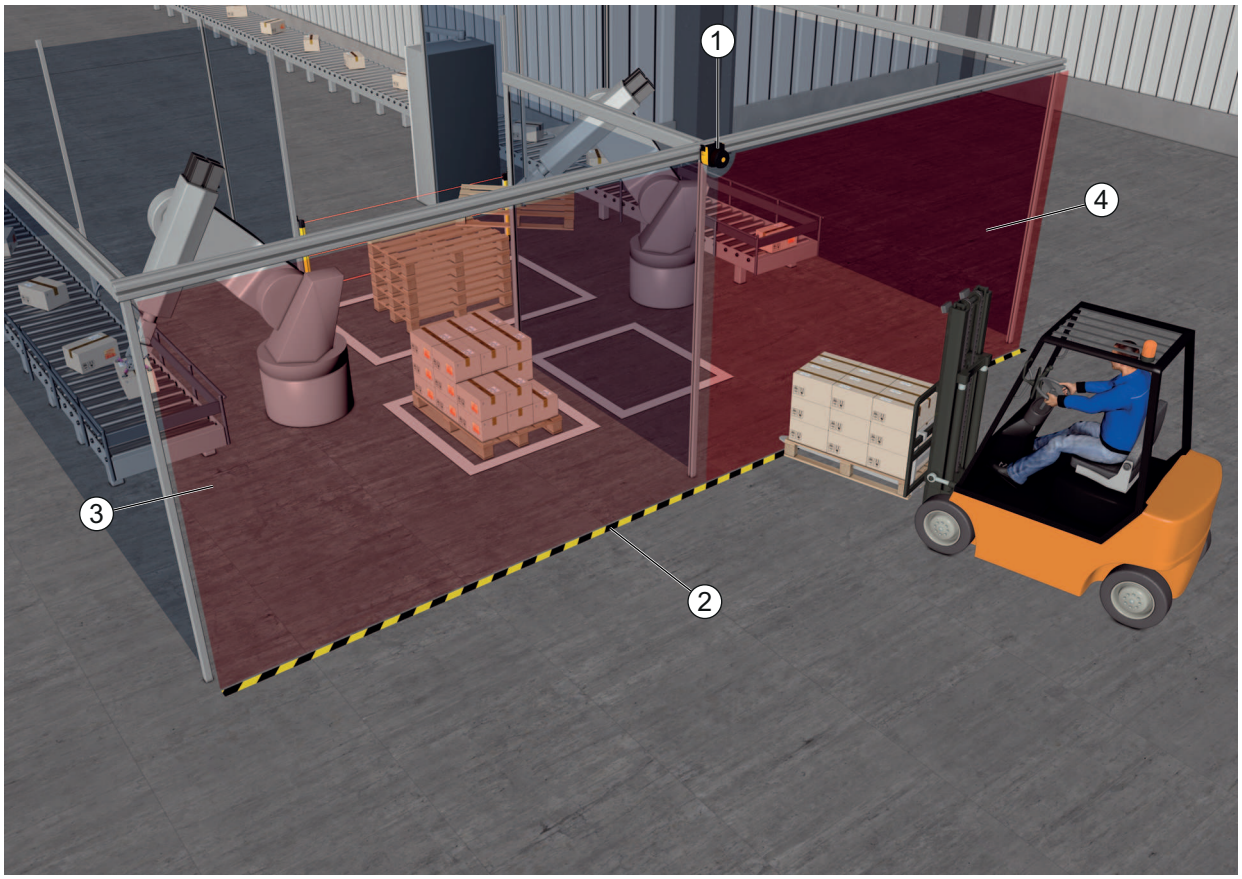
Fig. 6.1: Stationary danger zone guarding

6.2 Stationary point of operation guarding

Hand and arm protection are always required when people must work at the point of operation. The safety sensor is applied as a stop-activating and presence-detecting protective device. The safety sensor's protective field is set up vertically in front of the machine or system's point of operation. In accordance with EN ISO 13855, resolutions from 14 to 40 mm make sense here. This yields the necessary safety distance for finger protection, among others (see chapter 7.3 "Stationary point of operation guarding").

6.3 Stationary access guarding

Stationary access guarding protects people that step into a danger zone. The vertically aligned protective field of the safety sensor detects the passage of a person. A side post and the floor serve as reference contour for monitoring the position of the protective field. In contrast to danger zone guarding, the safety sensor no longer registers a person in the danger zone after the passage. This is why the *start/restart interlock* function is vital for access guarding.

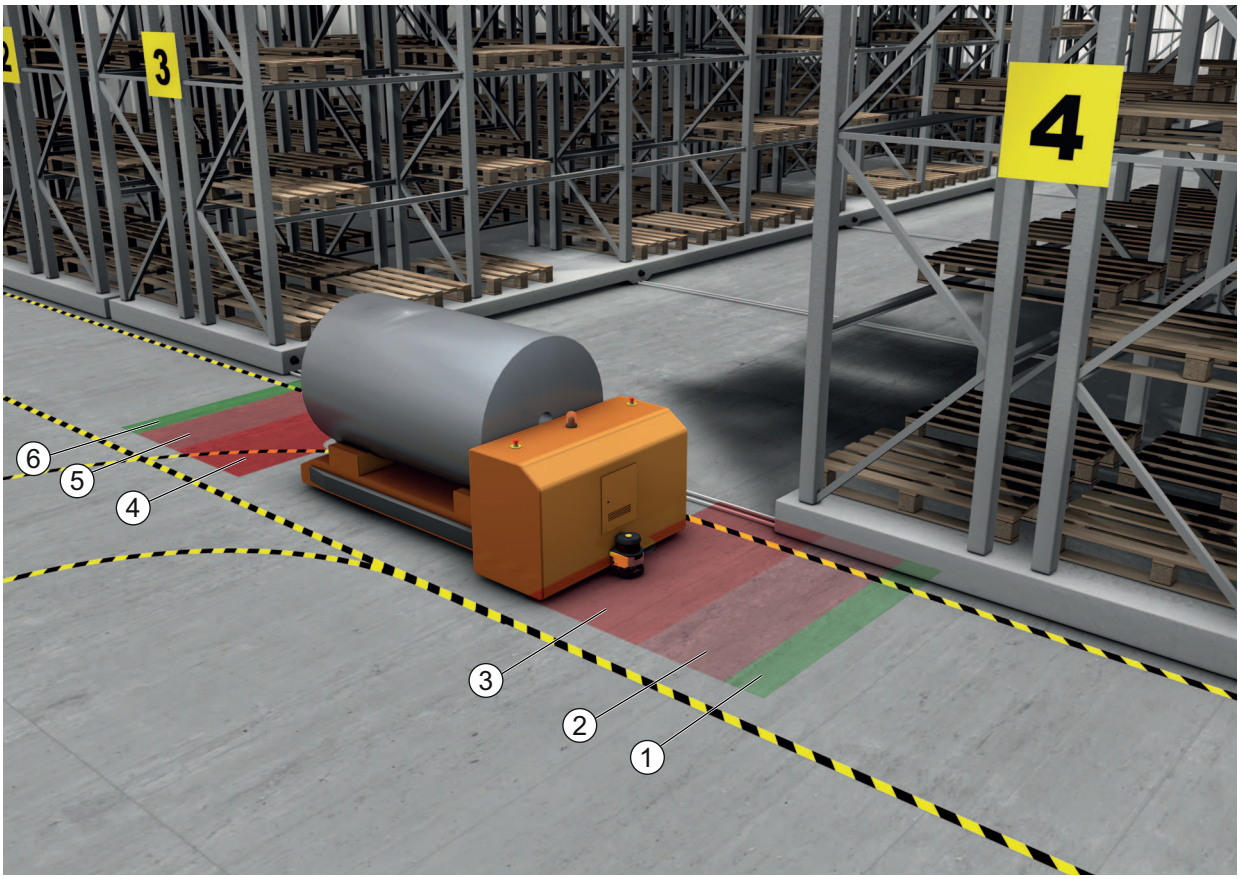


1	Safety sensor
2	Reference contour
3	Danger zone 1, protective function activated
4	Danger zone 2, protective function deactivated

Fig. 6.2: Stationary access guarding

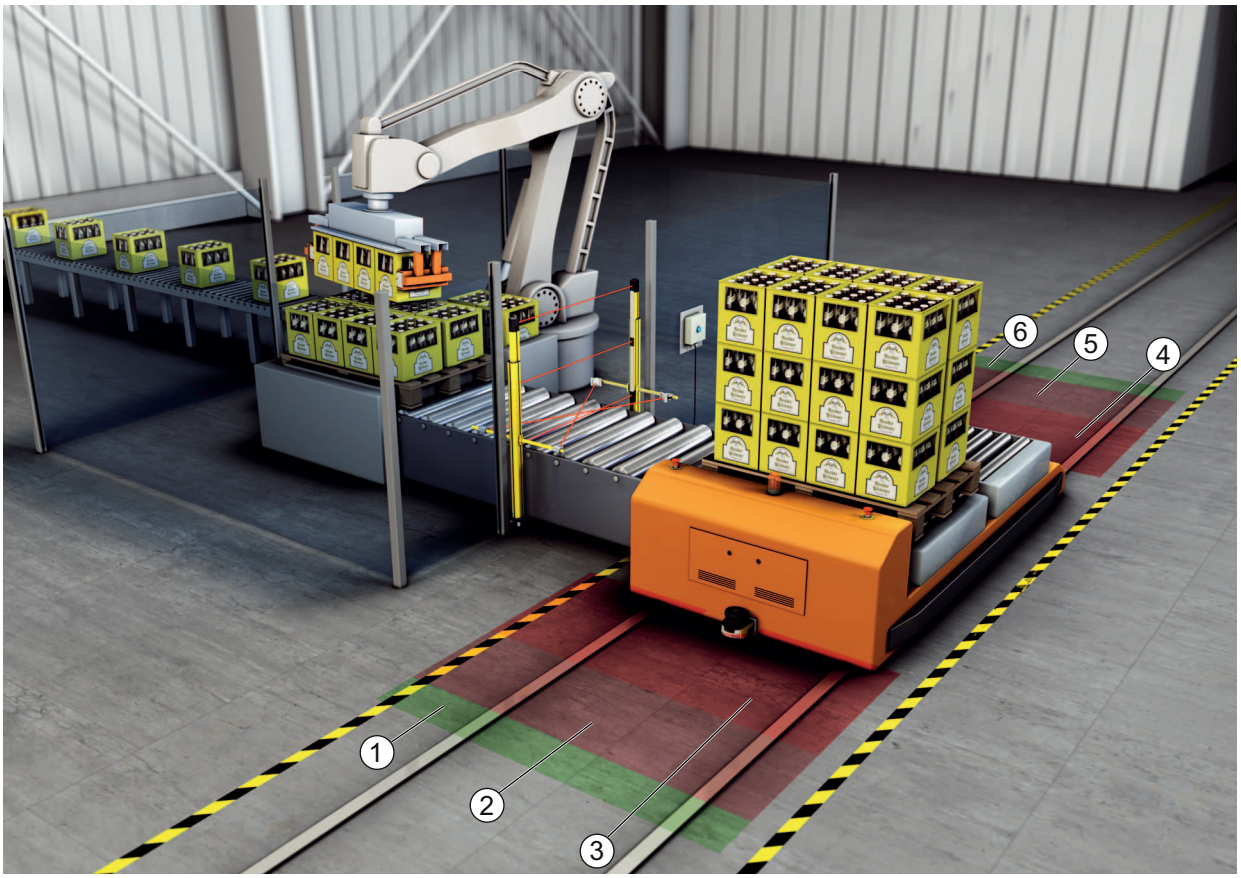
6.4 Mobile danger zone guarding

Mobile danger zone guarding protects people that are located in the transportation path of an automated guided vehicle (AGV). The distance between the protective field front edge and the vehicle front must be greater than the stopping distance of the vehicle with selected speed and maximum load. A safe control system selects speed-dependent protective fields and can activate side horizontal protective fields for curved stretches.



1 Warning field for forward travel
2 Protective field 1 for forward travel, deactivated
3 Protective field 2 for forward travel, activated
4 Protective field 1 for reverse travel, activated
5 Protective field 2 for reverse travel, deactivated
6 Warning field for reverse travel

Fig. 6.3: Mobile danger zone guarding



1 Warning field for forward travel
2 Protective field 1 for forward travel, deactivated
3 Protective field 2 for forward travel, activated
4 Protective field 1 for reverse travel, activated
5 Protective field 2 for reverse travel, deactivated
6 Warning field for reverse travel

Fig. 6.4: Mobile danger zone guarding

6.5 Danger zone safeguarding on side-tracking skates

Side-tracking skate guarding

Side-tracking skate guarding protects personnel who are located in the transportation path of a transverse side-tracking skate (TSS). One safety sensor is mounted in each direction of travel. The safety sensor that is mounted opposite the current direction of travel is deactivated. Evaluation of the warning field allows the transverse side-tracking skate to be braked gently. To ensure optimum material transport, the control changes over the protective/warning field pair depending on the state and speed.

Mobile side guarding

Mobile side guarding protects people and objects that are located on the vehicles path. This application is used when very low arranged roller conveyors do not permit an unobstructed passage of horizontal, lateral protrude protective fields. The safety sensors are positioned laterally and the protective fields are arranged vertically, at a slight tilt. The position of the front edges of the side protective fields is oriented here on the position of the front edge of the horizontal protective field.



1 Protective and warning field pair for forward travel, activated
2 Protective and warning field pair for side guarding, left, activated
3 Protective and warning field pair for side guarding, right, activated
4 Protective and warning field pair for reverse travel, deactivated

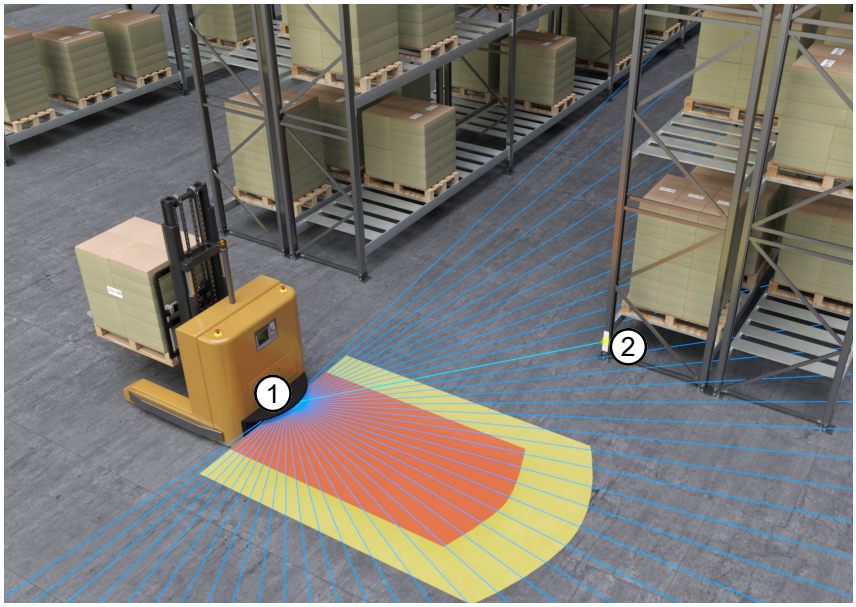
Fig. 6.5: Mobile side guarding on side-tracking skates

6.6 Vehicle navigation

NOTICE
This function is only available with RSL 425 devices.

The measurement data cyclically transmitted by the safety sensor can be used for navigation by automated guided vehicles.

For each measurement point of the scan level, values for distance and signal strength are part of the measurement data. A navigation system evaluates the measurement data and calculates the position of the vehicle. With the help of the transmitted signal strength, highly reflective landmarks can be detected.



1 Safety sensor
2 Retro-reflector

Fig. 6.6: Vehicle navigation

In addition to the measurement data, a status profile of the safety sensor is also transmitted. The status profile contains information about the status of the inputs and outputs as well as other status information. The status profile thereby offers a possibility for performing diagnostics on the safety sensor.

You can find additional information in document *RSL400 UDP specification*, which is available for download on the Leuze website: **www.leuze.com**

6.6.1 Signal strength and reflector detection

NOTICE
This function is only available with RSL 425 devices.

The signal strength transmitted via UDP is a measure of the the optical power received by the safety sensor, which is largely dependent on the following values:

- Distance
- Brightness of the object or structure of the object surface
- Angle of incidence of the laser beam on the object surface
  0°: vertically incident light
- Share of area of the light spot on the object
  100%: the light spot lies completely on the measured object

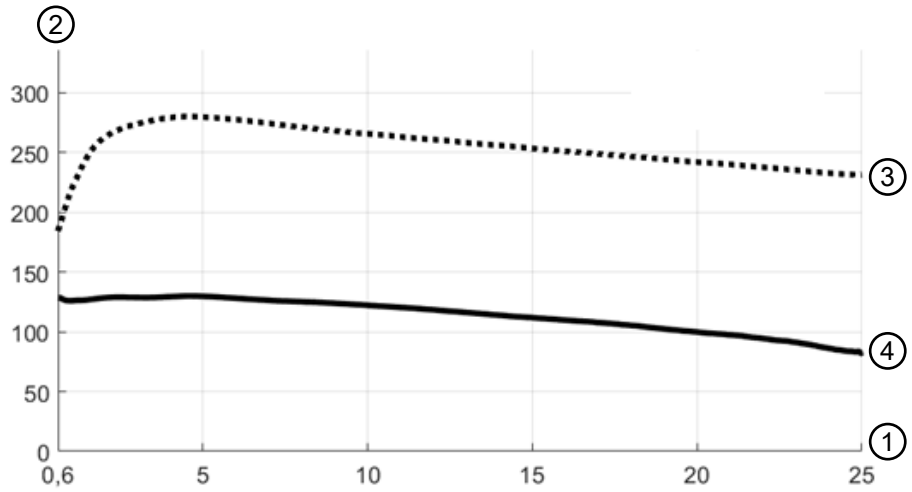
The signal strength transmitted by the safety sensor can be used to navigate automated guided vehicles. The transmitted signal strength value is a unitless, non-calibrated measurement value that is output unprocessed by the safety sensor.

To navigate automated guided vehicles, highly reflective landmarks are distinguished from the less-reflective surroundings. These landmarks usually consist of retro-reflector films.

Retro-reflectors can be identified by analyzing the signal strength values. If the signal strength exceeds a limit value, a retro-reflector can be mapped at this angle. Reliable detection of retro-reflectors is normally possible with a signal strength limit value of 180 or higher at a distance > 0.6 m.

For reflective surfaces, the safety sensor usually measures a signal strength value of maximum 500. Signal strength values > 500 can be caused by object edge effects and do not normally correspond to any real object diffuse reflection.

Due to the narrow light spot of the RSL400, object edge effects rarely occur. Object edge effects can be caused if a light beam is incident on multiple objects at different distances.



1 Object distance [m]
2 Signal strength
3 Retro-reflector film
4 White surface

Fig. 6.7: Signal strength curves depending on the distance

The figure shows a typical curve of the signal strength transmitted by the safety sensor as a function of the measured object distance and object diffuse reflection for the following boundary conditions:

- Angle of incidence of the laser beam: 0°
- Share of area of the light spot on the object: 100%

The upper curve (3) represents the typical, distance-dependent change of the signal strength for a typical retro-reflector film, e.g., 3M™ Diamond Grade 983-10™.

The lower curve (4) shows the typical, distance-dependent change of the signal strength for a white, naturally scattering surface with 90% diffuse reflection, e.g., a white wall.

7 Mounting

The safety sensor's protective function is only guaranteed when the device arrangement, configuration, protective field dimensioning and mounting are coordinated with the respective application.

The installation work must only be performed by a competent person in compliance with the applicable standards and these instructions. The mounting must be thoroughly inspected on completion.

- You must observe and comply with the respective relevant machine-specific standards and regulations (see chapter 16 "Standards and legal regulations").
- Observe the basic information on mounting (see chapter 7.1 "Basic infos").

WARNING

Improper mounting may result in serious injury!

The protective function of the safety sensor is only ensured if appropriately and professionally mounted for the respective, intended area of application.

- Only allow competent persons to install the safety sensor.
- Maintain the necessary safety distances (see chapter 7.1.1 "Calculation of safety distance S").
- Make sure that stepping behind, crawling under or stepping over the protective device is reliably ruled out and reaching under, over or around is taken into account in the safety distance, if applicable with additional distance C_{RO} corresponding to EN ISO 13855.
- Take measures to prevent that the safety sensor can be used to gain access to the danger zone, e.g. by stepping or climbing into it.
- Observe the relevant standards, regulations and these instructions.
- After mounting, check the safety sensor for proper function.
- Clean the safety sensor at regular intervals.
  Environmental conditions: see chapter 15 "Technical data"
  Care: see chapter 13 "Care, maintenance and disposal"

7.1 Basic infos

7.1.1 Calculation of safety distance S

Optical protective devices can only perform their protective function if they are mounted with adequate safety distance. When mounting, all delay times must be taken into account, such as the response times of the safety sensor and control elements as well as the stopping time of the machine, among others.

The following standards specify calculation formulas:

- EN ISO 13855, "Safety of machines - The positioning of protective device in respect of approach speeds of parts of the human body": mounting situation and safety distances.

General formula for calculating the safety distance S of an Optoelectronic Protective Device acc. to EN ISO 13855

$$S = K \cdot T + C$$

S	[mm]	= Safety distance
K	[mm/s]	= Approach speed
T	[s]	= Total time of the delay, sum from ($t_a + t_i + t_m$)
t_a	[s]	= Response time of the protective device
t_i	[s]	= Response time of the safety relay
t_m	[s]	= Stopping time of the machine
C	[mm]	= Additional distance to the safety distance

NOTICE

If longer stopping times are determined during regular inspections, an appropriate additional time must be added to t_m.

7.1.2 Suitable mounting locations

Area of application: Mounting

Tester: Technician who mounts the safety sensor

Tab. 7.1: Checklist for mounting preparations

Check:	Yes	No
Is the safety distance to the hazard location maintained?		
Has the scanning angle of the safety sensor as given on the marking/template on the top of the sensor been taken into consideration?		
Can the point of operation or the danger zone only be accessed through the protective field?		
Have measures been taken to prevent the protective field from being bypassed by crawling under?		
Is stepping behind the protective device prevented or is mechanical protection available?		
Can the safety sensors be fastened in such a way that they cannot be moved and turned?		
Is the safety sensor accessible for testing and replacing?		
Is it impossible to actuate the reset button from within the danger zone?		
Can the entire danger zone be seen from the installation site of the reset button?		

NOTICE
If you answer one of the items on the checklist with *no*, the mounting location must be changed.

7.1.3 Mounting the safety sensor

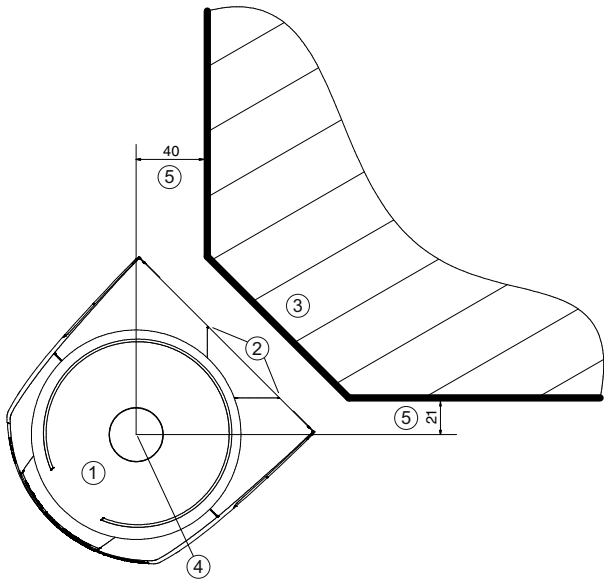
NOTICE
Detailed information on mounting the safety sensor can be found in the document "Quick Start Guide RSL 400".

Proceed as follows:

↳ Calculate the necessary safety distance and determine the required additional distances for your application.

↳ Determine the mounting location.

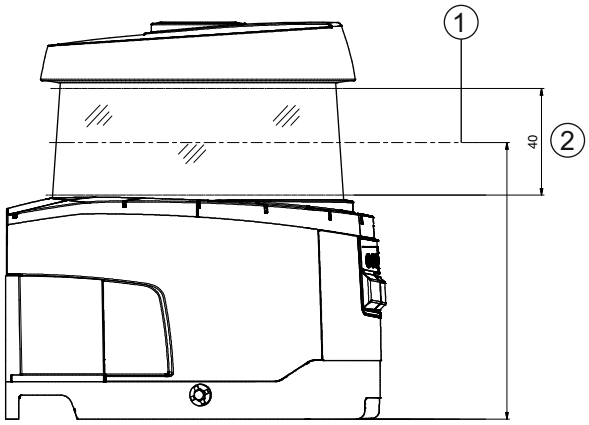
- Observe the information regarding the mounting locations; see chapter 7.1.2 "Suitable mounting locations"
- Ensure that machine parts, safety guards or covers do not impair the safety sensor's field of vision.
- Make sure that the scanning range of the safety sensor is not limited. To mount the safety sensor taking the scanning range into consideration, a template must be attached to the top cover of the safety sensor.



all dimensions in mm

1 Safety sensor
2 Template (markings on safety sensor)
3 Mounting location
4 Reference point for distance measurement and protective field radius
5 Area with unobstructed view; must remain free

Fig. 7.1: Mounting taking the scanning range of 270° into consideration



all dimensions in mm

1 Scan level
2 Area with unobstructed view; must remain free (40 mm)

Fig. 7.2: Mounting: area with unobstructed view

- Determine whether you are going to install the safety sensor with or without the mounting system. During mounting, use the four supplied M5 screws or four similar screws with a diameter of 5 mm, and make certain that the mounting elements or mounting construction supports at least four times the weight of the device with or without mounting system.
- Have the appropriate tools at the ready and mount the safety sensor.
- Install protective enclosures or safety bars if the safety sensor is in an exposed position.
- If there is a risk that the safety sensor will be used as a climbing aid, install a suitable physical cover over the safety sensor.
- Align the mounted safety sensor horizontally and vertically using the integrated electronic spirit level.
- For the electronic spirit level to work, the supply voltage of 24 V must be present at the safety sensor.

- The electronic spirit level indicates the vertical (V) and horizontal (H) alignment of the safety sensor. The spirit level is displayed
  - permanently after the end of the booting phase/start phase when starting without configuration
  - repeatedly until the end of the booting phase/start phase when starting with configuration
  - using the configuration and diagnostic software:
    Diagnosis > [Align sensor mechanically] button (▬)
- When mounting without a mounting system, the safety sensor can be aligned only slightly along the horizontal axis.

↳ Attach safety notice stickers to the mounted safety sensor (the stickers are included in the delivery contents).

↳ Configure the safety sensor with the configuration and diagnostics software; see chapter 9 "Configuring the safety sensor":

- Observe the information on the response times, the stopping time of the machine and the protective field dimensioning for your application.
- Determine the size of the protective field on the basis of the mounting location, the calculated safety distances and additional distances.

	NOTICE
	With protective field boundaries <200 mm, object detection may be restricted owing to the measurement error. ↳ When defining the protective field, take into account the additional distance Z_{sm} to the protective field contour (see chapter 7.2 "Stationary danger zone guarding").

- Configure the protective field so that the safety-related switching outputs are switched off from every accessible point with sufficient minimum distance D.
- Determine the start-up/restart operating mode required for the application.
- If you are using start and/or restart interlock, determine the position for the reset button.
- Many safety-relevant parameters are preset for each application in the configuration and diagnostics software. Use these preset values where possible.
- Determine the conditions for the field pair changeover and the sequence of the field pair changeover.

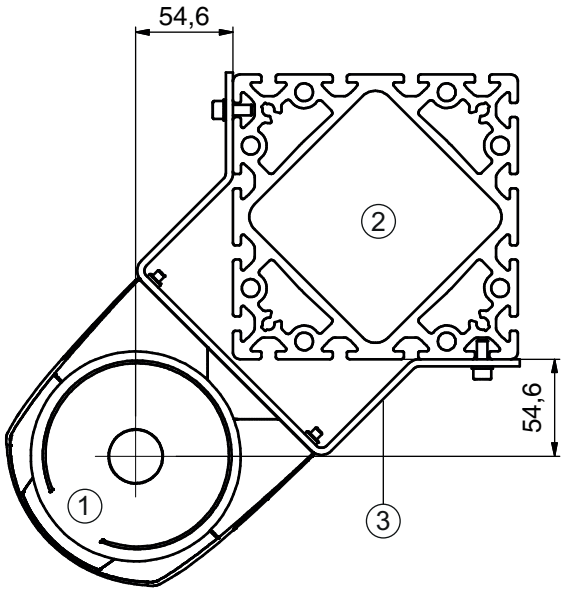
↳ Create a record document for the device configuration and protective field dimensioning.

- The document must be signed by the person responsible for the configuration.
- Include this document with the machine documentation.

↳ Mark the protective field boundaries on the floor.
You can easily test the safety sensor along this marking.

After mounting, you can electrically connect (see chapter 8 "Electrical connection"), start up, align (see chapter 10 "Starting up the device"), and test (see chapter 11 "Testing") the safety sensor.

7.1.4 Mounting examples



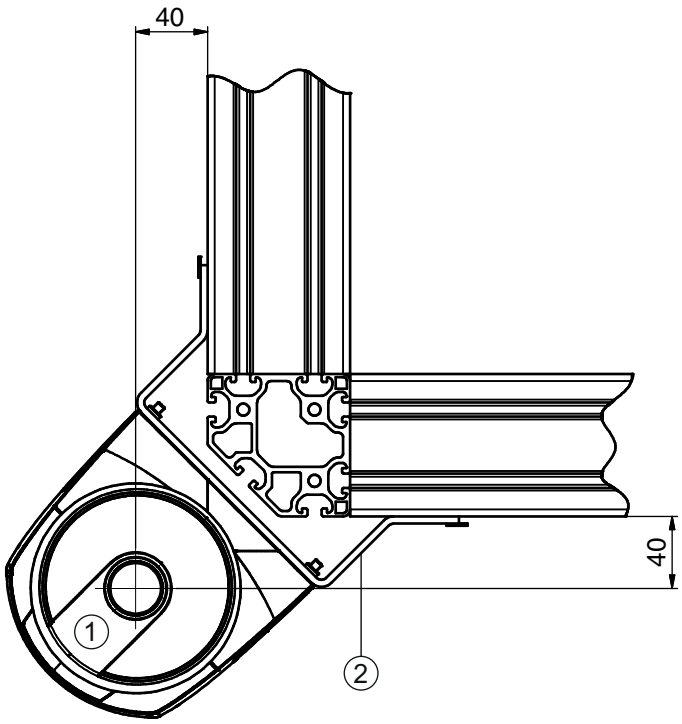
all dimensions in mm

1 Safety sensor

2 Column

3 BT856M mounting bracket

Fig. 7.3: Example: mounting on a post

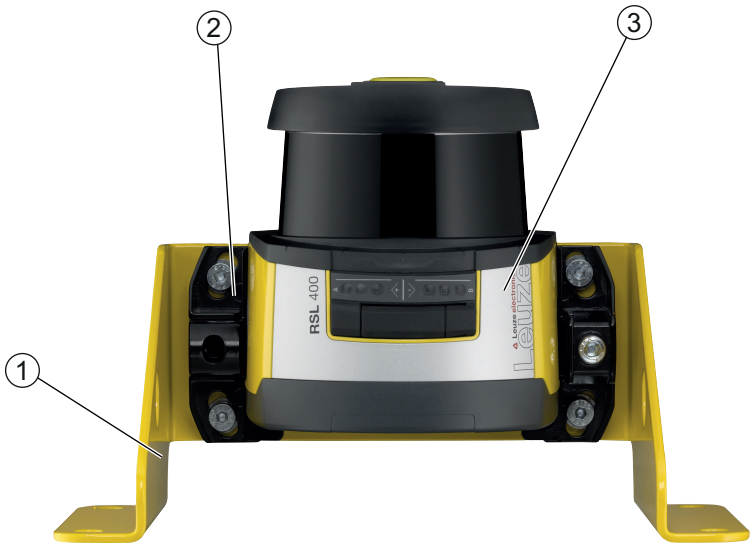


all dimensions in mm

1 Safety sensor

2 BT840M mounting bracket

Fig. 7.4: Example: mounting on a chamfered corner



1 BTF815M mounting bracket (only in combination with the BTU800M mounting system)
2 BTU800M mounting system
3 Safety sensor

Fig. 7.5: Example: mounting on floor

7.1.5 Information on protective field dimensioning

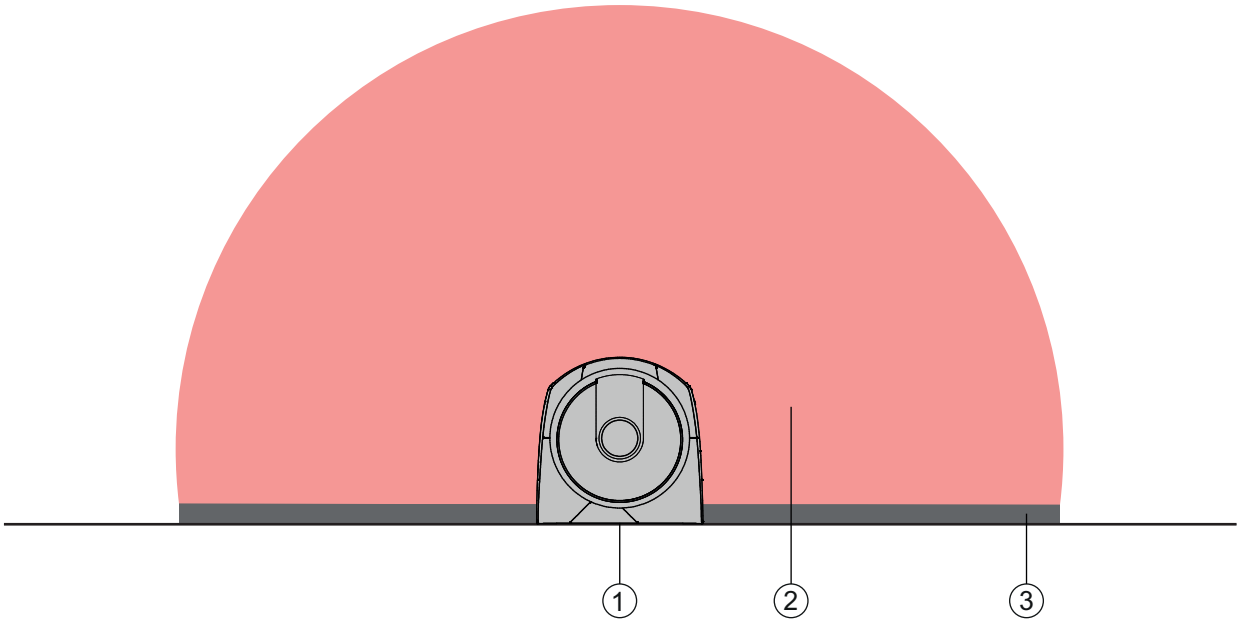
NOTICE
With protective field boundaries <200 mm, object detection may be restricted owing to the measurement error. ↳ When defining the protective field, take into account the additional distance Z_{sm} to the protective field contour (see chapter 7.2 "Stationary danger zone guarding").

- ↳ Dimension the protective field big enough that the safety sensor's switching signal can stop the dangerous movement in good time.
  If several protective fields are selected with field pair changeover, this condition applies for all protective fields.
  If you cannot sufficiently dimension a protective field, use additional protective measures, e.g. safety guards.
- ↳ Ensure that the protective field cannot be walked behind in the direction of the danger zone.
- ↳ Observe all delay times, e.g. safety sensor response times, control element response times, braking times or machine or automated guided vehicle stopping times (AGV).
- ↳ Take changed delay times, which, for example, can be caused by reducing the braking force, into account.
- ↳ Observe shadowing effects, e.g. surfaces and areas behind static objects. People in the shadows of these objects will not be detected by the safety sensor.
- ↳ Observe the lateral tolerance when dimensioning the protective fields (see chapter 15 "Technical data").
- ↳ Do not use cone-shaped protective field contours, as these do not guarantee any protective function.
- ↳ Take the additional distances required for the application into account.

Handling unmonitored areas

There is an area behind the safety sensor that the safety sensor does not monitor. Unmonitored areas can also materialize, e.g. if you install a safety sensor on a rounded off vehicle front.

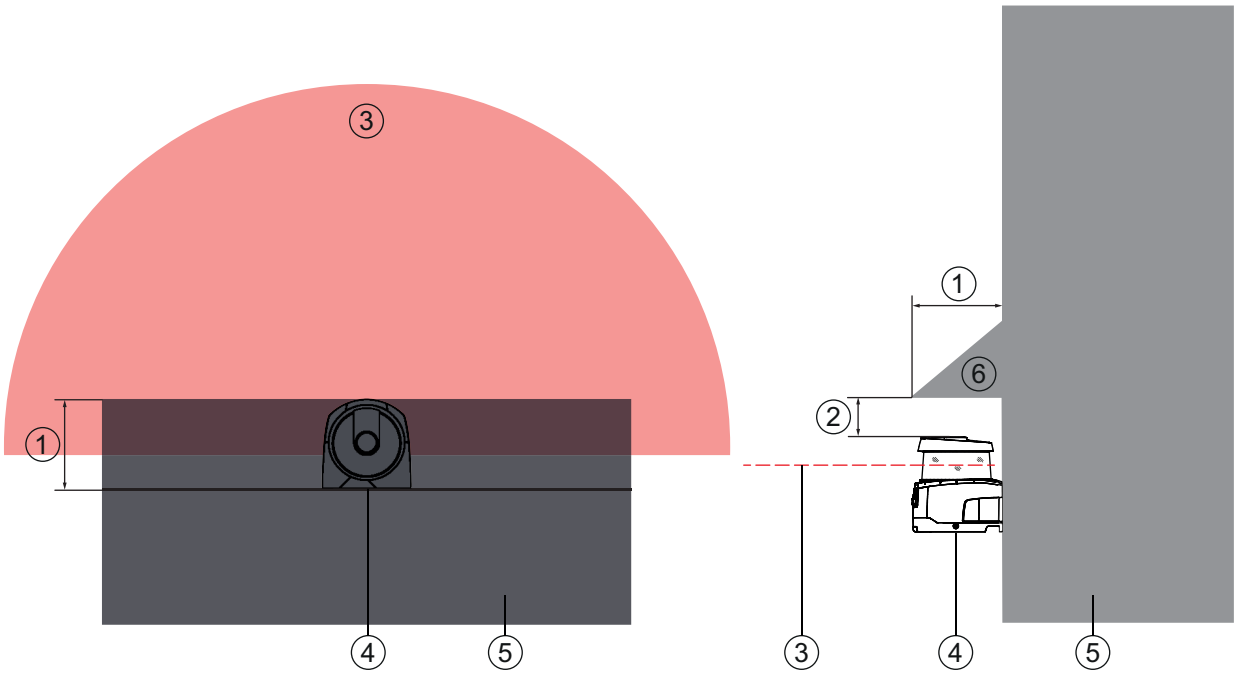
It must not be possible to walk behind unmonitored areas.



1 Safety sensor
2 Protective field
3 Unmonitored area;
Optimum availability at a distance of 50 mm to fixed contours

Fig. 7.6: Unmonitored area

- Prevent access to an unmonitored area with screens.
- Prevent walking behind by countersinking the safety sensor into the machine contour.



1 Countersinking into the machine contour, min. 100 mm
2 Minimum distance above the scanner unit, min. 34 mm
3 Protective field
4 Safety sensor
5 Machine
6 Angled physical cover

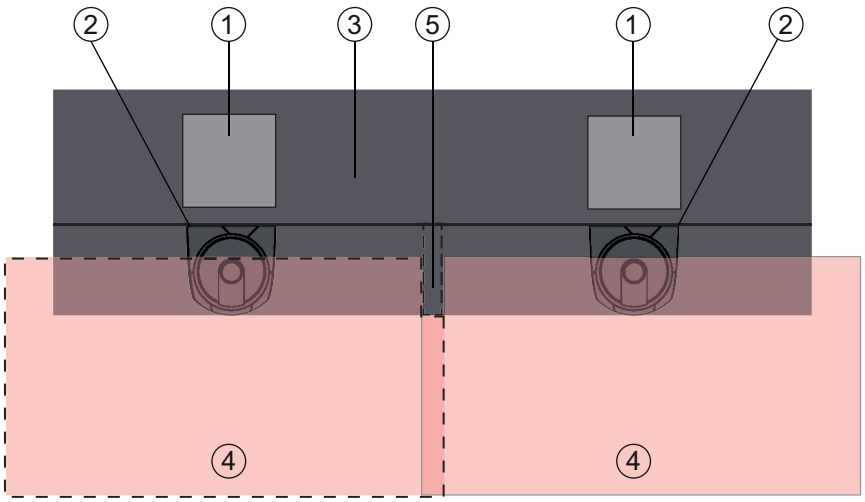
Fig. 7.7: Stepping behind protection by countersinking into the machine contour

- Use a physical cover set at an angle over the safety sensor if you expect that the safety sensor will be used as a climbing aid or standing surface.

Protective field setup with adjacent safety sensors

The safety sensor has been developed in a way that prevents several safety sensors from interfering with one another as much as possible. Nevertheless, if several safety sensors are positioned adjacent to each other, this may result in a reduction in the availability of the safety sensors.

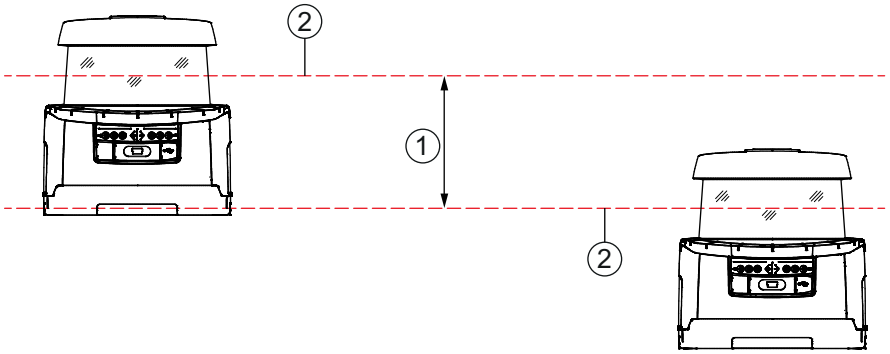
- When mounting the safety sensor, avoid glossy surfaces directly behind the optics cover.
- Plan for shielding with stationary applications.
  The shielding must be at least as high as the safety sensor's optics cover and embedded with the front housing edge.
  If you plan for a shielding that is still within the countersinking in the machine contour, the resolution of the protective fields must not be impaired at any accessible points.
  You require the reciprocal shielding with both horizontal and vertical alignment of the protective fields.



1 Point of operation
2 Safety sensor
3 Machine with countersinking for sensor installation
4 Protective fields
5 Shielding

Fig. 7.8: Shielding prevents reciprocal influencing of safety sensors set up beside one another

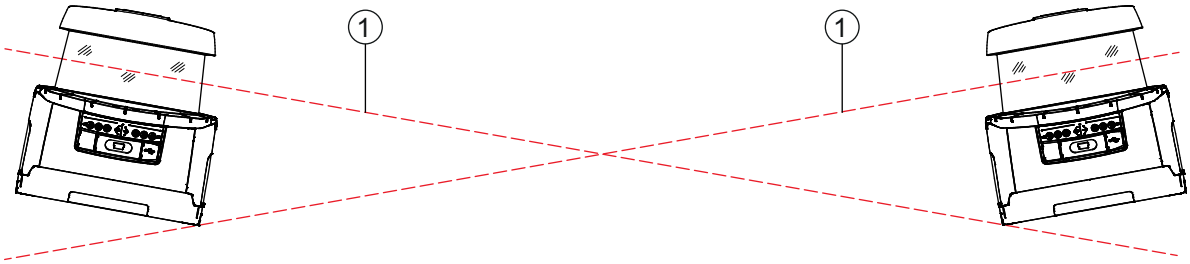
- Install the safety sensors off-set on the height.



1 Minimum distance, min. 100 mm
2 Scan level

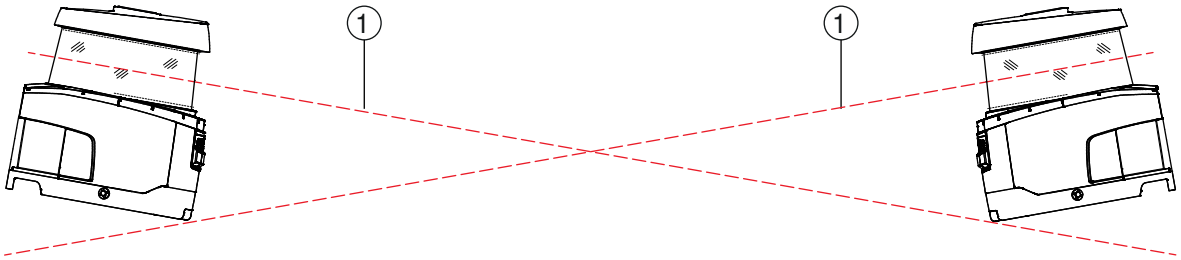
Fig. 7.9: Height offset mounting, parallel alignment

↳ Install the safety sensors with crossed alignment.



1 Scan level

Fig. 7.10: Mounting beside one another, without height offset, crossed alignment



1 Scan level

Fig. 7.11: Mutually opposing mounting, without height offset, crossed alignment

7.2 Stationary danger zone guarding

The safety sensor takes over the stop-activating and presence-detecting function.

Calculation of safety distance S for parallel approach to the protective field

$$S = K \cdot T + C$$

S_{RO}	[mm]	= Safety distance
K	[mm/s]	= Approach speed for danger zone guarding with approach direction parallel to the protective field (resolution up to 90 mm): 1600 mm/s
T	[s]	= Total time of the delay, sum from (t_a + t_i + t_m)
t_a	[s]	= Response time of the protective device
t_i	[s]	= Response time of the safety relay
t_m	[s]	= Stopping time of the machine
C	[mm]	Additional distance for danger zone guarding with approach reaction H = height of the protective field, H_{min} = minimum installation height permitted, but no smaller than 0, d = resolution of the protective device C = 1200 mm - 0.4 × H; H_{min} = 15 × (d - 50)

Response times, stopping time of the machine

The safety sensor's rotary mirror rotates on its own axis every 40 ms. One revolution is a scan. At least two consecutive scans must be interrupted so that the safety-related switching outputs switch off. The safety sensor's minimum response time is therefore 80 ms.

If you want to increase the safety sensor's availability in an environment with fine particles, increase the number of interrupted scans after which the safety-related switching outputs switch off. With each additional scan the response time t_a increases by 40 ms. With K = 1600 mm/s the safety distance increases by 64 mm per additional scan.

↳ Select a response time t_a of at least 120 ms or higher.

↳ Determine the machine/system's stopping time t_m.
If data is not available, you can commission Leuze to perform measurements; see chapter 14 "Service and support".

↳ If an increase in the stopping time within the regular test periods is to be expected, take an additional time into account for the machine's stopping time t_m.

Additional distance C for danger zone guarding with approach reaction

You prevent reaching the point of operation by reaching over with the additional distance C:

$$C = 1200 - 0,4 \cdot H$$

H	[mm]	= Height of protective field above floor (installation height)
C_{MIN}	[mm]	= 850 mm
H_{MAX}	[mm]	= 1000 mm

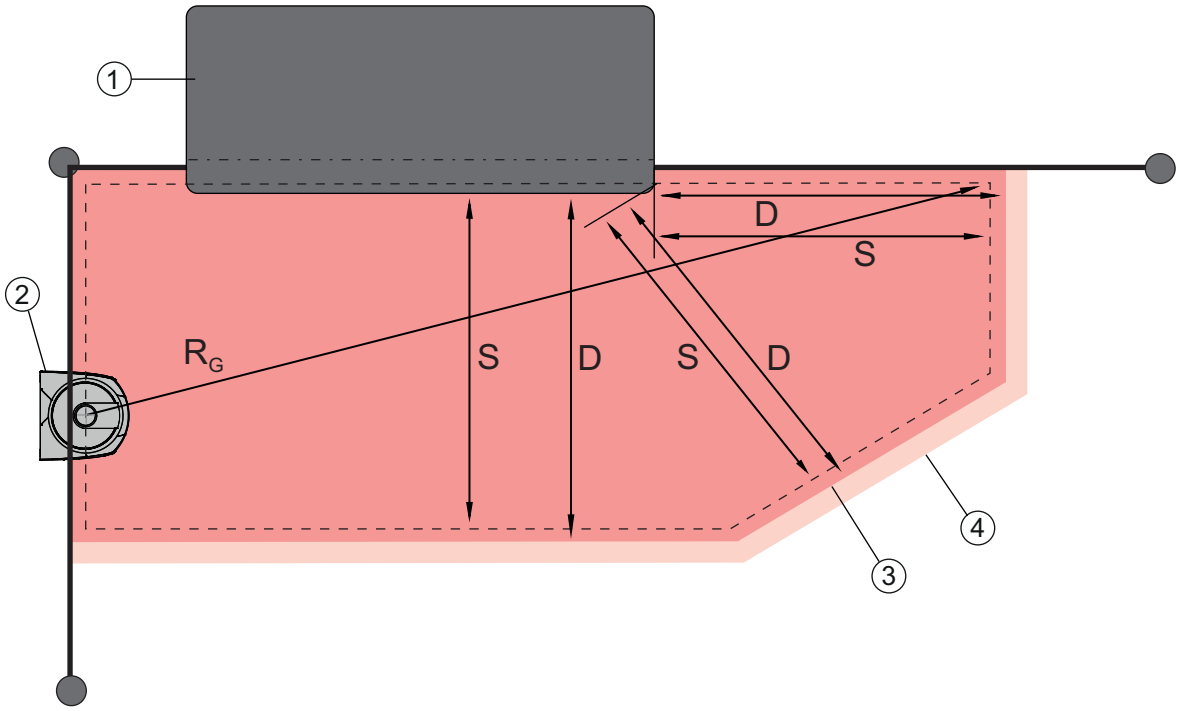
The minimum permissible installation height depends on the resolution of the safety sensor:

Tab. 7.2: Additional distance C depending on the resolution of the safety sensor

Safety sensor resolution (mm)	Minimum permissible installation height (mm)	Additional distance C (mm)
50	0	1200
60	150	1140
70	300	1080

Application-related additional distances for safety distance S

The protective field boundaries must be defined so that the calculated safety distance S to the point of operation, extended by the additional distances, is complied with everywhere. Where this is not possible or does not make sense, you can use hard guards as supplementary measures.



1	Routing machine with free space for sensor protective field in the area under the machine table
2	Safety sensor
3	Protective field contour
4	Warning field contour
S	Calculated safety distance S
D	Minimum distance D (= safety distance S + additional distance Z_{SM} + Z_{REFL}, where required)
R_G	Largest protective field radius without additional distances, measured from the rotation axis of the rotary mirror

Fig. 7.12: Defining the protective field contour for a stationary, horizontal protective field

- Define the limits of the protective field using the safety distance S without an additional distance.
- Determine the biggest protective field radius R_G for this protective field.
  The biggest protective field radius determines the additional distance Z_{SM} for the system-related measurement error, by which the protective field contour must be enlarged.
  The position of the rotary mirror's center point with regard to the housing is provided by the dimensioned drawings.

Tab. 7.3: Additional distance Z_{SM} for the protective field contour because of measurement error

Biggest protective field radius R_G without additional distances	Additional distance Z_{SM}
< 6.25 m	100 mm
> 6.25 m	120 mm

- Avoid retro-reflectors at the beam level beyond the protective field boundaries. If this is not possible, add another additional distance Z_{REFL} of **100 mm**.

Minimum distance D to the protective field contour

The minimum distance D is the distance between point of operation and protective field contour.

$$D = S + Z_{SM} + Z_{REFL}$$

D	[mm]	= Minimum distance between the point of operation and the protective field contour
Z_{SM}	[mm]	= Additional distance for system-related measurement error
Z_{REFL}	[mm]	= Additional distance for retro-reflectors

- If the protective field runs up against fixed boundaries, such as walls or machine frames, take a countersinking into the machine contour of at least the size of the necessary additional distance Z_{SM}, and Z_{REFL} where required, into account. With the protective field contour under these conditions, stay about 50 mm away from the machine surface.
- If the protective field runs up against hard guards, ensure that the protective field ends under instead of in front of the hard guards. The width of the lower post must correspond with the size of the required additional distances.
- If all hazards in the fenced off area are covered by the safety sensor and the height of the beam level is 300 mm, you can raise the bottom edge of the hard guards from 200 mm to 350 mm in the protective field range. The protective field reaching to under the hard guards takes over the protective function of preventing an adult from crawling under in this case.

NOTICE

The beam level of the safety sensor is level with the alphanumerical display.

- Prevent obstructions within the calculated protective field boundaries. If this is not possible, implement protective measures so that the point of operation cannot be reached from out of the shadow of the obstruction.

7.3 Stationary point of operation guarding

The safety sensor takes over the stop-activating and presence-detecting function.

Calculation of safety distance S_{RO} for access over the vertical protective field

$$S_{RO} = K \cdot T + C_{RO}$$

S_{RO}	[mm]	= Safety distance
K	[mm/s]	= Approach speed for point of operation guarding with approach reaction and normal approach direction to the protective field (resolution 14 to 40 mm): 2000 mm/s or 1600 mm/s, when S_{RO} > 500 mm
T	[s]	= Total time of the delay, sum from (t_a + t_i + t_m)
t_a	[s]	= Response time of the protective device
t_i	[s]	= Response time of the safety relay
t_m	[s]	= Stopping time of the machine
C_{RO}	[mm]	= Additional distance in which a body part can move towards the protective device before the protective device triggers

Response times, stopping time of the machine

The safety sensor's rotary mirror rotates on its own axis every 40 ms. One revolution is a scan. With each additional scan the response time t_a increases by 40 ms. With K = 2000 mm/s approach speed this corresponds with an increase in the safety distance of 80 mm per additional scan. With K = 1600 mm/s it is 64 mm.

- Select a response time t_a of at least 80 ms or higher.
- Determine the machine/system's stopping time t_m.
  If data is not available, you can commission Leuze to perform measurements (see chapter 14 "Service and support").
- If an increase in the stopping time within the regular test periods is to be expected, take an additional time into account for the machine's stopping time t_m.

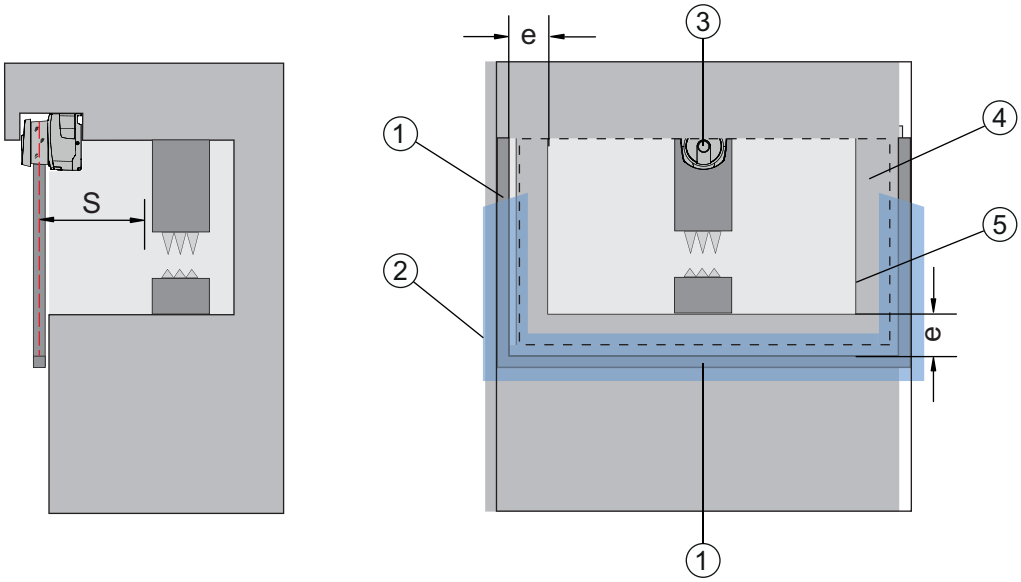
Additional distance C_{R0} for finger protection

The required finger protection is ensured here by an additional distance C, which depends on the safety sensor resolution, in addition to the safety distance.

- Detection of an adult's hand:
  - Resolution: 30 mm
  - Additional distance C_{RO}: 128 mm
- Arm detection:
  - Resolution: 40 mm
  - Additional distance C_{RO}: 208 mm

Protective field contour and reference contour

With a vertical protective field, you must define at least two sides of the protective field contour as reference contour. The objective is to monitor the position of the protective field with regard to its marginal area. If the arrangement misaligns and the distance of the safety sensor to the reference surface changes as a result, switch the safety-related switching outputs off.



1	Physical frame for reference contour
2	Reference contour, must cover at least two sides of the protective field
3	Safety sensor
4	Distance e between the reference contour frame and machine opening, recommended: e = 150 mm
5	Machine opening contour

Fig. 7.13: Defining the protective field contour and reference contour, stationary point of operation guarding, vertical protective field

7.4 Stationary access guarding

The vertical protective field used for access guarding only detects people during passage through. After a person has passed through, a start/restart interlock must ensure that the dangerous movement does not start again automatically.

$$S_{RT} = K \cdot T + C_{RT}$$

S_{RT}	[mm]	= Safety distance
K	[mm/s]	= Approach speed for access guarding with approach direction orthogonal to the protective field: 2000 mm/s or 1600 mm/s, when S_{RT} > 500 mm
T	[s]	= Total time of the delay, sum from (t_a + t_i + t_m)
t_a	[s]	= Response time of the protective device, max. 80 ms
t_i	[s]	= Response time of the safety relay
t_m	[s]	= Stopping time of the machine
C_{RT}	[mm]	= Additional distance for access guarding with approach reaction with resolutions of 14 to 40 mm, d = resolution of protective device C_{RT} = 8 × (d - 14) mm. Additional distance for access guarding for resolutions > 40 mm: C_{RT} = 850 mm (standard value for arm length)

Response times, stopping time of the machine

The safety sensor's rotary mirror rotates on its own axis every 40 ms. One revolution is a scan. With each additional scan the response time t_a increases by 40 ms. With K = 2000 mm/s approach speed this corresponds with an increase in the safety distance of 80 mm per additional scan. With K = 1600 mm/s it is 64 mm.

↳ Select a response time t_a of 80 ms or higher.
Never define a value higher than 80 ms for t_a for access guarding or passage controls. With higher values it can happen that a person might not be detected when passing through the protective field with an approach speed of 1600 mm/s.

↳ Determine the machine/system's stopping time t_m.
If data is not available, you can commission Leuze to perform measurements (see chapter 14 "Service and support").

↳ If an increase in the stopping time within the regular test periods is to be expected, take an additional time into account for the machine's stopping time t_m.

Additional distance C_{RT} for finger protection

The required finger protection is ensured here by an additional distance C, which depends on the safety sensor resolution, in addition to the safety distance.

- Detection of an adult's hand:
  - Resolution: 30 mm
  - Additional distance C_{RT}: 128 mm
- Arm detection:
  - Resolution: 40 mm
  - Additional distance C_{RT}: 208 mm

Protective field contour and reference contour

With a vertical protective field, you must define at least two sides of the protective field contour as reference contour. The objective is to monitor the position of the protective field with regard to its marginal area. If the arrangement misaligns and the distance of the safety sensor to the reference surface changes as a result, switch the safety-related switching outputs off.

↳ When defining the protective field ensure that there are no gaps bigger than 150 mm.

↳ When defining the protective field boundaries, specify the sectors that monitor the position of the protective field as reference contour.

7.5 Mobile danger zone guarding on AGVs

Danger zone guarding protects people and objects that are in rooms in which vehicles move in, e.g. automated guided vehicle systems (AGVs).

A horizontally arranged protective field protects people and objects that are in the vehicle's path and are detected by the front edge of the protective field.

WARNING

Danger of injury because of insufficient vehicle stopping distance

↳ The operator of the machine must use organizing measures to prevent people from entering the protective field of the vehicle from the sides or being able to move towards an approaching vehicle.

↳ Only use the safety sensor on vehicles with electrical drive and electrically influenced drive and braking devices.

↳ Only install the safety sensor on the front of the vehicle.
If you must also guard the reverse travel, you must also install a safety sensor on the rear of the vehicle.

↳ Mount the safety sensor on the vehicle so that there are no unmonitored areas ≥ 70 mm between the protective field and vehicle front.

↳ Set the mounting height such that the beam level is not more than 200 mm above the floor.
A person lying on the floor can therefore be safely detected. This is required by the C standard, EN 1525 "Safety of industrial trucks – Driverless corridor supply vehicles and their systems".

NOTICE

The beam level of the safety sensor is level with the alphanumerical display.

7.5.1 Minimum distance D

$$D = D_A + Z_{Ges}$$

D	[mm]	= Minimum distance, vehicle front (danger) to protective field front edge
D_A	[mm]	= Stopping distance
Z_{TOT}	[mm]	= Sum of required additional distances

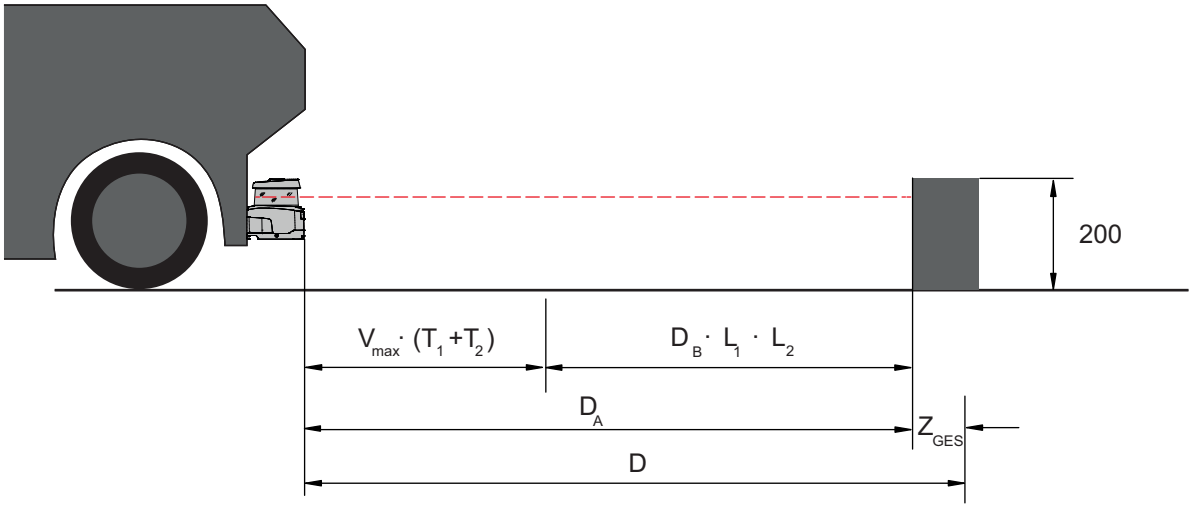


Fig. 7.14: Mobile danger zone guarding, calculation of required minimum distance D

Stopping distance D_A

$$D_A = v_{max} \cdot (T_1 + T_2) + D_B \cdot L_1 \cdot L_2$$

D_A	[mm]	= Stopping distance
v_{max}	[mm/s]	= Maximum vehicle speed
T_1	[s]	= Response time of the safety sensor
T_2	[s]	= Response time of the AGV
D_B	[mm]	= Braking distance with v_{max} and maximum vehicle load
L_1	[---]	= Factor for brake wear
L_2	[---]	= -Factor for problematic floor conditions, e.g. dirt, wet conditions

Additional distances Z

$$Z_{Ges} = Z_{SM} + Z_F + Z_{REFL}$$

Z_{tot}	[mm]	= Total of the required additional distances
Z_{SM}	[mm]	= Additional distance for system-related measurement error, see chapter 7.2 "Stationary danger zone guarding"
Z_F	[mm]	= Additional distance required with lack of floor space H_F
Z_{REFL}	[mm]	= Additional distance required with retro-reflectors beyond the protective field boundaries; Z_{REFL} = 100 mm

The **additional distance Z_{SM}** is always required. Its size depends on the biggest radius R_G from the safety sensor mirror's rotary axis to the protective field boundary without Z_{Tot}. The position of the rotary mirror axis depends on the installation situation.

The **additional distance Z_F** is required if the vehicle does not have enough free floor space H_F and there is therefore no space under the vehicle or the safety sensor for the tips of the feet. You determine the additional distance Z_F according to the following diagram:

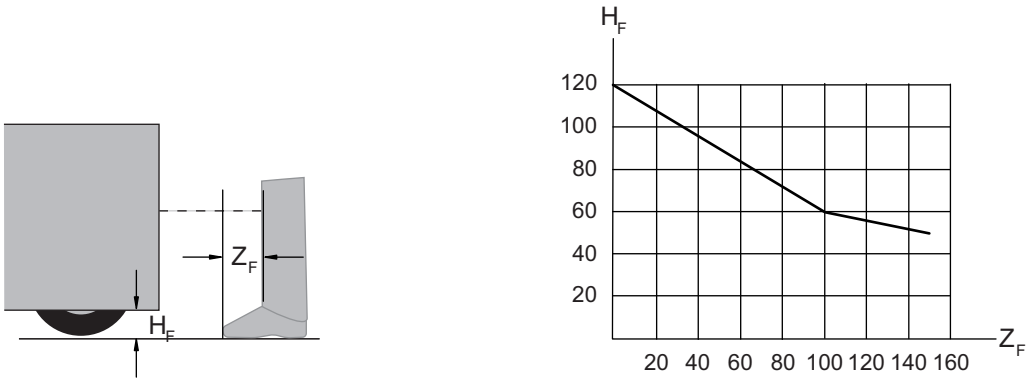
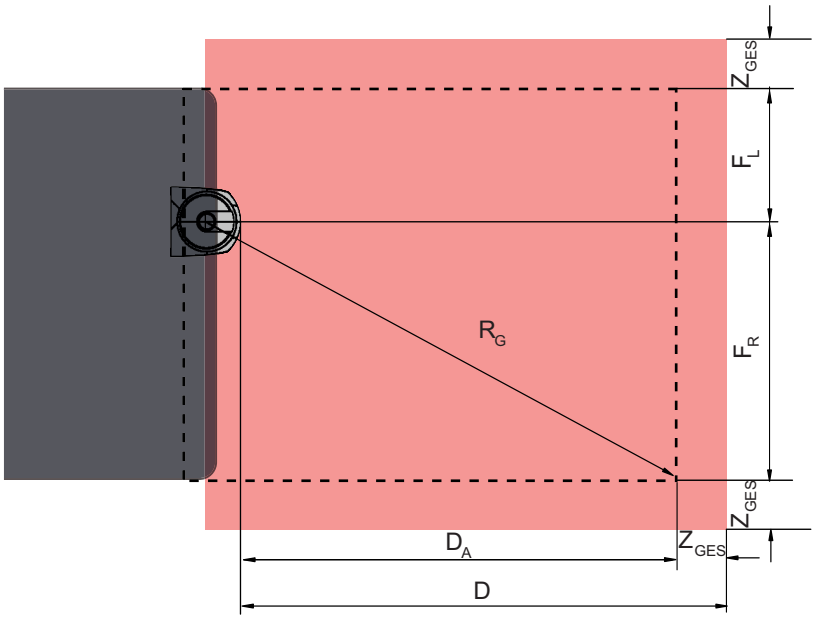


Fig. 7.15: Diagram for determining the additional distance Z_F with lack of floor space H_F

If wheels are mounted near the side wall, always add an additional distance Z_F > 150 mm.

7.5.2 Protective field dimensions



D	Minimum distance, vehicle front (danger) to protective field front edge
D_A	Stopping distance
Z_{TOT}	Total required additional distances to the front and for both sides
F_L	Distance from safety sensor center to left vehicle edge
F_R	Distance from safety sensor center to right vehicle edge
R_G	Biggest radius in the protective field without Z_{TOT} for determining the additional distance Z_{SM}

Fig. 7.16: Mobile danger zone guarding, dimensions for horizontal protective field

- Select 70 mm resolution.
- Set the protective field length so that the response time until braking and the braking distance, including factors for wear and tear and floor conditions, and any necessary additional distances are taken into account.
- Arrange the protective field symmetrically with reference to the vehicle width, even if the safety sensor is not arranged centered.
- Configure an upstream warning field that reduces the vehicle's speed.
  A full brake with a subsequent interruption of the protective field is then executed moderately and is less demanding on the vehicle's drives.
  Dimension the minimum distance D for the maximum speed as if the speed reduction initiated by the warning field had not happened.

- Take the required free space for lateral protrude protective fields under the roller conveyors along the transportation path into account.
- If you have to expect angular deviations of the vehicle during the travel, plan an additional tolerance area to guarantee undisturbed travel operation.

7.6 Mobile side guarding on AGVs

WARNING

Danger of injury because of insufficient vehicle stopping distance

- The operator of the machine must use organizing measures to ensure that people cannot enter the vehicle's protective field from the side.

- For mobile vertical protective fields use a resolution of at least 150 mm.
- Position the protective field edges in the travel direction in accordance with the front protective field edge of the horizontal protective field.
- Ensure that the response times of all components of the switch-off circuit are the same or balance the response times with different protective field dimensioning.
- Set the vertical protective fields at a slight angle so that the lower protective field edges protrude over the vehicle width by the amount of the additional distances, Z_{SM}, Z_F and Z_{REFL} where required; see chapter 7.5.2 "Protective field dimensions".

7.7 Mounting accessories

7.7.1 Mounting system

Using the mounting system you can adjust the safety sensor horizontally and vertically by ±10 degrees when mounting.

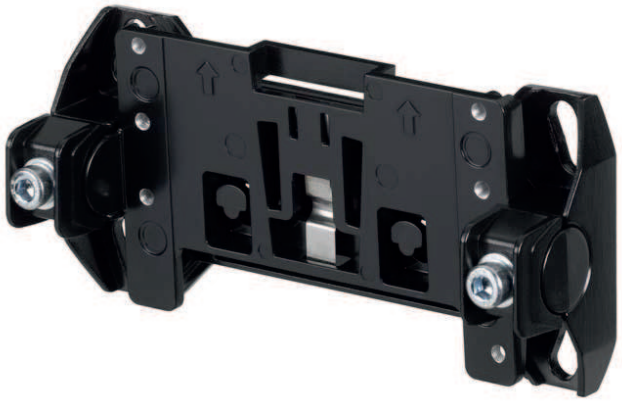


Fig. 7.17: BTU800M mounting system

NOTICE

Floor mounting only with mounting system BTU800M

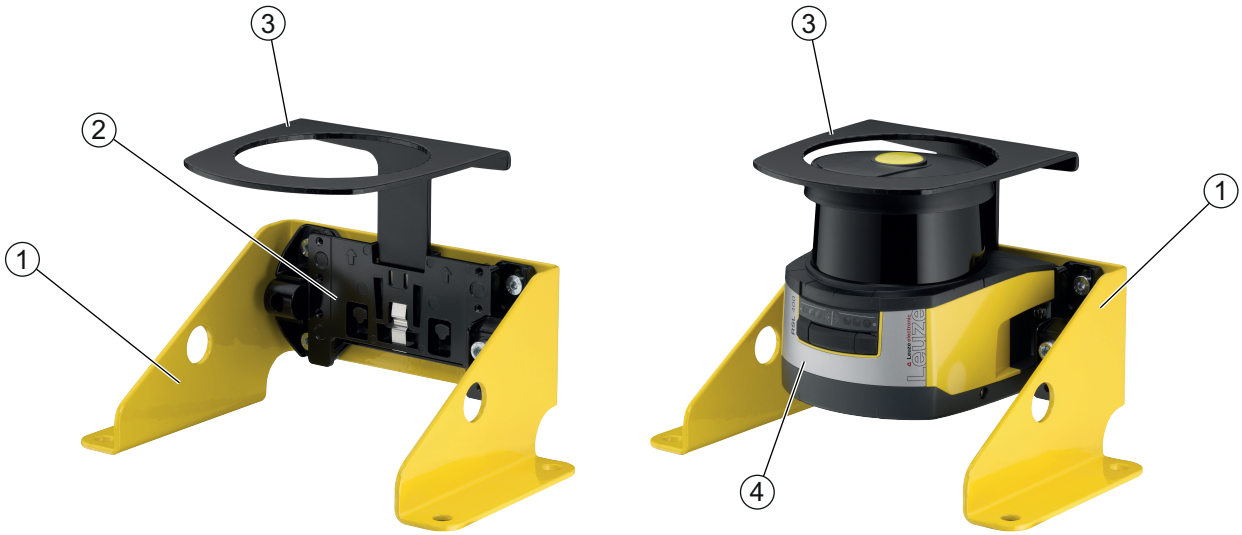
- The mounting system BTU800M must be used in the case of installation using the mounting bracket for floor mounting.

- Install the wall mount or mounting bracket for floor mounting on the system side.
- Mount the mounting system on the wall mount or on the mounting bracket for floor mounting.
- Attach the safety sensor to the mounting system.
  Tightening the screws fixes the safety sensor in position.
- Align the safety sensor using the integrated electronic spirit level.

7.7.2 Loop guard

The loop guard for the optics cover prevents damage to the safety sensor caused by light contact with foreign objects.

	NOTICE
	The loop guard can only be used together with the mounting system BTU800M.



1 BTF815M mounting bracket for floor mounting (only with BTU800M mounting system)
2 BTU800M mounting system
3 Loop guard
4 Safety sensor

Fig. 7.18: Loop guard

- Attach the safety sensor to the mounting system.
- Engage the loop guard for the optics cover from above into the mounting system.

8 Electrical connection

WARNING

Faulty electrical connection or improper function selection may result in serious injury!

- Only allow competent persons to perform the electrical connection.
- For access guarding, activate the start/restart interlock and make certain that it cannot be unlocked from within the danger zone.
- Select the functions so that the safety sensor can be used as intended (see chapter 2.1 "Intended use").
- Select the safety-relevant functions for the safety sensor (see chapter 5.2 "Function modes of safety sensor").
- Always loop both safety-related switching outputs OSSD1 and OSSD2 into the work circuit of the machine.
- Signal outputs must not be used for switching safety-relevant signals.

NOTICE

Laying cables!

- Lay all connection cables and signal lines within the electrical installation space or permanently in cable ducts.
- Lay the cables and lines so that they are protected against external damages.
- For further information: see EN ISO 13849-2, Table D.4.

NOTICE

Observe the maximum cable length!

Observe the maximum cable lengths as a function of operating voltage and load current (see chapter 8.3 "Connection unit CU416").

NOTICE

Observe when wiring with terminals and connectors!

In the case of wiring that continues beyond the device or during repairs to connectors, the user must ensure that cables or conductors that have defectively disconnected cannot result in contact with other signals.

- Use suitable terminals.
- Use heat-shrink tubing, wire-end sleeves or similar.

8.1 Electrical supply

see chapter 15.1 "General specifications".

Functional earth

NOTICE

Always connect the housing of the safety sensor to functional earth or ground!

- The housing of the safety sensor must always be connected to earth (functional earth) or machine/vehicle ground.
- If the safety sensor is attached to a non-conductive material (e.g. a concrete wall), the housing of the safety sensor must be earthed.

- Factory recommendation: Functional earth via a ground strap/braid (low impedance for RF). Connection points for self-tapping screws used for the ground connection are provided and labeled on the bottom of the connection unit (see chapter 8.3 "Connection unit CU416").
- Functional grounding via the shield of the connection cable. For grounding, the shield of the connection cable in the switch cabinet must be connected to earth or machine/vehicle ground.

NOTICE

Make sure that potential equalization is provided!

- If the housing of the safety sensor or the mounting bracket – despite being mounted on a non-conductive material – is connected to metallic parts (even temporarily), you must ensure that the appropriate potential equalization is provided between the switch cabinet and housing potential; e.g. by grounding the Ethernet connection.

8.2 Interfaces

The safety sensor has the following interfaces:

- Interface for connection with the control system
- Ethernet interface for communication with PC or laptop
- USB interface for communication with PC or laptop

Tab. 8.1: Interfaces

Interface	Type	Function
Control	Connection cable, 16-wire	• Power supply • Switching lines and signal lines
Communication	M12 – RJ 45	Configuration interface and data interface: • Parameter configuration • Protective field definition and warning field definition • Data transmission and measurement value transmission • Diagnosis
Communication	USB 2.0 mini-B socket	Configuration interface and diagnosis interface: • Parameter configuration • Protective field definition and warning field definition • Diagnosis

NOTICE

- Use the USB connection only temporarily for configuration or diagnosis of the safety sensor.
- For permanent connection, connect the safety sensor to the Ethernet connection of the connection unit.

The control cable is permanently attached to the connection unit. A protection cap on the connection unit protects the communication interface when no PC is connected.

8.2.1 Connection cable, control

The safety sensor is equipped with a 16-wire connection cable.

Tab. 8.2: Connection cable, control

Core color	Signal	Description
White	RES1	Start/restart input, protective function A Acknowledgment
Brown	24 V	Supply voltage
Green	EA1	Contactor monitoring OSSD A State signaling, configurable
Yellow	A1	Output signal State signaling, configurable
Gray	OSSDA1	Safety-related switching output, protective function A
Pink	OSSDA2	Safety-related switching output, protective function A
Blue	0 V (GND)	Supply voltage ground
Red	MELD	Output signal State signaling, configurable
Black	F1	5 function inputs for field pair changeover, protective function A
Violet	F2	
Gray/pink	F3	
Red/blue	F4	
White/Green	F5	
Brown/Green	SE1	Linkage input (E-Stop, OSSD – external device)
White/Yellow	SE2	Linkage input (E-Stop, OSSD – external device)
Yellow/Brown	A2	Output signal State signaling, configurable

8.2.2 Connection cable with M30 connector

The safety sensor is equipped with a 16-pin M30 connector.

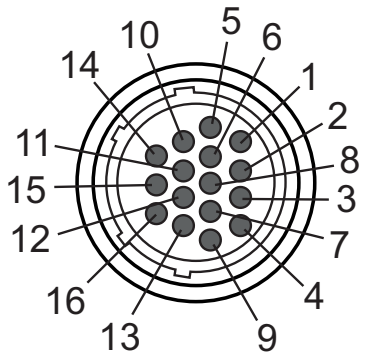


Fig. 8.1: Pin assignment for M30 connector, 16-pin

Tab. 8.3: Pin assignment

Pin	Core color	Signal	Description
1	White	RES1	Start/restart input protective function A acknowledgment
2	Brown	24 V	Supply voltage
3	Green	EA1	Contactor monitoring OSSD A Alternatively: State signaling, configurable
4	Yellow	A1	Output signal state signaling, configurable
5	Gray	OSSDA1	Safety-related switching output protective function A
6	Pink	OSSDA2	Safety-related switching output protective function A
7	Blue	0 V (GND)	Supply voltage ground
8	Red	MELD	Output signal State signaling, configurable
9	Black	F1	5 function inputs for field pair changeover protective function A Field pair changeover with 100 field pairs (A1.x) – 2nd position Field pair changeover with multi configuration (A1.x) within one bank
10	Violet	F2	
11	Gray/pink	F3	
12	Red/blue	F4	
13	White/Green	F5	
14	Brown/Green	SE1	Linkage input (E-Stop, OSSD – external device)
15	White/Yellow	SE2	Linkage input (E-Stop, OSSD – external device)
16	Yellow/Brown	A2	Output signal state signaling, configurable
Connector housing	Shield	FE	Functional earth, connection cable shield

8.2.3 Pin assignment of M12 Ethernet interface (communication) (D-coded)

The safety sensor is equipped with a 4-pin M12 connector.

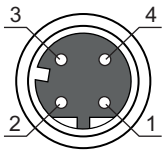
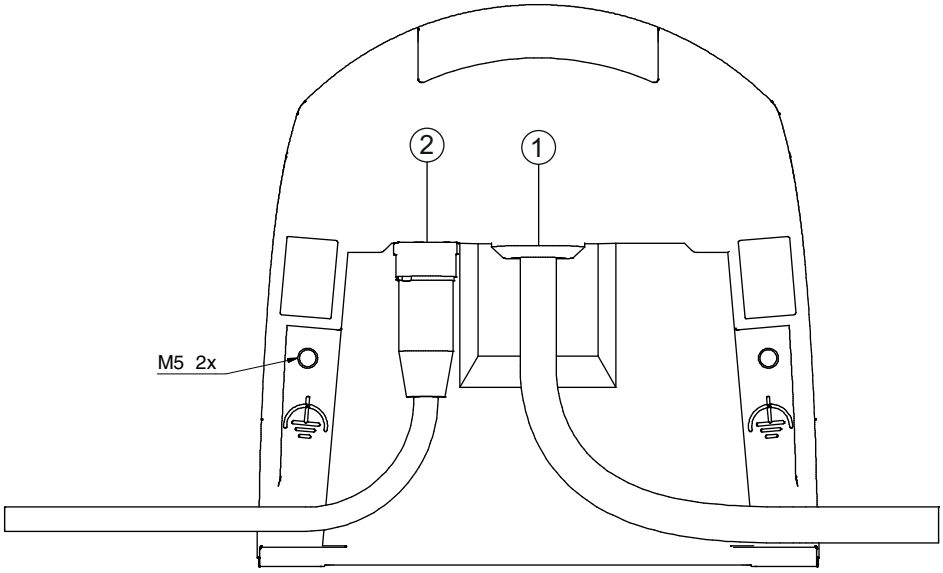


Fig. 8.2: Pin assignment of the Ethernet interface

Tab. 8.4: Pin assignment of the Ethernet interface

PIN	Signal	Description
1	TD+	Data communication, transmission
2	RD+	Data communication, transmission
3	TD-	Data communication, reception
4	RD-	Data communication, reception
FE	GND/shield	Functional earth, communication cable shield. The shield of the inter-connection cable is on the thread of the M12 connector. The thread is part of the metallic housing. The housing is at the same potential as functional earth.

8.3 Connection unit CU416



1 Connection cable, connection to the machine
2 M12 socket, D-coded, Ethernet communication connection
M5 Connection for functional earth with M5 x 10 self-cutting/self-tapping (gas tightness) and ground strap

Fig. 8.3: Connection unit CU416

Cable lengths as a function of operating voltage and load current

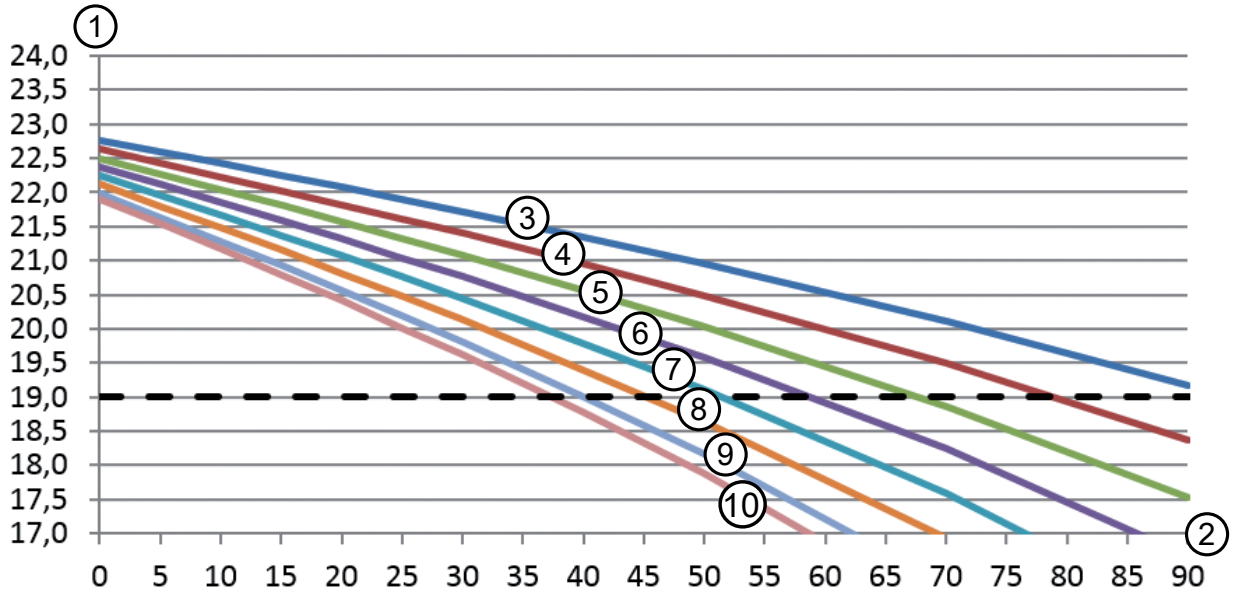
The maximum cable length is determined by voltage drops on the supply and signal lines.

The following conditions apply for the necessary operating voltage U_B at the input terminals of the connection unit:

- U_B must be greater than the permissible nominal voltage limit of 16.8 V.

	NOTICE
	The recommended operating voltage is at least 19 V! Leuze recommends an operating voltage U_B of at least 19 V at the input terminals of the connection unit. ↳ The operating voltage should not be allowed to drop below the recommended value if possible.

- The necessary operating voltage U_B must also ensure the function of the downstream devices.
  - Once the operating voltage U_B has been determined, check whether the resulting signal voltages are sufficient for the downstream devices.
  - Take into account the voltage drops in the safety sensor – up to 3.2 V – and on the signal wiring.



1 Operating voltage [V]
2 Cable length [m]
3 I_{Load} = 0 A
4 I_{Load} = 250 mA
5 I_{Load} = 500 mA
6 I_{Load} = 750 mA
7 I_{Load} = 1 A
8 I_{Load} = 1.25 A
9 I_{Load} = 1.5 A
10 I_{Load} = 1.65 A

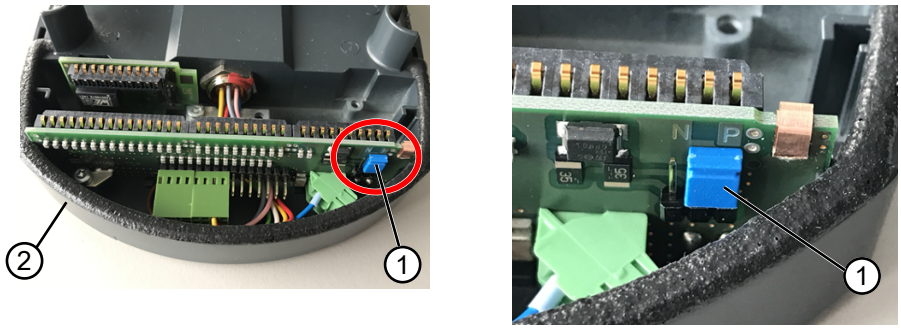
Fig. 8.4: Diagram for estimating the voltage drop on the supply line

- Maximum load current: 1 A with RSL 400 cable
  1 mm²/AWG18 for supply and 0.14 mm²/AWG26 for signals

PNP/NPN changeover

The PNP/NPN changeover for signal inputs F1 … F5, RES1 is performed via a jumper on the connection unit. The reference potential for the signal inputs is set via the jumper:

- P: reference potential +24 V
- N: reference potential 0 V (GND)



1 Jumper
2 Connection unit

Fig. 8.5: Jumper for PNP/NPN changeover

	NOTICE
	PNP/NPN changeover occurs simultaneously for signals F1 … F5, RES1.

8.4 Cable lengths according to the operating voltage

The maximum cable length is determined by voltage drops on the supply and signal lines.

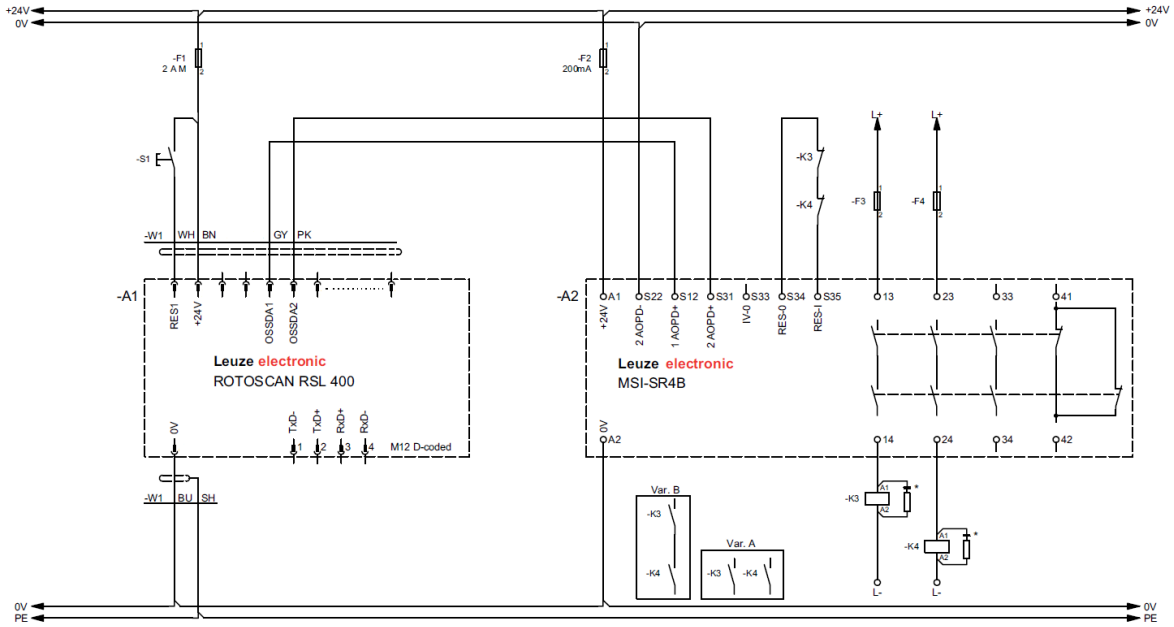
The following conditions apply for the necessary operating voltage U_B at the input terminals of the connection unit:

- U_B must be greater than the permissible nominal voltage limit of 16.8 V.

	NOTICE
	The recommended operating voltage is at least 19 V! Leuze recommends an operating voltage U_B of at least 19 V at the input terminals of the connection unit. ↳ The operating voltage should not be allowed to drop below the recommended value if possible.

- The necessary operating voltage U_B must also ensure the function of the downstream devices in the case of a linear configuration.

8.5 Circuit diagram example



* Spark extinction circuit, suitable spark extinction provided

Fig. 8.6: RSL 420 with MSI-SR4B safety relay

9 Configuring the safety sensor

To start up the safety sensor in your application, the safety sensor must be individually adapted using the software. All configuration data is defined using the configuration and diagnostics software.

General procedure for configuring safety sensor

↳ Assessing the risk

- The system has been determined and its boundaries defined.
- The safety sensor has been selected as the safety component.
- The type of guarding has been determined (danger zone guarding, point of operation guarding, access guarding).

↳ Calculating safety distance
Shape and size of the protective and warning fields

↳ Configuring the safety sensor

- Configuration and diagnostics software (see chapter 4 "Configuration and diagnostic software Sensor Studio")
- Determine the configuration project (see chapter 9.3 "Determine the configuration project")
- Configure the protective function (see chapter 9.4 "Configuring protective function")

↳ Checking function (see chapter 11 "Testing")

9.1 Defining safety configuration

WARNING

Serious accidents caused by incorrect safety configuration!

The protective function of the safety sensor is only ensured if the safety sensor is correctly configured for the intended application.

↳ Allow only competent persons to perform safety configuration.

↳ Select the safety configuration so that the safety sensor can be used as intended (see chapter 2.1 "Intended use").

↳ Select the protective field dimensions and contours according to the safety distance calculated for the application (see chapter 7.1.1 "Calculation of safety distance S").

↳ Select the parameters of the safety configuration according to your risk analysis.

↳ After start-up, check the function of the safety sensor (see chapter 11.1 "Before the initial start-up and following modifications").

WARNING

Additional protection against manipulation when the monitoring time is increased!

If the monitoring time is increased to above 5 s or if manipulation protection is deactivated, the system operator must introduce other measures to prevent manipulation.

↳ For example, make sure that the distance range in which manipulation is possible cannot be accessed by personnel under normal operating conditions.

NOTICE
OSSDs will switch off if no reflection signals are being measured! If the safety sensor is unable to measure any reflection signals in a continuous scanning angle of ≥ 90° for a long period of time, the safety-related switching outputs switch off. In certain application types (e.g. in buildings with extremely large distances), the safety sensor may not be able to measure any reflection signals. For such application types, it is possible to set or deactivate the monitoring times. ↳ In the **CONFIGURATION** menu, click the *Other* option. ⇨ The **OTHER** dialog box opens. ↳ In the **PROTECTION AGAINST MANIPULATION** dialog box, define the monitoring time according to your specific conditions. ⇨ If the parking position is active, there will be no manipulation monitoring.

Prerequisites:

- The safety sensor is mounted (see chapter 7 "Mounting") and connected (see chapter 8 "Electrical connection") correctly.
- Dangerous process is switched off, outputs of the safety sensor are disconnected, and the system is protected against being switched back on.
- The size of the protective field is determined on the basis of the mounting location, the calculated safety distances and additional distances.
- The start/restart operating mode required by the application has been determined.
- The conditions for field pair changeover, if required, have been determined.
- The configuration and diagnostics software for the safety sensor is installed on the PC (see chapter 4.2 "Installing software").

NOTICE
Many safety-relevant parameters are preset for each application in the configuration and diagnostics software. Use these preset values where possible.

Procedure

All configuration data is defined using the configuration and diagnostics software.

To configure the safety sensor, proceed as follows:

↳ Connect the PC to the safety sensor

↳ Start the software

- Set up communication
- Determine the configuration project

↳ Configure the protective function using the project wizard

- Protective/warning field configuration
- Resolution and response time
- Start-up behavior
- Contactor monitoring
- E-stop linkage
- Field pair changeover
- Configuration of the signal outputs

↳ Save configuration project

↳ Transferring a configuration to the safety sensor

↳ Create a record document for the device configuration and protective field dimensioning. The document must be signed by the person responsible for the configuration.
To document the configuration, you can create a PDF file of the safety configuration or save the configuration and settings in an *.xml file.

NOTICE

The configuration data is stored in the connection unit of the safety sensor and is therefore also available after replacement or repair of the scanner unit. The configuration data only needs to be transferred again if changes are made to the configuration.

9.2 Connecting safety sensor to PC

9.2.1 Connection via Ethernet cable

↳ Connect the Ethernet cable to the PC or to the network; see the document "Quick Start Guide RSL 400".

NOTICE

The TCP/IP protocol is used for communication via Ethernet.

9.2.2 Connection via Bluetooth

Prerequisites: Bluetooth communication of the safety sensor has been activated (see chapter 9.2.4 "Communication between safety sensor and PC")

↳ Activate the Bluetooth interface on the PC.

↳ Select the safety sensor as the device for the Bluetooth connection.

NOTICE

Distance between safety sensor and PC

The possible distance between safety sensor and PC depends on the quality of the Bluetooth adapter that is used.
USB Bluetooth adapters with external rod antenna enable a larger operating range.

9.2.3 Connection via USB

The USB interface is behind a protection cap on the front of the safety sensor.

NOTICE

Distance between safety sensor and PC with USB connection!

The USB interface of the safety sensor is connected to the USB interface on the PC with a standard USB cable (plug combination - Mini-B type / Type A).

The distance between safety sensor and PC is limited to 5 m if a standard USB cable is used. Use active USB cables if longer cable lengths are required.

NOTICE

↳ If possible, use the ready-made cables from Leuze (see chapter 17 "Order guide and accessories").

- Connect the USB cable to the safety sensor and the PC.
- Select the *LAN / USB (RNDIS)* interface for the device search.
- Start the device search by clicking the [Start] button.
- Select the safety sensor from the list of found devices.

NOTICE

↳ After use, seal the USB connection using a protection cap. Make sure that the protection cap is felt to engage when sealing. The IP degree of protection specified in the technical data is only achieved when the protection cap is closed.

9.2.4 Communication between safety sensor and PC

The following communication settings are active when the safety sensor is delivered:

LAN

- DHCP: Obtain IP address automatically

USB

Bluetooth

- Bluetooth module activated
- Device scan activated

You can change the communication settings on the PC using the configuration and diagnostics software in order to, for example, assign a permanent IP address to the safety sensor in your network.

↳ Start the configuration and diagnostics software on your PC.

⇨ The **mode selection** of the Project Wizard is displayed.

⇨ If the **mode selection** is not shown, click the [Project Wizard] button ( ) in the menu bar of the software to start the project wizard.

↳ Select the configuration mode and click [Next].

⇨ The **Project Wizard** displays the **device selection** list containing the configurable safety sensors.

↳ Select the safety sensor from the device selection list and click [Next].

⇨ The initial screen for the configuration project is displayed together with information for identification of the selected safety sensor.

↳ In the initial screen, click the *SETTINGS* tab.

⇨ The **SETTINGS** menu opens.

Assign permanent IP address

↳ Select the menu command **Communication > LAN**.

↳ In the **DHCP** dialog box, deactivate the *Obtain IP address automatically* checkbox.

↳ In the **CONNECTION SETTINGS** dialog box, enter the IP address information.

Activating/deactivating the Bluetooth interface

↳ Select the menu command **Communication > Bluetooth**.

↳ Activate/deactivate communication with the safety sensor via the Bluetooth interface using the *Activate Bluetooth module* checkbox. If the Bluetooth module is deactivated, communication with the safety sensor via the Bluetooth interface is not possible.

↳ Activate/deactivate the Bluetooth device scan using the *Activate device scan* checkbox. If the device scan is deactivated, the safety sensor will not be found during the Bluetooth device scan. To allow communication via the Bluetooth interface, you must enter the device identification of the safety sensor manually.

9.3 Determine the configuration project

↳ Start the configuration and diagnostics software on your PC.

⇨ The **mode selection** of the Project Wizard is displayed.

⇨ If the **mode selection** is not shown, click the [Project Wizard] button ( ) in the menu bar of the software to start the project wizard.

	NOTICE
	During installation of the software, a user *admin* (without password query) is created so that you can start the software without user identification. If other users are registered (**Tools > User management** in the FDT frame menu), you must log in at the software with a user name and password. This setting allows you to connect to the safety sensor and to read out, upload, enter or change the safety configuration and all settings using the RSL 400 device DTM. The password for the safety sensor only needs to be entered (i.e. the access level only needs to be changed) when the changes are downloaded to the safety sensor (see chapter 4.5.1 "Selecting access level").

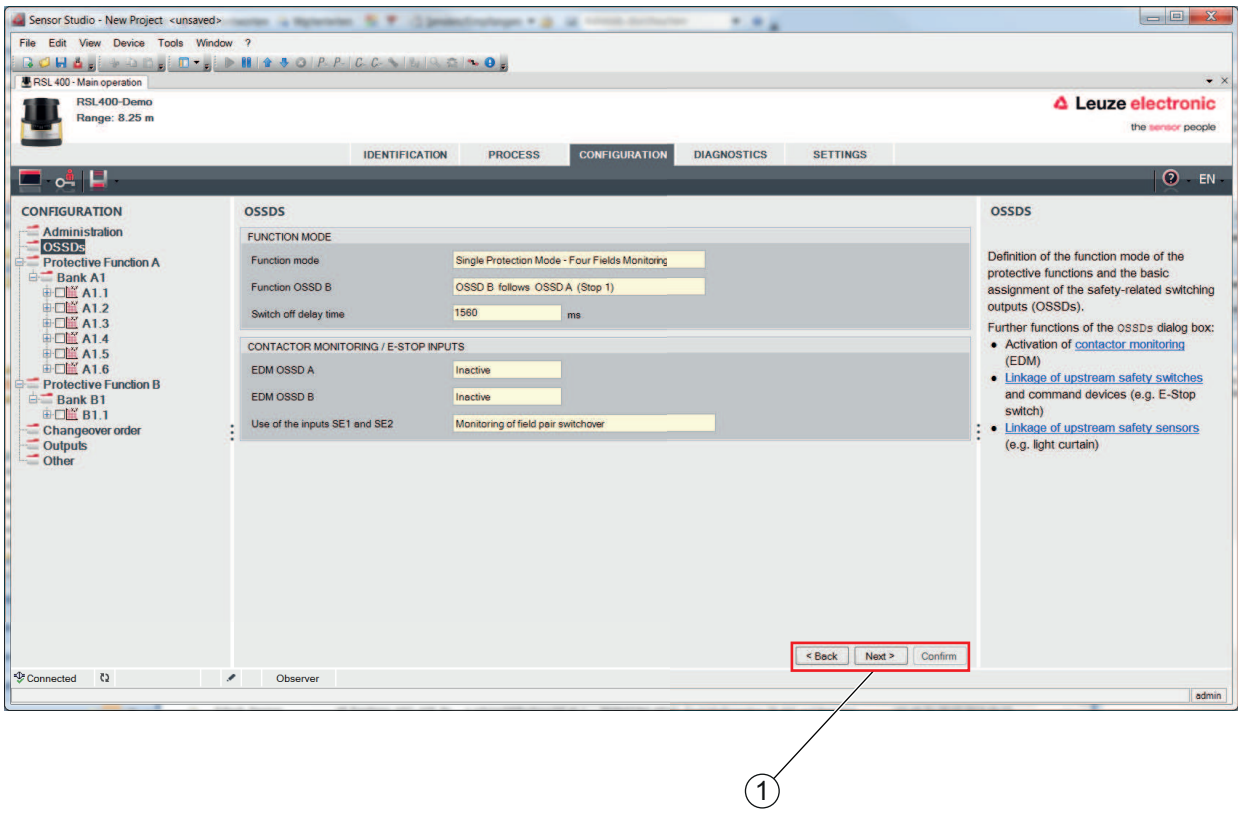
↳ Select the configuration mode and click [Next].

⇨ The **Project Wizard** shows the list of configurable safety sensors.

NOTICE
You can use a prepared configuration project as a template and make changes to it. To do so, select the configuration mode *Open a stored project file*. If you want to load the configuration project currently stored in the safety sensor to the PC, select the configuration mode *Device selection with device scan and establishment of connection (online)*.

↳ Select the safety sensor in the **Sensor** list and click OK.
Alternatively, you can select the safety sensor by entering the part number or by specifying the sensor range and the sensor type.

⇨ The device manager (DTM) of the safety sensor shows the initial screen for the configuration project.



1 Configuration Wizard

Fig. 9.1: Safety configuration using Configuration Wizard

NOTICE
The device manager (DTM) starts without querying the access level of the user. During communication with the safety sensor, the safety sensor does however query the access level of the user. To change the access levels, see chapter 9.9 "Selecting access level".

9.4 Configuring protective function

Prerequisites: The safety distance, additional distances and protective field dimensions and contours have been determined according to the mounting position (see chapter 7.1.1 "Calculation of safety distance S").

↳ In the initial screen, click the *CONFIGURATION* tab.

⇨ The CONFIGURATION menu opens with the options:

- Administration
- *OSSDs*
  If the *OSSDs* option is selected in the **CONFIGURATION** menu, the *Protective function A* option is displayed.
- *Changeover order*
  The *Changeover order* option is only displayed if more than one protective/warning field pair is created (see chapter 9.4.4 "Creating and configuring protective/warning field pairs").
- *Outputs*
- *Other*

9.4.1 Creating simple safety configuration

To create a safety configuration for simple commissioning, you must first perform five configuration steps to access the editor used for defining the contours of the protective and warning fields.

By clicking [Next], you can proceed to the next configuration step without selecting the corresponding option in the **CONFIGURATION** menu.

If you make changes to the default settings in a configuration step, first click the [Confirm] button and then [Next].

↳ *Administration*

↳ *OSSDs*

↳ *Protective function A*

↳ *Bank A1*

↳ *Outputs*

9.4.2 Entering administration parameters

↳ In the **CONFIGURATION** menu, click the *Administration* option.

⇨ The **ADMINISTRATION** dialog box opens.

↳ In the input fields, enter the device data and the project data for the configuration project.

9.4.3 Activating protective function and contactor monitoring

↳ In the **CONFIGURATION** menu, click the *OSSDs* option.

⇨ The **OSSDs** dialog box opens.

↳ In the **FUNCTION MODE** list, select the protective function of the safety sensor.

⇨ The *Protective function A* option is shown in the **CONFIGURATION** menu.

	NOTICE
	The changeover-capable protective/warning field pairs for the selected protective function are defined in configuration banks.

↳ In the **CONTACTOR MONITORING** list, activate the contactor monitoring of the safety sensor:

- EDM OSSD A
- E-Stop
- OSSD linkage

NOTICE
The activated contactor monitoring (EDM) is assigned to indication signal outputs EA1 and/or EA2. These signal outputs are thus disabled for the configuration of the signal outputs.

↳ Click the [Confirm] button.

9.4.4 Creating and configuring protective/warning field pairs

The changeover-capable protective/warning field pairs for the selected protective function are defined in configuration banks. The configuration banks are shown in the navigation tree of the configuration menu as "Bank", e.g. *Bank A1*.

Creating banks

↳ In the **CONFIGURATION** menu, click the *Protective function A* option.

⇨ The **PROTECTIVE FUNCTION A** dialog box opens.

↳ Enter the description of the protective function in the input field.

↳ In the **CONFIGURATION** menu, right-click the *Protective function A* option.
Select *Add configuration bank*.

⇨ The **Add bank** dialog box opens.

↳ In the **Bank** list, select the number of the bank and click the [Add] button.
When you have added all banks for the protective function, click [Close].

⇨ The *Bank [x]* option is shown for each added bank under *Protective function A* in the **CONFIGURATION** menu.

Configuring banks

The resolution for hand, leg or body detection, the response time and start-up behavior of the safety sensor and the field pair changeover for the protective/warning field pairs are configured via the banks.

NOTICE
For resolution, response time and AGV speed, select the values that you used for calculating the safety distances and additional distances for the application assigned to the configuration bank.

↳ In the **CONFIGURATION** menu, select the bank the configuration of which you want to define.

⇨ The **RESOLUTION**, **RESPONSE TIME**, **START-UP BEHAVIOR** and **EXTENDED OUTPUT SIGNALS** dialog boxes are displayed.

↳ In the **RESOLUTION** dialog box, enter the resolution and, if applicable, the maximum speed of an automated guided vehicle (AGV) in the input fields.

NOTICE
If in the *Resolution* and *Max. AGV speed* input fields you select values > 0, the application usually used for the bank is displayed in the *Application* field, e.g. *Point of operation guarding*. For access guarding, point of operation guarding and danger zone guarding, you must select *Max. AGV speed* = 0!

↳ In the **RESPONSE TIME** dialog box, select the response time of the safety sensor.

↳ In the **START-UP BEHAVIOR** dialog box, select the start-up behavior and the restart time of the safety sensor.

NOTICE
Configuration of the start-up behavior is only implemented if the corresponding electrical signal connections exist; see chapter 8 "Electrical connection".

↳ In the **EXTENDED OUTPUT SIGNALS** dialog box, activate the definition of output signals.

↳ Click the [Confirm] button.

↳ Configure all other banks of the protective function following the described procedure.

Create protective and warning fields

A field pair consists of one protective field and one warning field.

↳ In the **CONFIGURATION** menu, right-click the *Bank 1* option under *Protective function_A* Select *Add field pair*.

⇨ The **Add field pair** dialog box opens.

↳ In the **Field pair** list, select the number of the field pair and click the [Add] button. When you have added all field pairs for the bank, click [Close].

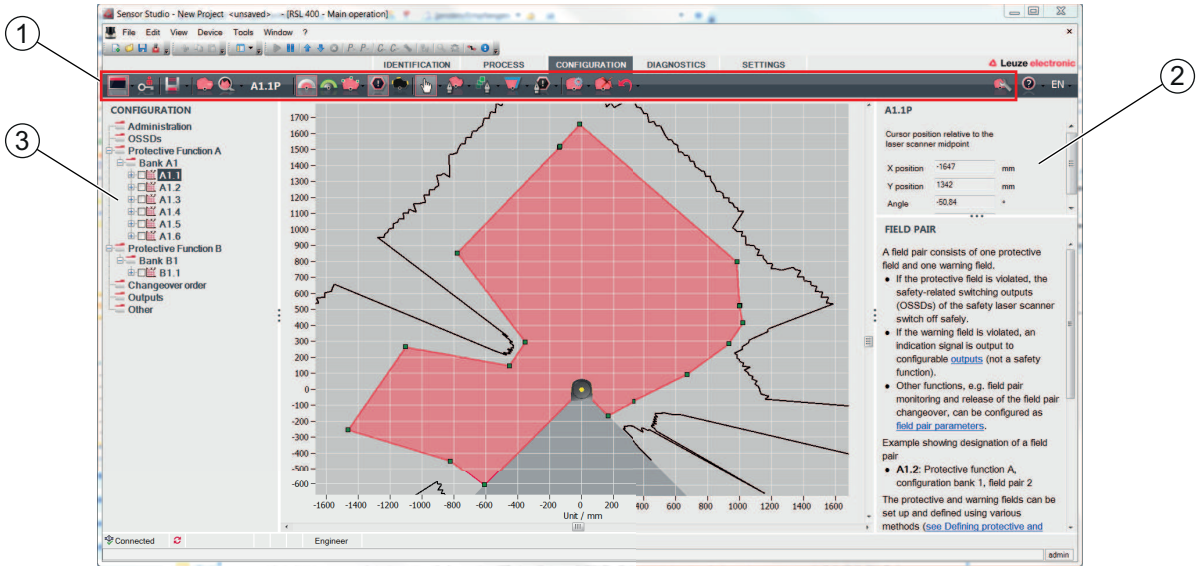
⇨ The added field pairs are shown in the **CONFIGURATION** menu as an option under *Bank 1* under *Protective function_A*. The *Parameters* option is displayed for each field pair.

↳ Add the field pairs for the other banks of *Protective function A* if one protective function with multiple configuration banks has been selected.

⇨ The added field pairs are shown in the **CONFIGURATION** menu under *Bank [x]* under *Protective function A*.

Configure protective and warning fields

Defining contours and boundaries for protective field and warning field



1 Toolbar of field editor
2 Display of field coordinates
3 Structure of safety configuration

Fig. 9.2: Field editor with toolbar for field definition

↳ In the **CONFIGURATION** menu, click the field pair the protective and warning fields of which you want to define.

↳ Click the  button and define the contours and boundaries of the protective field.

	NOTICE
	Determine protective field size! The protective field size is determined by the calculated safety distances and additional distances that you determined for the application assigned to the configuration bank.

	NOTICE
	With protective field boundaries <200 mm, object detection may be restricted owing to the measurement error. ↳ When defining the protective field, take into account the additional distance Z_{sm} to the protective field contour (see chapter 7.2 "Stationary danger zone guarding").

↳ Click the  button and define the contours and boundaries of the warning field.

NOTICE
By right-clicking the field pair in the **CONFIGURATION** menu, you can calculate an autocontour for the protective or warning field. You can determine the display options for the field editor in the menu **SETTINGS > Field editor display options** (see chapter 4.5.6 "SETTINGS").

↳ Configure all other field pairs of the configuration bank following the described procedure.

NOTICE
It is also possible to read in an RS4 configuration file as well as to convert the protective fields on the RSL400. Note here, that the converted field pairs are only contour suggestions. Therefore, check that the fields are appropriate for the requirements of your safety application.

9.4.5 Configuring field pair monitoring

↳ In the **CONFIGURATION** menu, click the *Parameters* option of the field pair the protective and warning fields of which you have defined.

↳ Select the monitoring mode for the field pair in the **Field pair monitoring** list.

9.5 Defining permissible field pair changeovers

If monitoring of field pair changeover is activated, you can define the permissible sequence of field pair changeovers.

Determining changeover mode

↳ In the **CONFIGURATION** menu, select the *protective function A* option.

↳ In the dialog box **MODE FOR FIELD PAIR ACTIVATION AND CHANGEOVER**, select the field pair activation, the mode for field pair changeover and, if required, the changeover time.

Field pair activation Changeover mode	Description
Fixed selection of one field pair	Changeover of two field pairs
Selection by signal inputs Fixed changeover moment	Changeover of 10 field pairs (see chapter 5.7.3 "Changeover of ten field pairs in changeover mode Fixed changeover moment") When the changeover time has expired, the system changes over to the field pair which at this time has a permanent and valid assignment. Field pair changeover signals issued during the changeover time are ignored. The inputs F1 - F5 are active.
Selection by signal inputs Overlapped monitoring	Changeover of 5 field pairs () Both field pairs are monitored during the changeover time. The inputs F1 - F5 are active.

↳ Click the [Confirm] button.

Determining changeover order

↳ In the **CONFIGURATION** menu, select the *Changeover order* option.

⇨ The **CHANGEOVER ORDER** dialog box opens.

↳ In the **MONITORING OF FIELD PAIR CHANGEOVER** dialog box, activate the *Monitoring* option.

↳ In the **MONITORING OF FIELD PAIR CHANGEOVER** dialog box, define the sequence of field pair changeovers according to your conditions.

↳ Click the [Confirm] button.

9.6 Configuring signal outputs

You can define which indication signals are transmitted to the individual indication signal connections.

- In the **CONFIGURATION** menu, select the *Outputs* option.

The **OUTPUTS** dialog box opens.

- For each usable connection, select the function group and the function of the indication signal.
- Click the [Confirm] button.

NOTICE
All signal outputs are *high active*, i.e. logical 1 or +24 V DC with an active signal.

9.7 Saving configuration

To save the changed configuration loaded in the software, you can transfer the configuration and settings to the safety sensor or save them in a file on the PC.

Saving safety configuration as PDF file

- In the CONFIGURATION menu, click the [Create PDF file of safety configuration] button.
- Determine the storage location and the file name for the safety configuration.
- Click [Save].
- ⇨ The safety configuration is saved as a PDF file.

Saving configuration and settings as file

- In the **CONFIGURATION** menu or in the **SETTINGS** menu, click the [Save configuration and settings to file] button.
- Determine the storage location and the name of the configuration file.
- Click [Save].
- ⇨ The configuration and settings are saved in the file format *.xml.

Saving configuration project as file

- In the menu bar of the FDT frame menu, click the  button.
  Alternatively, select the menu command **File > Save**.
- Determine the storage location and the name of the configuration project file.
- Click [Save].

9.8 Transferring configuration project to safety sensor

The changes that you have made to the configuration only become effective when the changed configuration project file is transferred to the safety sensor.

Prerequisites:

- The software and safety sensor are connected.
- The changed configuration project has been loaded in the software.
- The individual password for the access level *Engineer* is available.
  - Only users with the access level *Engineer* can transfer configuration data to the safety sensor. To change the access level, see chapter 9.9 "Selecting access level".
  - If no individual password has been defined for the access level *Engineer*, use the preset default password (**safety**).

NOTICE
Alternatively, you can transfer a configuration project saved as a file on the PC directly to the safety sensor.

↳ In the menu bar of the FDT frame menu, click the [download arrow] button. Alternatively: In the FDT menu bar, select **Device > Download parameters**.

⇨ The software asks for the access level and the password.

↳ Select the access level *Engineer* and enter the preset default password (**safety**) or the defined individual password.
Confirm with [OK].

↳ Before downloading the safety configuration, check whether you are connected to the correct safety sensor.
Confirm the displayed safety notice with [Yes].

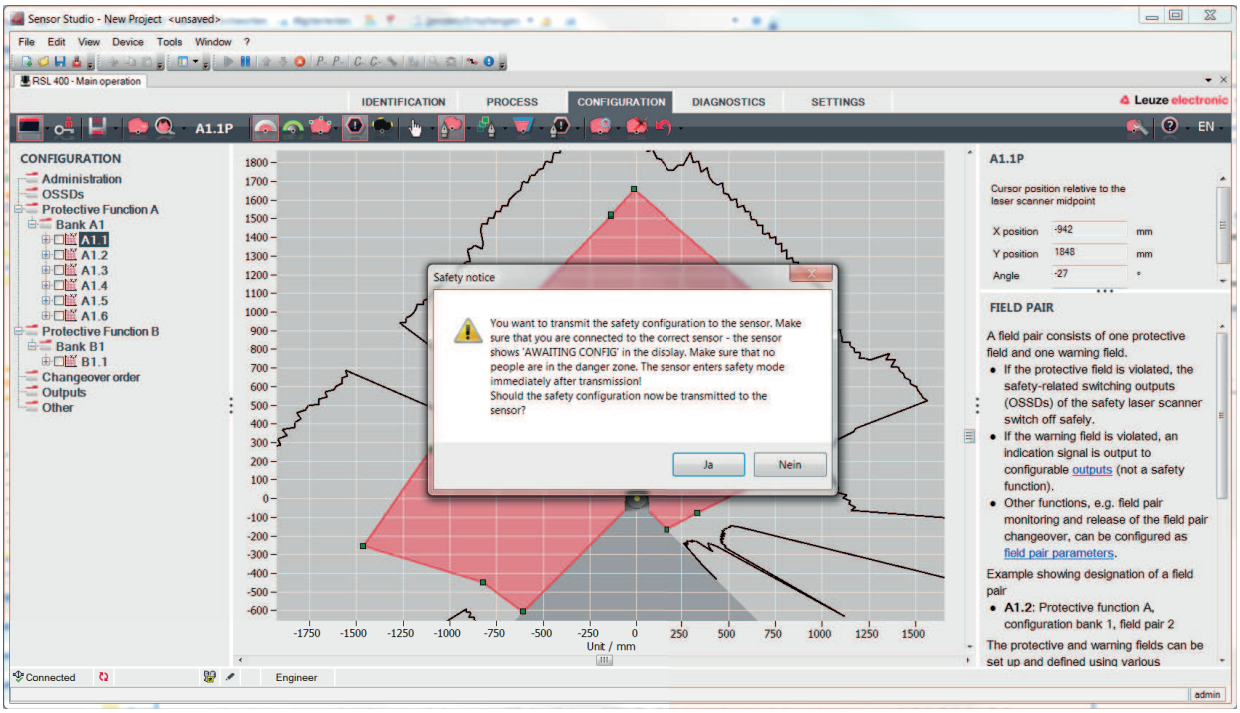


Fig. 9.3: Check before safety configuration is downloaded

The software transfers the data of the configuration project to the safety sensor.

After successful transfer, the safety sensor immediately enters safety mode, i.e. the safety-related switching outputs switch on if all conditions are fulfilled.

- The configuration data is saved in the connection unit of the safety sensor.
- A copy of the safety configuration is saved in the scanner unit of the safety sensor.
  If, due to a device swap-out, the scanner unit is attached to a brand new, unconfigured connection unit, the safety configuration is transferred from the scanner unit to the connection unit.

	NOTICE
	Observe the safety notices regarding changes to the configuration! Transferring the safety configuration from the scanner unit to the connection unit corresponds to reconfiguration of the system consisting of scanner unit and connection unit. ↳ Observe the relevant safety notices regarding changes to the configuration (see chapter 9.1 "Defining safety configuration").

↳ Check the displayed signature.

↳ Confirm successful transfer of the safety configuration to the safety sensor with [OK].
The safety configuration has only been successfully transferred to the safety sensor when the confirmation dialog is displayed during the download.

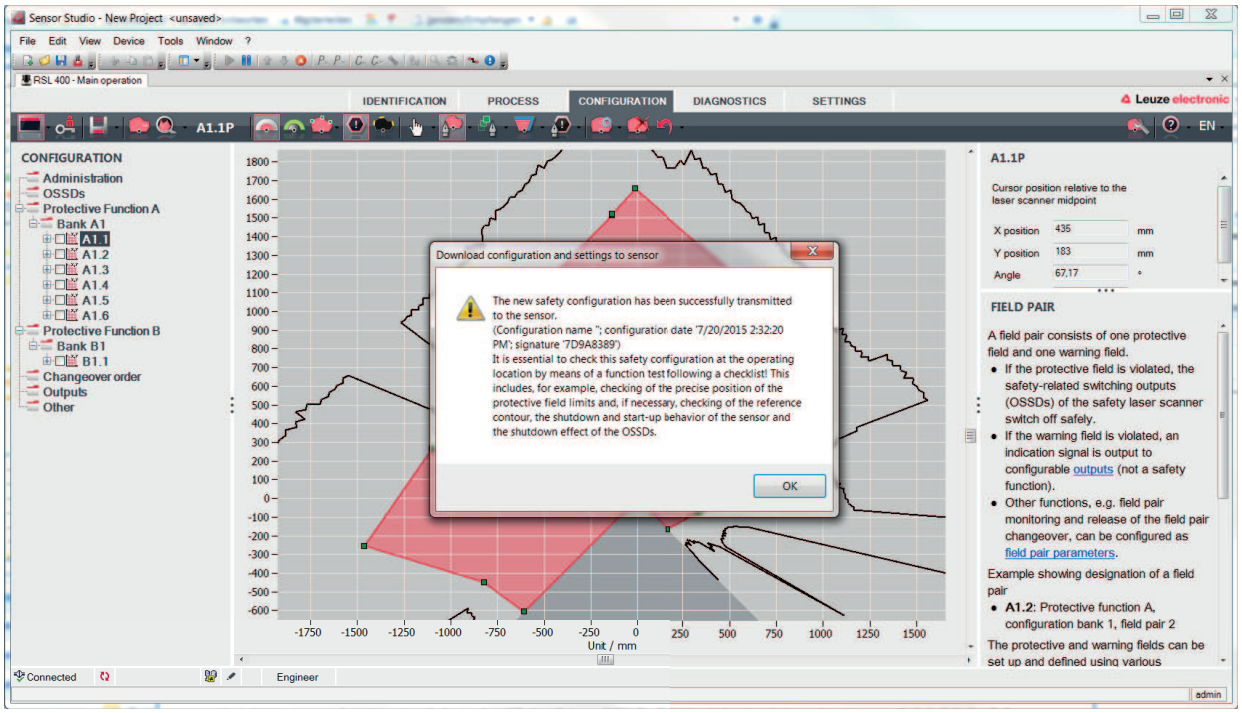


Fig. 9.4: Confirmation: safety configuration downloaded

NOTICE

The safety-related switching outputs will already have switched on if all conditions are fulfilled.

⇨ The software has saved the configuration project in the safety sensor.

9.9 Selecting access level

Using the device manager (DTM) you can change the access level of the user, if necessary (see chapter 5.1 "Authorization concept of safety sensor").

↳ Click in the DTM menu bar on the Change access level button ( ).

⇨ The **Change access level** dialog box opens.

↳ In the **Authorization** list, select the item *Engineer, Expert* or *Observer* and enter the default password or the password defined for the individual user (see chapter 4.5.6 "SETTINGS").

- Default password for *Engineer*: **safety**
- Default password for *Expert*: **comdiag**

↳ Confirm with [OK].

9.10 Reset safety configuration

The device manager (DTM) can be used to reset the safety configuration to the default configuration (one protective function, no restart).

↳ In the DTM menu bar, click the [Reset safety configuration] button.

⇨ Users with the access level *Engineer* can additionally transfer the changed safety configuration to the safety sensor (see chapter 9.8 "Transferring configuration project to safety sensor").

10 Starting up the device

WARNING

Improper use of the safety sensor may result in serious injury!

- Make certain that the entire device and the integration of the optoelectronic protective device was inspected by competent and instructed persons.
- Make certain that a dangerous process can only be started while the safety sensor is switched on

Prerequisites:

- Safety sensor mounted (see chapter 7 "Mounting") and connected (see chapter 8 "Electrical connection") correctly
- Operating personnel were instructed in proper use
- Dangerous process is switched off, outputs of the safety sensor are disconnected, and the system is protected against being switched back on

After start-up, check the function of the safety sensor (see chapter 11.1 "Before the initial start-up and following modifications").

10.1 Switching on

Requirements for the supply voltage (power supply unit):

- Safe mains separation is ensured.
- Current reserve of at least 3 A is available.

Switch on the safety sensor.

10.2 Aligning the safety sensor

NOTICE

Faulty or incorrect alignment may result in an operating fault!

- The alignment performed during start-up should only be performed by qualified personnel.
- Observe the data sheets and mounting instructions of the individual components.

To simplify alignment during start-up, the safety sensors of the RSL 400 series have an integrated electronic spirit level.

Align the safety sensor using the integrated electronic spirit level.

10.3 Unlocking start/restart interlock

WARNING

Premature unlocking of the start/restart interlock may result in serious injury!

If the start/restart interlock is unlocked, the system can start up automatically.

- Before unlocking the start/restart interlock, make certain that no people are in the danger zone.

The responsible person can restore the ON state of the safety sensor following process interruptions (due to triggering of protective function, failure of the voltage supply).

Unlock the start/restart interlock using the reset button.
The safety-related switching outputs are only enabled if you hold down the reset button for between 0.12 s and 4 s.

10.4 Shutting down

Temporarily shutting down the machine with the safety sensor

When you shut down the machine with the safety sensor temporarily, you do not have to observe any more steps. The safety sensor saves the configuration and starts again with the switch-on with this configuration.

Shutting down safety sensor and removing from machine

When you shut down the safety sensor and store it away for a later use, you must reset the safety sensor to the factory settings.

↳ Reset the safety sensor to the factory settings using the software.
In the device manager (DTM) of the safety sensor, select the *CONFIGURATION* tab.
Click the [Reset safety configuration] button.

10.5 Restarting

Restarting the machine with the safety sensor

If you have only shut down the system with the safety sensor temporarily and are restarting the system without any changes, you can restart the safety sensor with the configuration that applied with the shut-down. The configuration remains saved in the safety sensor.

↳ Perform a function test (see chapter 11.3 "Periodically by the operator").

Starting up machine with safety sensor after modification or reconfiguration

If you have performed significant changes on the machine or have reconfigured the safety sensor, the safety sensor must be checked as with the initial start-up.

↳ Test the safety sensor (see chapter 11.1 "Before the initial start-up and following modifications").

10.6 Starting up replacement scanner unit

The replacement scanner unit and the original scanner unit must be the same with regard to the following points:

- Scanner unit type in accordance with name plate or downward compatible with previous scanner unit with greater range and greater function range
- Mounting on the existing connection unit

Mounting and aligning replacement scanner unit

↳ Mount the replacement scanner unit on the connection unit instead of the original scanner unit (see chapter 13.1 "Changing scanner unit").

NOTICE

Realignment of safety sensor not necessary!

Realignment of the safety sensor is not necessary since the replacement scanner unit is mounted on the existing, aligned connection unit.

Transferring configuration to replacement scanner unit

The configuration stored in the connection unit is automatically transferred to the replacement scanner unit.

WARNING

Malfunctioning of safety sensor due to incorrect configuration!

↳ The safety sensor configuration stored in the connection unit can only be adopted without changes if the replacement scanner unit and the original scanner unit are downward compatible with respect to range and performance class.
The replacement scanner unit will reject an invalid configuration.

↳ Change the configuration parameters of the safety sensor using the configuration and diagnostic software according to the performance class of the replacement scanner unit.

↳ Change the configuration parameters of the safety sensor using the configuration and diagnostic software according to the operating range of the replacement scanner unit.

Transferring configuration with the PC

If the range and/or performance class of the replacement scanner unit is not compatible with the original scanner unit, you must adapt the configuration of the safety sensor to the replacement scanner unit.

- Connect the safety sensor's Ethernet communication interface with the PC.
- Configure the safety sensor according to the range and performance class of the replacement scanner unit (see chapter 9 "Configuring the safety sensor").
- Transfer the configuration to the safety sensor with the replacement scanner unit.
- ⇨ The alphanumerical display confirms successful transfer of the configuration.
  The replacement scanner unit is not compatible with the connection unit if the safety sensor displays a fault.

	NOTICE
	**Extension of boot time!** After installing large configurations, the boot time of the safety sensor can increase significantly.

Checking replacement scanner unit

The check performed on the replacement device depends on whether you automatically adopted the configuration from the connection unit or whether you transferred the changed configuration to the safety sensor.

- If you adopted the configuration from the connection unit, check the safety sensor using the checklist for the daily test.
- If you transferred a new configuration to the safety sensor, check the safety sensor according to the routine for initial start-up (see chapter 11.1.1 "Checklist for integrator – to be performed prior to the initial start-up and following modifications").

11 Testing

NOTICE

- Safety sensors must be replaced at the end of their mission time (see chapter 15 "Technical data").
- Always exchange entire safety sensors.
- For the tests, observe, if necessary, nationally applicable regulations.
- Document all tests in a comprehensible manner and include the configuration of the safety sensor along with the data for the safety- and minimum distances in the documentation.

11.1 Before the initial start-up and following modifications

WARNING

Unpredictable machine behavior during initial start-up may result in serious injury!

- Make certain that there are no people in the danger zone.

- Before they begin work, train the operators on their respective tasks. The training is the responsibility of the operating company.
- Attach notes regarding daily testing in the respective national language of the operator on the machine in a highly visible location, e.g. by printing out the corresponding chapter (see chapter 11.3 "Periodically by the operator").
- Test the electrical function and installation according to this document.

Acc. to IEC 62046 and national regulations (e.g. EU directive 2009/104/EC), tests are to be performed by competent persons in the following situations:

- Prior to initial commissioning
- Following modifications to the machine
- After longer machine downtime
- Following retrofitting or new configuration of the machine

- As preparation, check the most important criteria for the safety sensor according to the following checklist (see chapter 11.1.1 "Checklist for integrator – to be performed prior to the initial start-up and following modifications"). Completing the checklist does not replace testing by a competent person!

Not until proper function of the safety sensor is ascertained may it be integrated in the control circuit of the system.

11.1.1 Checklist for integrator – to be performed prior to the initial start-up and following modifications

NOTICE

Completing the checklist does not replace testing by a competent person!

- If you answer one of the items on the check list with *no*, the machine must no longer be operated (see table below).
- IEC 62046 contains additional recommendations on testing protective devices.

Tab. 11.1: Checklist for integrator – to be performed prior to the initial start-up and following modifications

Check:	Yes	No	n. a. not applicable
Is the safety sensor operated acc. to the specific environmental conditions that are to be maintained (see chapter 15 "Technical data")?			
Is the safety sensor correctly aligned and are all fastening screws and connectors secure?			
Are safety sensor, connection cables, connectors, protection caps and command devices undamaged and without any sign of manipulation?			
Does the safety sensor satisfy the required safety level (PL, SIL, category)?			
Are the safety-related switching outputs (OSSDs) integrated in the downstream machine control acc. to the required safety category?			
Are switching elements that are controlled by the safety sensor monitored according to the required safety level (PL, SIL, category) (e.g., contactors through EDM)?			
Are all points of operation near the safety sensor accessible only through the protective field of the safety sensor?			
Are the necessary additional protective devices in the immediate surroundings (e.g., safety guard) properly mounted and secured against tampering?			
If it is possible to be present undetected between the safety sensor and point of operation: is an assigned start/restart interlock functional?			
Is the command device for unlocking the start/restart interlock mounted in such a way that it cannot be reached from within the danger zone and so that the complete danger zone can be seen from the installation location?			
Has the maximum stopping time of the machine been measured and documented?			
Is the required safety distance maintained?			
Does interruption with a test object intended for this purpose cause the dangerous movement(s) to stop?			
Is the safety sensor effective during the entire dangerous movement(s)?			
Is the safety sensor effective in all relevant operating modes of the machine?			
Is start-up of dangerous movements reliably prevented if the protective field is interrupted with a test object intended for this purpose?			
Was the sensor detection capacity successfully tested (see chapter 11.3.1 "Checklist – periodically by the operator")?			
Were distances to reflective surfaces taken into account during configuration and no reflection bypasses subsequently detected?			
Are notices for regular testing of the safety sensor legible to the operator and are they located in a highly visible location?			
Are changes to the safety function (e.g. protective field changeover) not easy to achieve through tampering?			
Are settings that could result in an unsafe state possible only by means of key, password or tool?			
Are there incentives that pose stimulus for tampering?			
Were the operators instructed prior to starting work?			

11.2 To be performed periodically by competent persons

The reliable interaction of safety sensor and machine must be periodically tested by competent persons in order to detect changes to the machine or impermissible tampering with the safety sensor.

Acc. to IEC 62046 and national regulations (e.g., EU directive 2009/104/EC), tests of elements which are subject to wear must be performed by competent persons at regular intervals. Testing intervals may be regulated by nationally applicable regulations (recommendation acc. to IEC 62046: 6 months).

- Have all tests performed by competent persons.
- Observe the nationally applicable regulations and the time periods specified therein.
- As preparation, observe the checklist (see chapter 11.1 "Before the initial start-up and following modifications").

11.3 Periodically by the operator

The function of the safety sensor must be checked regularly (e.g., daily, on shift change, monthly or in an even longer cycle) according to the following checklist. The frequency of the checks is determined by means of the risk analysis performed by the operating company.

Due to complex machines and processes, it may be necessary under certain circumstances to check some points at longer time intervals. Observe the classification in "Test at least" and "Test when possible".

WARNING

Unpredictable machine behavior during the test may result in serious injury!

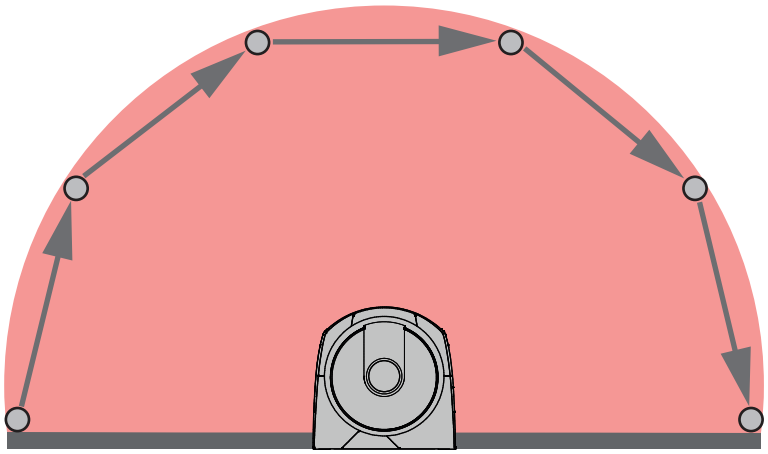
- Make certain that there are no people in the danger zone.
- Before they begin work, train the operators on their respective tasks and provide suitable test objects and an appropriate test instruction.

11.3.1 Checklist – periodically by the operator

NOTICE

- If you answer one of the items on the check list with *no*, the machine must no longer be operated (see chapter 11.1.1 "Checklist for integrator – to be performed prior to the initial start-up and following modifications").

Tab. 11.2: Checklist – regular function test by trained operators/persons

Test at least:	Yes	No
Are safety sensor and connectors securely mounted and free of obvious signs of damage, changes or tampering?		
Were obvious changes made to access or entry possibilities?		
Test the effectiveness of the safety sensor: 1. The LED 1 on the safety sensor must illuminate green (see chapter 3.4 "Display elements"). 2. Interrupt the protective field using a suitable opaque test object (see figure).  Checking the protective field function with test rod. Use a sample item with the set resolution as the test rod. The sample item should have a matt surface structure. Does the LED 1 on the safety sensor illuminate constantly red while the protective field is interrupted?		

Tab. 11.3: Checklist – regular function test by trained operators/persons

When possible, test during running operation:	Yes	No
Protective device with approach function: during machine operation, the protective field is interrupted with the test object – are the obviously dangerous machine parts stopped without noticeable delay?		
Protective device with presence detection: the protective field is interrupted with the test object – does this prevent operation of the obviously dangerous machine parts?		

12 Diagnosis and troubleshooting

12.1 What to do in case of failure?

After switching the safety sensor on, the display elements assist in checking the correct functionality and in faultfinding (see chapter 3.4 "Display elements").

In case of failure, you can determine the fault from the LED displays and read a message from the display. With the error message you can determine the cause of the error and initiate measures to rectify it.

	NOTICE
	**If the safety sensor responds with an error display, you will often be able to eliminate the cause yourself!** ↳ Switch off the machine and leave it switched off. ↳ Analyze the cause of the fault using the diagnostics displays and rectify the fault. ↳ If you are unable to rectify the fault, contact the Leuze branch responsible for you or call the Leuze customer service (see chapter 14 "Service and support").

12.2 Diagnostics displays

The diagnostics displays consist of one letter plus four numbers, divided into classes consisting of letters and the first number.

Diagnostics classes:

- I (Information)
  - No OSSD switch-off
  - Unhindered operation possible
- U (Usage)
  Application error
- E (External)
  External fault
- F (Failure)
  internal device error
  - OSSD switch-off
  - Self test unsuccessful
  - Hardware error
- P (Parameter)
  Inconsistency in configuration

Tab. 12.1: Diagnostics displays in order of ascending ID number

Diagnostic ID	Diagnostic message	Measure
U0370	Input level at the electrical inputs is unclear.	Check the wiring of the safety sensor.
P0409	Safety configuration is not compatible: unknown bank switchover.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0410	Safety configuration is not compatible: unknown output signals.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0413	Safety configuration is not compatible: unknown inputs SE1 and SE2.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.

Diagnostic ID	Diagnostic message	Measure
P0414	Safety configuration is not compatible: unknown EDM inputs.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0415	Safety configuration is not compatible: unknown field pair monitoring mode.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0416	Safety configuration is not compatible: unknown field pair monitoring parameters.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0417	Safety configuration is not compatible: unknown field pair monitoring mode.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0419	Safety configuration is not compatible: unknown monitoring parameter for the changeover order.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0420	Safety configuration is not compatible: unknown monitoring mode of the field pair changeover.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0421	Safety configuration is not compatible: unknown parameter for field pair changeover monitoring.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0422	Safety configuration is not compatible: unknown field pair selection mode.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0423	Safety configuration is not compatible: unknown field pair selection parameter.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0424	Safety configuration is not compatible: unknown parameter for manipulation monitoring.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0425	Safety configuration is not compatible: unknown configuration of the output signals.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0426	Safety configuration is not compatible: unknown resolution.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0427	Safety configuration is not compatible: unknown parameter.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.

Diagnostic ID	Diagnostic message	Measure
P0429	Safety configuration is not compatible: unknown start/restart mode.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0430	Safety configuration is not compatible: unknown start mode.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0431	Safety configuration is not compatible: unknown restart mode.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0432	Safety configuration is not compatible: unknown OSSD stop mode.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
U0573	EDM fault at system start.	Check the wiring of the downstream relays and that they are functioning correctly.
U0574	Switching fault, EDM at OSSD A: external relay does not switch off.	Check the wiring of the downstream relays and that they are functioning correctly.
U0575	Switching fault, EDM at OSSD A: external relay does not switch on.	Check the wiring of the downstream relays and that they are functioning correctly.
U0576	Switching fault, EDM at OSSD B: external relay does not switch off.	Check the wiring of the downstream relays and that they are functioning correctly.
U0577	Switching fault, EDM at OSSD B: external relay does not switch on.	Check the wiring of the downstream relays and that they are functioning correctly.
U0580	Switching fault at inputs SE1 and SE2; external safety device does not switch in accordance with the specifications.	Check the wiring of the external safety device and that the parameter settings in the configuration are correct.
U0582	Field pair changeover is not performed in accordance with the specifications configured in the safety sensor: overlap time too long.	Check the changeover times of function inputs F1 to F10 or the parameter settings in the configuration.
U0583	Field pair changeover is not performed in accordance with the specifications configured in the safety sensor: no signal for field pair activation.	Check the wiring and the changeover times of function inputs F1 to F10.
U0584	Field pair changeover is not performed in accordance with the specifications configured in the safety sensor: changeover time exceeded.	Check the changeover times of function inputs F1 to F10 or the parameter settings in the configuration.
U0585	Field pair changeover is not performed in accordance with the specifications configured in the safety sensor: changeover order not observed.	Check the wiring of function inputs F1 to F10 and that the parameter settings in the configuration are correct.
U0792	Field pair changeover without release.	Check the release signal for field pair changeover or change the safety configuration.
U0793	Field pair changeover without request.	Check the request signal for field pair changeover or change the safety configuration.
U0849	Field pair changeover not permitted.	Check the wiring of the field pair inputs.

Diagnostic ID	Diagnostic message	Measure
E0588	Optics cover is soiled.	Clean the optics cover.
I0604	Optics cover is soiled.	Clean the optics cover as soon as possible. Sensor is still in safety mode.
P0653	Safety configuration is not compatible: protective/warning field radius too large.	Swap out the safety sensor or change the configuration. The type of safety sensor must be the same as the type stored in the connection unit or in the *Sensor Studio* software.
P0654	Field pair changeover is not performed in accordance with the specifications configured in the safety sensor: field pair not defined.	Check the wiring of function inputs F1 to F10 and that the parameter settings in the configuration are correct.
I0660	Field pair changeover is not performed in accordance with the specifications configured in the safety sensor: no field pair activated at system start.	Check the wiring of function inputs F1 to F10 and that the parameter settings in the configuration are correct.
U0661	Safety-related switching outputs (OSSDs) cannot be switched: short circuit with 0 V, +24 V DC or between OSSDs.	Check the wiring of the OSSDs.
I0719	Timeout of signals RES1 or RES2 (acknowledgment button, start/restart).	Check the wiring of inputs RES1 and RES2. The time specifications for start/restart must be observed.
P0747	Safety configuration is not compatible: protective/warning field radius too small.	Change the dimensions and contour of the protective field in the configuration. The minimum range of the protective field must be observed.
I0825	Simulation mode has been activated.	The safety-related switching outputs (OSSDs) have been switched off.
I0826	Simulation mode has been deactivated.	Safety sensor is again in safety mode. **CAUTION!** Be aware of potential hazards which can occur when the machine is started up!
I0859	Configuration was reset.	+24 V detected at RES input after switch-on. The communication parameters were reset to default values.
I1004	Field violation due to glare. (With switch-off of the OSSDs)	Mount the safety sensor so that the light source does not hit the outlet disc directly.
I1005	Dazzled RSL. (Without switch-off of the OSSDs)	Mount the safety sensor so that the light source does not hit the outlet disc directly.
F....	The monitoring functions have detected an internal error.	Create the service file (see chapter 4.5.5 "DIAGNOSIS") and contact the Leuze customer service (see chapter 14 "Service and support").

13 Care, maintenance and disposal

13.1 Changing scanner unit

If the safety sensor check or an error message indicates a defective scanner unit, change the scanner unit.

Only a trained and competent person is permitted to change the scanner unit.

The scanner unit is changed as follows:

- Detach the scanner unit from the connection unit.
- Attach the replacement scanner unit to the connection unit.

NOTICE

Safety sensor malfunction caused by dirt!

- Perform all work in an environment which is as dust-free and dirt-free as possible.
- Do not touch any of the parts inside the device.

WARNING

Malfunctioning of safety sensor due to incompatibility of connection unit and scanner unit! Malfunctioning of safety sensor due to incorrect configuration!

- Wherever possible, replace the scanner unit with a scanner unit with the same range and performance class (e.g. RSL 420-M with RSL 420-M). The safety sensor configuration stored in the connection unit is only adopted without changes if the new scanner unit supports all configured functions.
- Change the configuration parameters of the safety sensor using the configuration and diagnostic software according to the performance class of the scanner unit or of the connection unit.
  If a scanner unit is attached to a connection unit with a lower performance class (e.g. scanner unit RSL 430 to connection unit CU416), the integrated cable management of the connection unit means that only the functions of the lower performance class (of the connection unit) are available.
  If a scanner unit is attached to a connection unit with a higher performance class (e.g. RSL 420 scanner unit to CU429 connection unit), the performance of the scanner unit restricts the functions to those of the lower performance class (of the scanner unit).
- Change the configuration parameters of the safety sensor using the configuration and diagnostic software according to the operating range of the replaced scanner unit. If the scanner unit is replaced with a scanner unit with a different range (e.g. RSL 420-L with RSL 420-M), you must check and, if necessary, adapt the configuration of the safety sensor.

NOTICE

Detailed information on attaching the scanner unit can be found in the document "Quick Start Guide RSL 400".

- Undo the quick-release fasteners on both sides of the scanner unit.
- Pull the scanner unit off the connection unit.
- Place the new scanner unit on the connection unit.
- Connect and lock the new scanner unit using the quick-release fasteners on both sides.
- Check the configuration of the safety sensor (see chapter 9 "Configuring the safety sensor").

NOTICE

If a preconfigured scanner unit is attached to a brand new, unconfigured connection unit, the safety configuration stored in the scanner unit is transferred to the connection unit and you can use the safety sensor without reconfiguration after a restart.

- Check the safety sensor according to the routine for initial start-up (see chapter 11.1.1 "Checklist for integrator – to be performed prior to the initial start-up and following modifications").

13.2 Cleaning the optics cover

Clean the optics cover as required by the application-related load rating.

Use the cleaning set consisting of special cleaning agent and cleaning cloths for cleaning (see chapter 17 "Order guide and accessories").

The procedure for cleaning depends on the kind of contamination:

Soiling	Cleaning
Particles, loose, scouring	Vacuum without touching or blow away softly, oil-free Wipe free in one swipe with cleaning cloth
Particles, loose, non-scouring	Vacuum without touching or blow away softly, oil-free or Wipe free in one swipe with cleaning cloth
Particles, sticking	Wet with cloth soaked in cleaning agent Wipe free in one swipe with cleaning cloth
Particles, statically charged	Vacuum without touching Wipe free in one swipe with cleaning cloth soaked with cleaning agent
Particles/drops, smearing	Wet with cloth soaked in cleaning agent Wipe free in one swipe with cleaning cloth
Water drops	Wipe free in one swipe with cleaning cloth
Oil drops	Wet with cloth soaked in cleaning agent Wipe free in one swipe with cleaning cloth
Fingerprints	Wet with cloth soaked in cleaning agent Wipe free in one swipe with cleaning cloth
Scratches	Change optics cover

NOTICE

The wrong cleaning agents or cloths will damage the optics cover!

↳ Do not use any scouring cleaning agents or scratching cloths.

NOTICE

If cleaning takes longer than four seconds, e.g. with fingerprints, the safety sensor displays a fault of optics cover monitoring. After cleaning is complete, the safety sensor resets itself automatically.

↳ Clean the optics cover over the entire 360° range.

↳ Soak cloth with cleaning agent.

↳ Wipe optics cover free in one swipe.

↳ Clean not only the optics cover, but also the reflector ring under the cap.



1 Reflector ring

Fig. 13.1: Reflector ring

	NOTICE
	Internal monitoring of optics cover! ↳ The monitored area is dependent on the configuration and can be smaller than the entire scanning range of 270°. ↳ On account of device safety, the internal monitoring of the optics cover monitors a range that is larger than specified by the configured protective field.

13.3 Servicing

The device does not normally require any maintenance by the operator.

Repairs to the device must only be performed by the manufacturer.

↳ For repairs, contact your responsible Leuze subsidiary or Leuze customer service (see chapter 14 "Service and support").

13.4 Disposing

↳ For disposal observe the applicable national regulations regarding electronic components.

14 Service and support

24-hour on-call service at:
+49 7021 573-0

Service hotline:
+49 7021 573-123

E-mail:
service.protect@leuze.de

Return address for repairs:
Servicecenter
Leuze electronic GmbH + Co. KG
In der Braike 1
D-73277 Owen/Germany

15 Technical data

15.1 General specifications

Tab. 15.1: Safety-relevant technical data

Type in accordance with IEC 61496	Type 3
SIL in accordance with IEC 61508	SIL 2
SILCL in accordance with IEC 62061	SILCL 2
Performance Level (PL) in accordance with ISO 13849-1	PL d
Category in accordance with ISO 13849-1	Cat. 3
Average probability of a failure to danger per hour (PFH_d)	$9x10^{-8}$ 1/h
Mission time (T_M)	20 years

Tab. 15.2: Optics

Laser protection class in accordance with EN 60825-1	Class 1
Wavelength	905 nm (infrared)
Impulse duration	2.5 ns
Maximum output power (peak)	35 W
Pulse frequency of laser transmitter	90 kHz
Scanning rate	25 scans/s, equal to 40 ms/scan
Scanning angle	Max. 270 °
Angular resolution	0.1 °
Tolerance field of reference contour	+ 200 mm

Tab. 15.3: Protective field data

Safety sensor	RSL 410	RSL 420 RSL 425	RSL 430	RSL 440 RSL 445
Number of field pairs	1	10	10 + 10	100
Reference contour selectable	x	x	x	x
Minimum adjustable range	50 mm			
Detection range of the test object from the housing edge	The detection capability is limited in the 0 mm to 50 mm range to increase availability.			
Diffuse reflectance PF minimum	1.8 %			

Tab. 15.4: Protective field range

Device range	**S**	**M**	**L**	**XL**
Resolution [mm]	**Protective field range [m]**			
150	3.00	4.50	6.25	8.25
70	3.00	4.50	6.25	8.25
60	3.00	4.50	6.25	8.25
50	3.00	4.50	6.25	6.25
40	3.00	4.50	4.50	4.50
30	3.00	3.50	3.50	3.50

Tab. 15.5: Warning field data

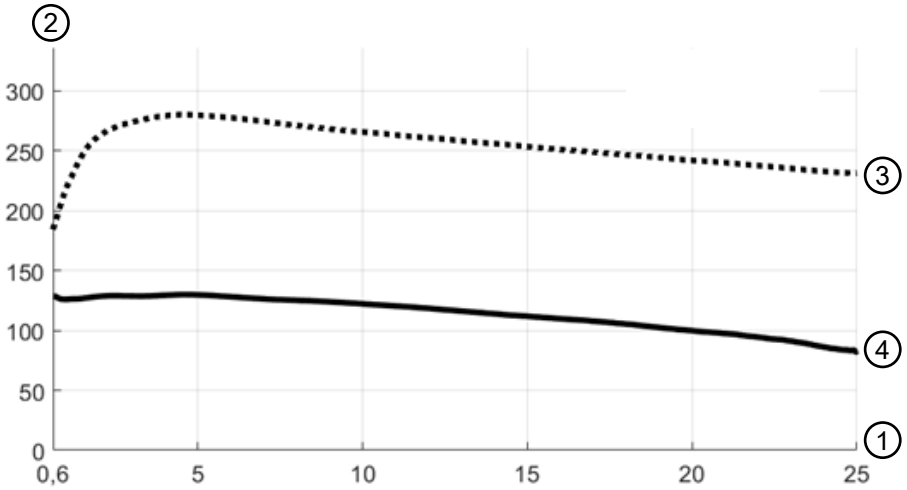
Safety sensor	RSL 410	RSL 420 RSL 425	RSL 430	RSL 440 RSL 445
Number of field pairs	1	10	10 + 10	100
Warning field range	0 … 20 m			
Object size	150 mm x 150 mm			
Diffuse reflectance WF minimum	Min. 10%			

Tab. 15.6: Measurement field data

Detection range	0 … 50 m
Diffuse reflection	90 %
Radial resolution	1 mm
Lateral resolution	0.1 °

Tab. 15.7: Measurement field data for RSL 425

		Min.	Typical	Max.
Detection range	Diffuse reflection > 90%		0 … 50 m	
Distance resolution, radial			1 mm	
Distance resolution, lateral			0.1 °	
Systematic measurement error D_{meas} - D_{real}	Diffuse reflection: 1.8% … retro-reflector Measurement range: 0.2 m … 25 m	 -20 mm	 -10 mm	 +0 mm
Measurement value noise	1 σ • Diffuse reflection: 1.8% … 20% Measurement range: 0 m … 9 m • Diffuse reflection: 20% … retro-reflector Measurement range: 0 m … 25 m		10 mm	
Laser spot height	10 m 20 m 30 m 40 m		60 mm 165 mm 265 mm 285 mm	
Laser spot width	10 m 20 m 30 m 40 m		13 mm 24 mm 40 mm 57 mm	



1 Object distance [m]
2 Signal strength
3 Retro-reflector film
4 White surface

Fig. 15.1: Signal strength curves depending on the distance

The figure shows a typical curve of the signal strength transmitted by the safety sensor as a function of the measured object distance and object diffuse reflection for the following boundary conditions:

- Angle of incidence of the laser beam: 0°
- Share of area of the light spot on the object: 100%

Tab. 15.8: Electrical supply

RSL 420 voltage supply	24 V DC (+20% / -30%)
Power supply unit/battery	Supply acc. to IEC 742 with safe mains separation and equalization for power outages of up to 20 ms acc. to IEC 61496-1.
Current consumption	Approx. 700 mA (use power supply unit with 3 A)
Power consumption	17 W with 24 V plus output capability
Switch-on current	Max. 2 A
Overvoltage protection	overvoltage protection with protected limit stop
Protective conductor	Connection required
Device connection	Connection cable, 16-wire
Connection socket for Ethernet/communication	M12-4 connector, D-coded

Tab. 15.9: Inputs

Reset	+24 V, dynamically monitored (0.12 s to 4 s)
Field pair changeover	Selection of 10 field pairs via 5 control cables +24 V, dynamically monitored
Signal definition:	
High/logical 1	16 - 30 V
Low/logical 0	< 3 V

Tab. 15.10: Safety-related switching outputs

OSSD transistor safety-related switching outputs	2 safe PNP semiconductor outputs Short-circuit proof, cross circuit monitored		
	Minimum	Typical	Maximum
Response time	80 ms (2 scans)		1000 ms (25 scans)
Switching voltage high active	U_B – 3.2 V		
Switching voltage low			2.0 V
Switching current			300 mA
Cut-off frequency f_g			1 kHz
Load capacity C_{load}			100 nF
Cable length between safety sensor and load	see chapter 8.3 "Connection unit CU416"		
Cable resistance			15 Ω
Test pulse width	60 µs		110 µs
Test pulse distance	35 ms	40 ms	40 ms

NOTICE

The safety-related transistor outputs perform the spark extinction. With transistor outputs, it is therefore neither necessary nor permitted to use the spark extinction circuits recommended by contactor or valve manufacturers (RC elements, varistors or recovery diodes), since these considerably extend the decay times of inductive switching elements.

Tab. 15.11: Inputs and outputs

Properties	Max. output current I_a	Min. input current I_e	Typical connection components
E=Input (F1-F5) PNP/NPN, can be changed over together	---	4 mA (-4 mA)	Switching contacts control/sensor output
E=Input (RES1) PNP/NPN changeover together with F1-F5	---	10 mA (-10 mA)	Start/restart
E=Input (SE1/SE2) changeover	---	4 mA (< 1 mA=OFF)	E-Stop input OSSD linkage
EX/A = changeover-capable (EA1)	20 mA (-20 mA)	10 mA (-10 mA)	Auxiliary contact of power contactor (EDM)
AX=output Current-limited, short-circuit proof (A1, MELD)	100 mA (-20 mA)	---	Lamp (PNP only) Control input (PNP/NPN)
Signal definition:			
High/logical 1	16 - 30 V		
Low/logical 0	< 3 V		

Tab. 15.12: USB

Type of interface	USB 2.0
Connection type	USB 2.0 mini-B socket
Transmission rate	≤ 12 Mbit/s
Cable length	≤ 5 m Longer cable lengths are possible using active cables.

Tab. 15.13: Bluetooth

Frequency band	2400 ... 2483.5 MHz
Radiated transmitting power	Max. 4.5 dBm (2.82 mW), class 2

Tab. 15.14: Software

Configuration and diagnostics software	Sensor Studio for Windows 7 or higher

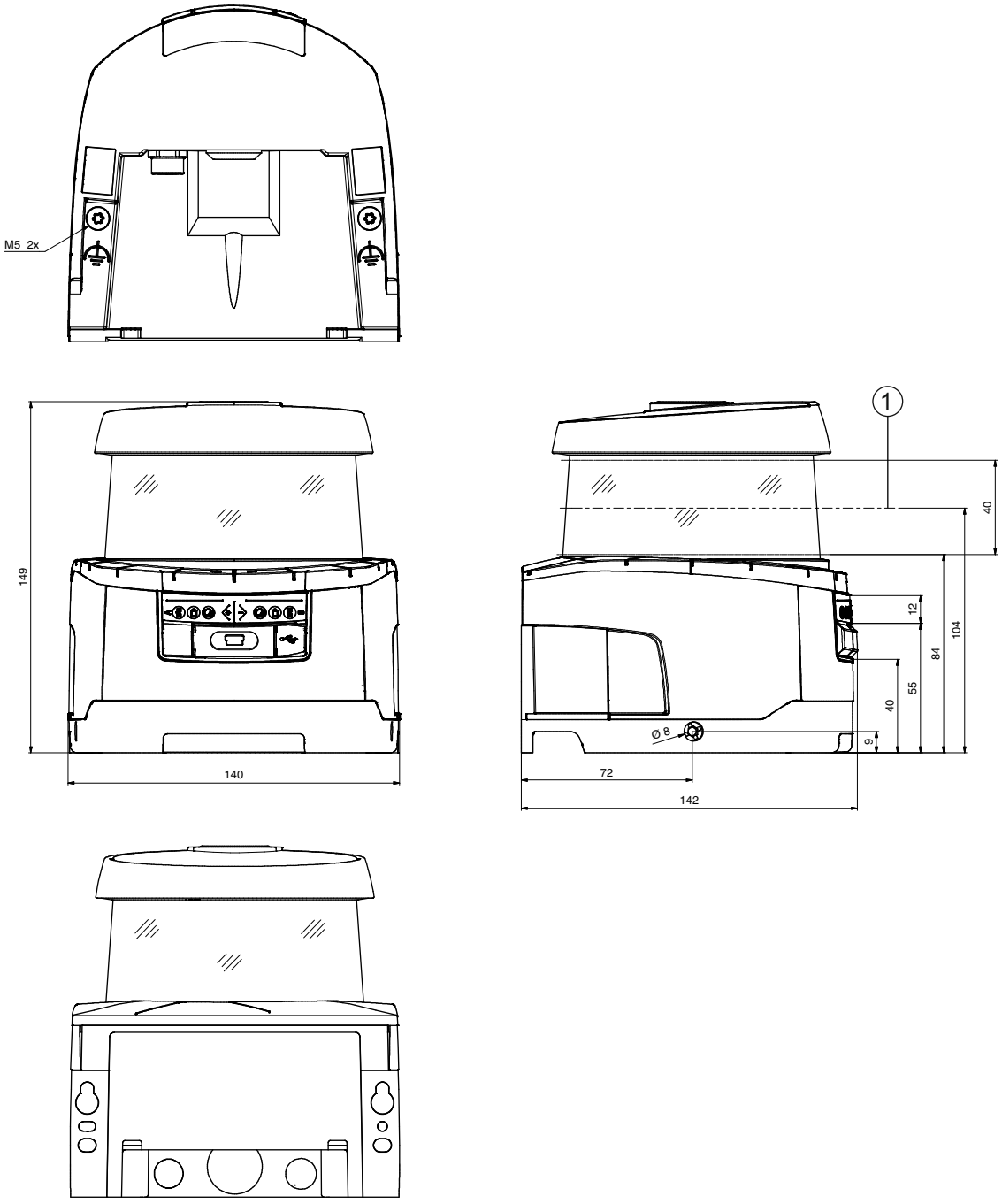
Tab. 15.15: General system data

Degree of protection	IP 65 in acc. with IEC 60529
Protection class	III in accordance with EN 61140
Ambient temperature, operation	0 … +50 °C
Ambient temperature, storage	-20 … +60 °C
Humidity	DIN 40040, table 10, code letter E (reasonably dry)
Interference rejection	In acc. with IEC 61496-1 (type 4), also in acc. with DIN 40839-1/3 test pulses 1, 2, 3a, 3b and 5
Vibration stress over 3 axes	In acc. with IEC 60068 part 2 - 6, 10 - 55 Hz max 5 G
Continuous shock over 3 axes	In acc. with IEC 60068 part 2 - 29, 10 G, 16 ms
Disposal	Specialist disposal required
Housing	Diecast zinc, plastic
Standard version dimensions (ensure free space for connector with fixing and connection cable)	140 x 149 x 140 (W x H x D) in mm
Weight of standard version incl. connection unit	Approx. 3 kg
Distance, beam level center to bottom housing edge	104 mm

Tab. 15.16: Patents

US patents	US 7,656,917 B US 7,696,468 B US 8,520,221 B US 2016/0086469 A

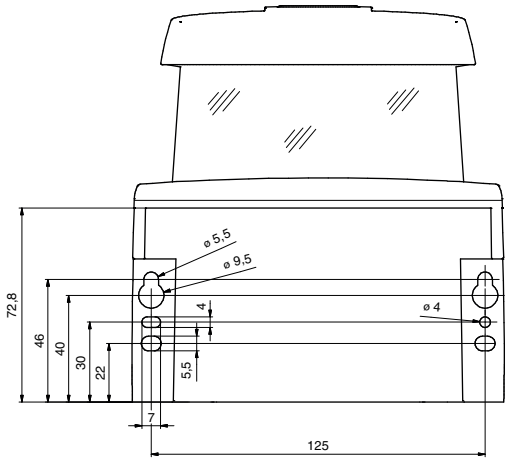
15.2 Dimensions



all dimensions in mm

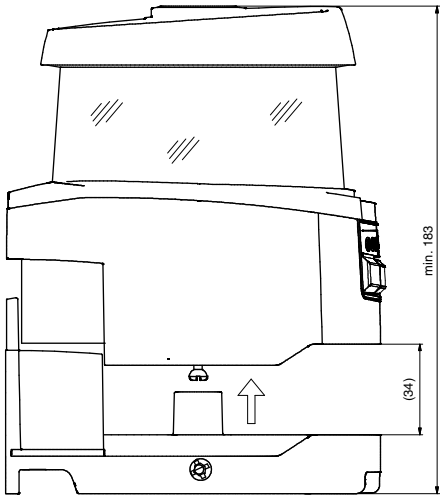
1 Scan level

Fig. 15.2: Dimensions safety laser scanner with connection unit



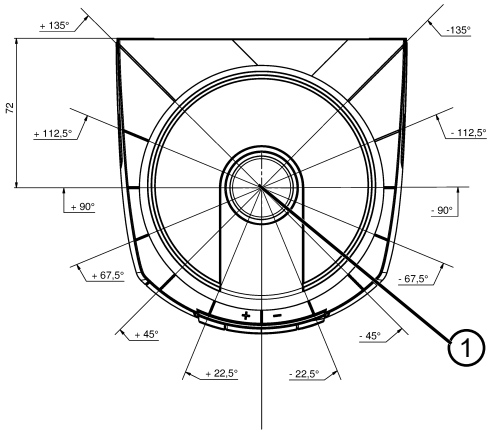
all dimensions in mm

Fig. 15.3: Mounting dimensions safety laser scanner with connection unit



all dimensions in mm

Fig. 15.4: Minimum space requirements for installation and replacement of scanner unit

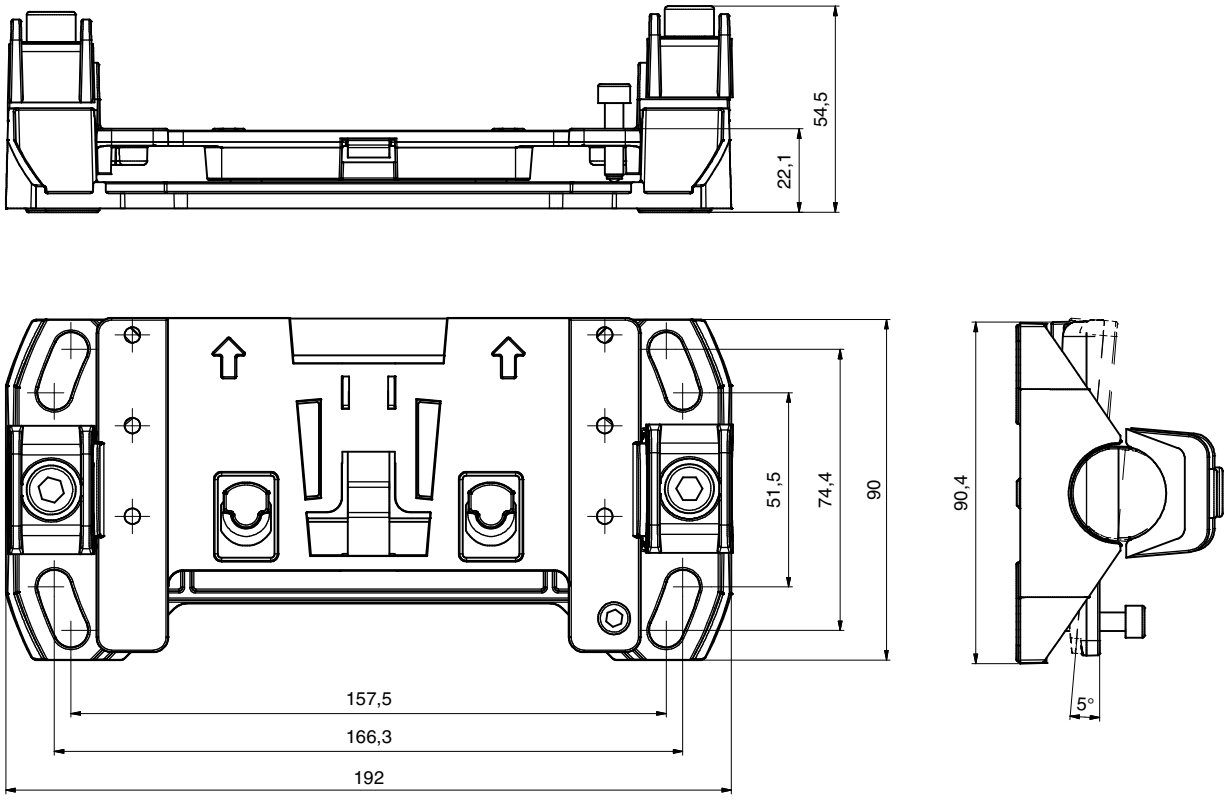


all dimensions in mm

1 Reference point for distance measurement and protective field radius

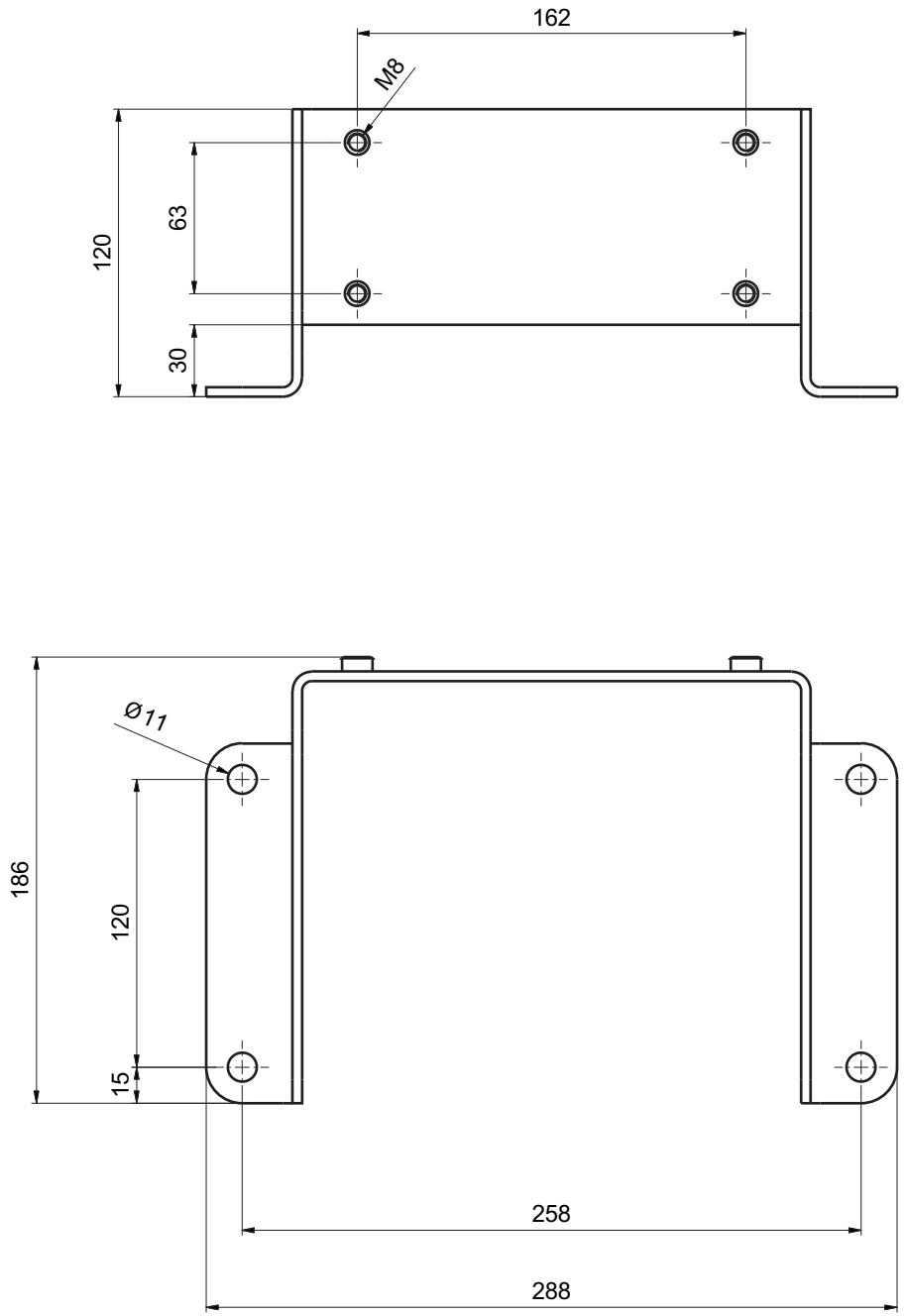
Fig. 15.5: Dimensions of scanning range

15.3 Dimensioned drawings: Accessories



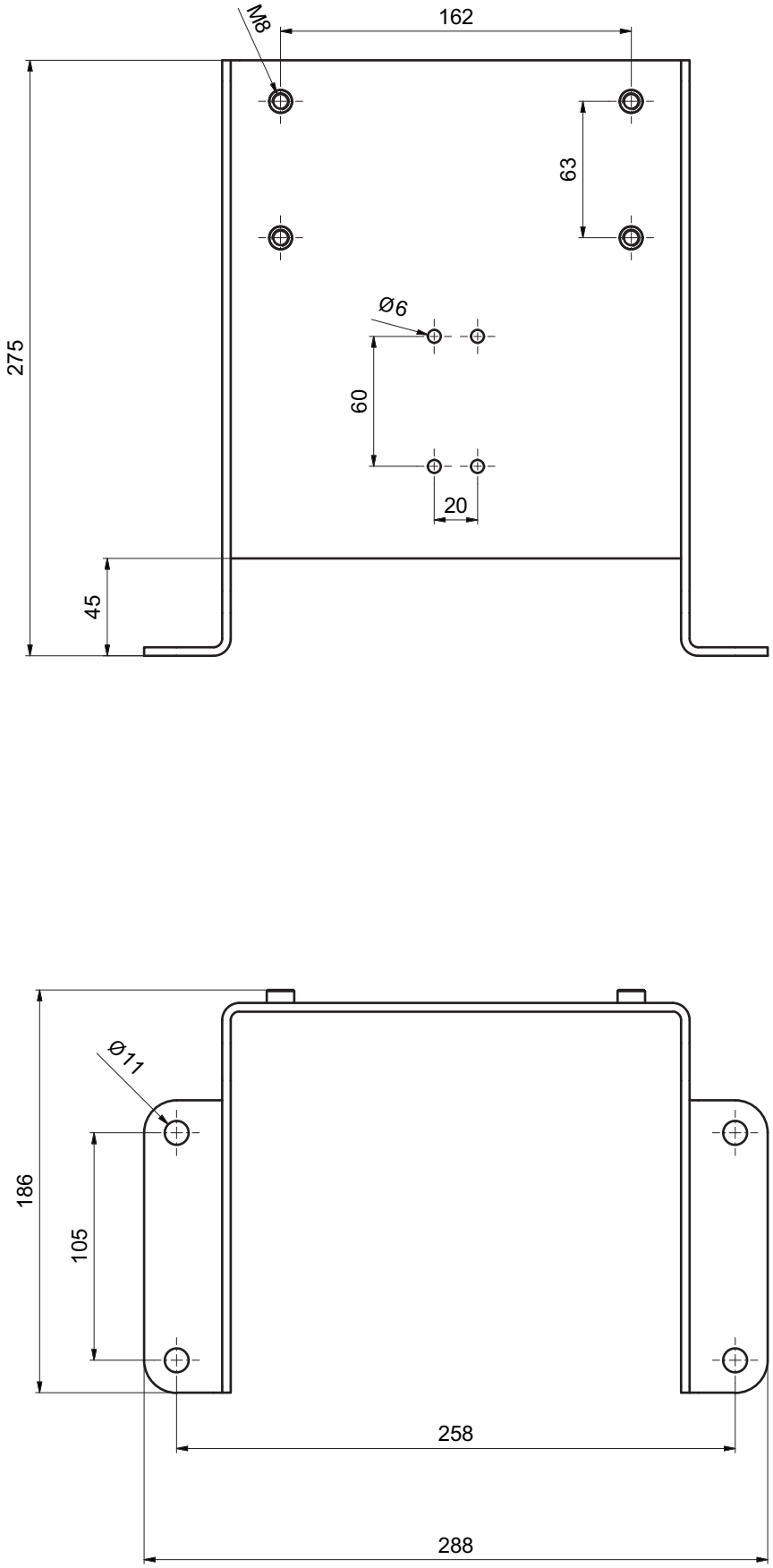
all dimensions in mm

Fig. 15.6: BTU800M mounting system



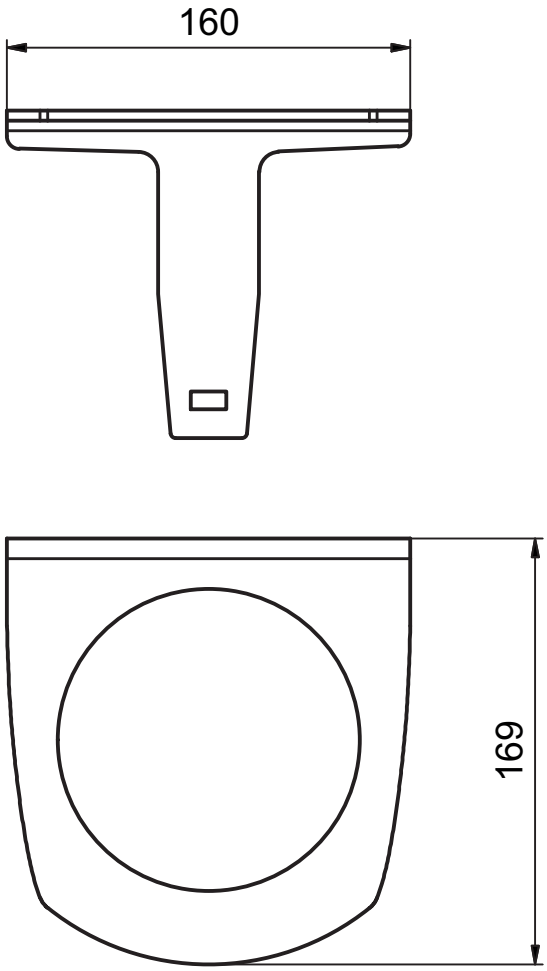
all dimensions in mm

Fig. 15.7: BTF815M mounting bracket



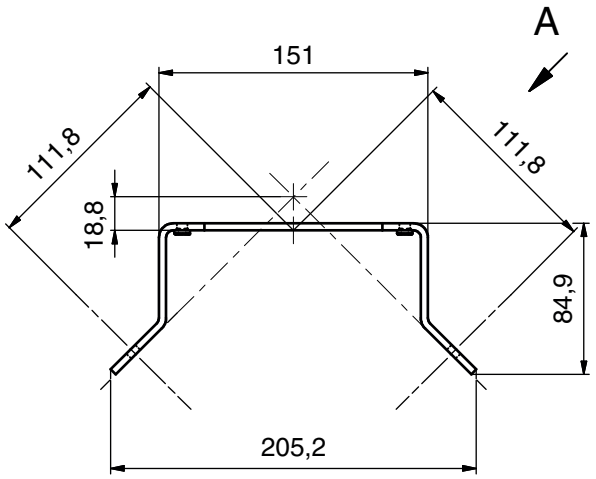
all dimensions in mm

Fig. 15.8: BTF830M mounting bracket



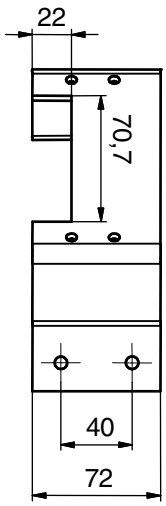
all dimensions in mm

Fig. 15.9: Loop guard BTP800M



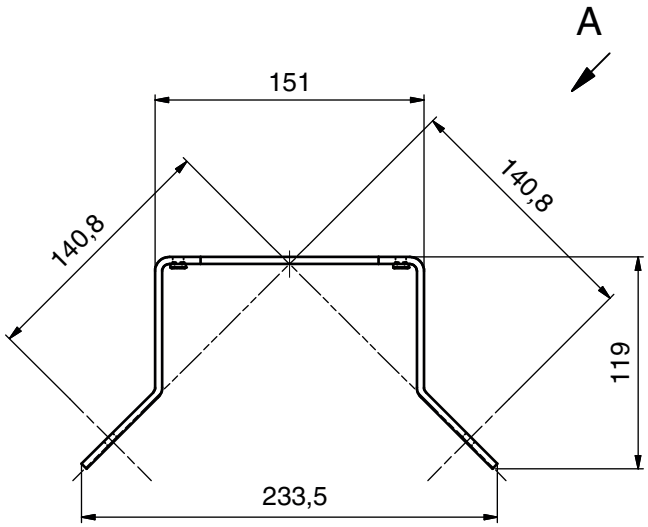
all dimensions in mm

Fig. 15.10: BT840M mounting bracket



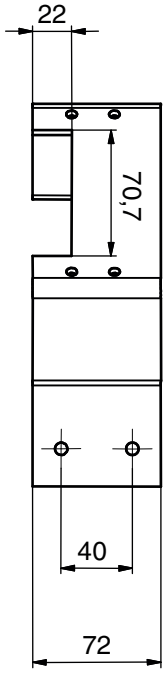
all dimensions in mm

Fig. 15.11: Mounting bracket BT840M, view A



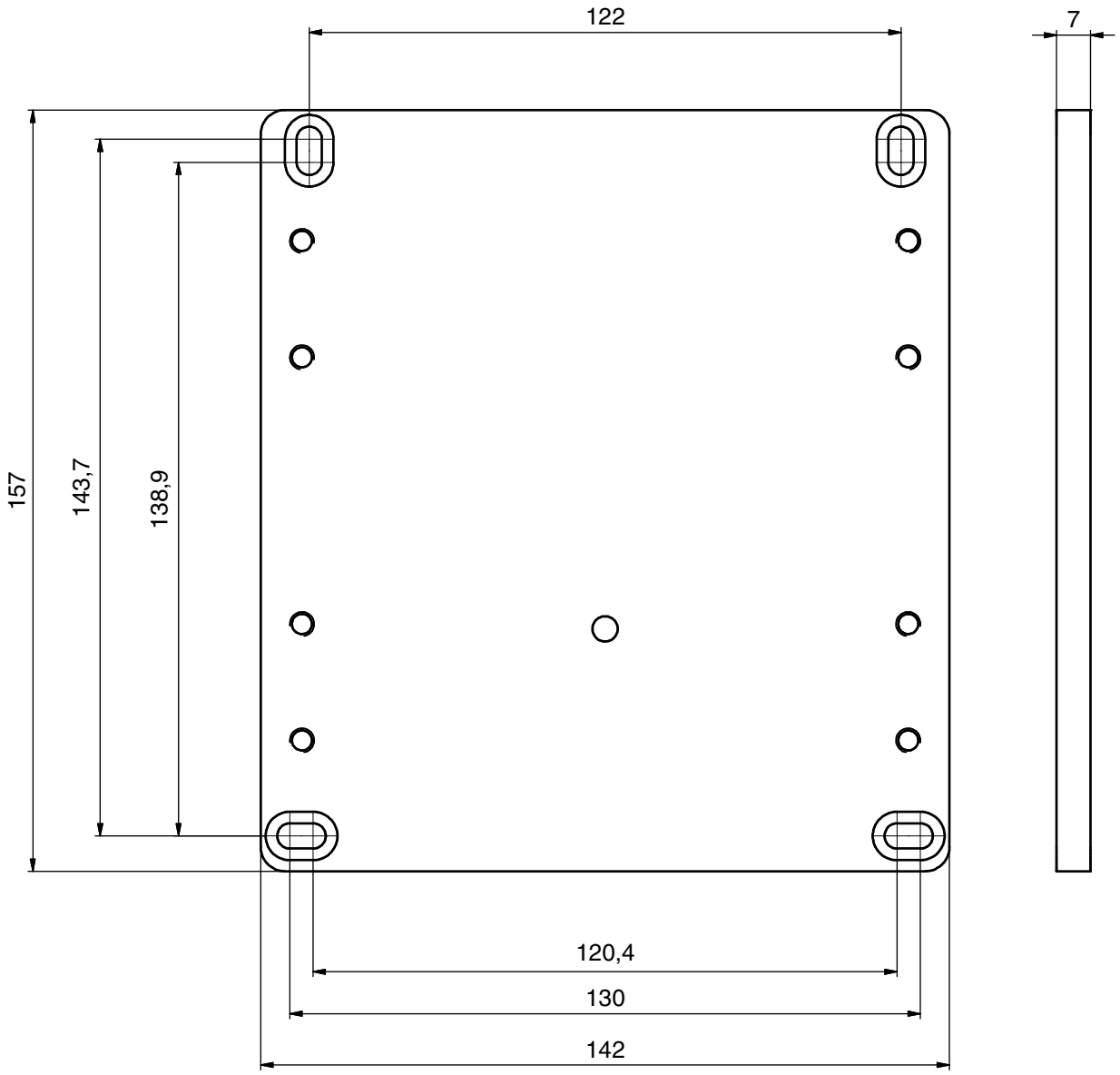
all dimensions in mm

Fig. 15.12: BT856M mounting bracket



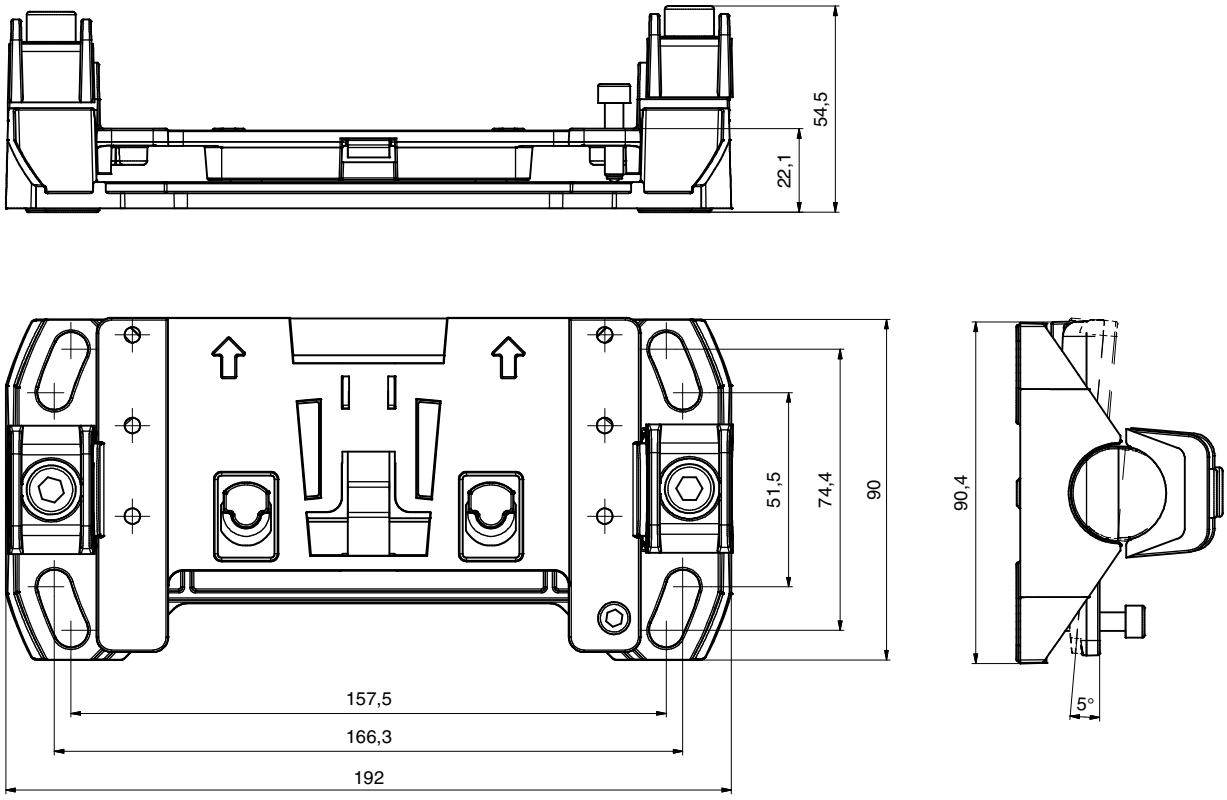
all dimensions in mm

Fig. 15.13: Mounting bracket BT856M, view A



all dimensions in mm

Fig. 15.14: Drilling template for adapter plate, RS4/ROD4 BT800MA



all dimensions in mm

The mounting plate BTU804MA supplements the old mounting system of the RS4/ROD4 for the mounting system BTU800M.

Fig. 15.15: BTU804MA mounting plate

15.4 Representation of safety sensor status

The table lists all logic and electrical signals that are present in the safety sensor. The signal names are used consistently throughout the configuration and diagnostics software (device DTM), in the event log and in the data telegram.

Tab. 15.17: Status profile

Byte	Bit	Signal	Description	Value "0"	Value "1"	Default
0	---	---	Type (model) of status profile. Extensions require new type of status profile	---	---	1
1	---	OP-MODE	Operating mode: • 1: Safety mode • 2: Simulation mode	---	---	1
Messages and OSSDs						
2	7	ERROR	Collective message: Error with switch-off	off	message	0
	6	ALARM	Collective message: Warnings with switch-off (also window warning)	off	message	0
	5	SCREEN	Contamination display for optics cover Warning and switch-off	off	message	0
	4	EDM	EDM collection error	off	message	---
	3	FIELD PAIR	Collective message: Fault detected by field pair selection monitoring	off	message	---
	2	E-STOP	Error with OSSD linkage / E-Stop monitoring	off	message	---
	1	A-OSSD	OSSD state Protective function A	off	on	0
	0	B-OSSD	OSSD state Protective function B	off	on	0
Emergency stop and parking						
3	7	Status-Input-SE	Status of the inputs SE1 and SE2 E-STOP	off	on	0
	6	Mode-PARK	Park request fulfilled	off	parked	0
	5	Reserved	---	---	---	0
	4	Reserved	---	---	---	---
	3	Reserved	---	---	---	---
	2	Reserved	---	---	---	---
	1	Reserved	---	---	---	---
	0	Reserved	---	---	---	---

Byte	Bit	Signal	Description	Value "0"	Value "1"	Default
Electrical signals at sensor connection						
4	7	F1	Control input Input group 0	---	---	0
	6	F2	Control input Input group 0	---	---	0
	5	F3	Control input Input group 0	---	---	0
	4	F4	Control input Input group 0	---	---	---
	3	F5	Control input Input group 0	---	---	---
	2	F6	Control input Input group 1	---	---	---
	1	F7	Control input Input group 1	---	---	---
	0	F8	Control input Input group 1	---	---	---
5	7	F9	Control input Input group 1	---	---	0
	6	F10	Control input Input group 1	---	---	0
	5	RES1	Start input Protective function A	---	---	0
	4	RES2	Start input Protective function B	---	---	---
	3	EA1	EDM input Protective function A	---	---	---
	2	EA2	EDM input Protective function B	---	---	---
	1	EA3	---	---	---	---
	0	EA4	---	---	---	---
6	7	SE1	Linkage input	---	---	0
	6	SE2	Linkage input	---	---	0
	5	PNP-NPN	PNP/NPN changeover	npn	pnp	0
	4	A1	Output	---	---	---
	3	A2	Output	---	---	---
	2	A3	Output	---	---	---
	1	A4	Output	---	---	---
	0	MELD	Output	---	---	---
7	---	Reserved	---	---	---	---
8-11 uint32	31-0	SCAN	Consecutive numbering of scans Resetting to 0 by switching off	---	---	value

Byte	Bit	Signal	Description	Value "0"	Value "1"	Default
Protective function A						
12	7	A-ACTIVE	Protective function A is active / configured	off	Active	0
	6	A-WF-VIO	Status of active warning field Protective function A	violation	free	0
	5	A-PF-VIO	Status of active protective field Protective function A	violation	free	0
	4	A-RES	Start/restart interlock active Start Request A	off	Active	0
	3	A-CLEAR	Internal signal OSSD A	off	on	0
	2	Reserved	---	---	---	---
	1	Reserved	---	---	---	---
	0	Reserved	---	---	---	---
Field pair selection A						
13	7-4	A-BANK-SEL	Selected bank A Numbers 1 … 10	---	---	0
	3-0	A-PAIR-SEL 1	First selected field pair A Numbers 1 … 10	---	---	0
14	7-4	A-PAIR-SEL 2	Second selected field pair A Numbers 1 … 10	---	---	0
	3-0	A-PAIR-SEL 3	Third selected field pair A Numbers 1 … 10	---	---	0
Output signals A						
15	7	A-WF-VIO-SEG-1	Status of active warning field segment Protective function A	violation	free	0
	6	A-WF-VIO-SEG-2	Status of active warning field segment Protective function A	violation	free	0
	5	A-PF-VIO-SEG-1	Status of active protective field segment Protective function A	violation	free	0
	4	A-PF-VIO-SEG-2	Status of active protective field segment Protective function A	violation	free	0
	3	A-FP-SEL-1	Defined field pair selected Protective function A	off	selected	0
	2	A-FP-SEL-2	Defined field pair selected Protective function A	off	selected	0
	1	Reserved	---	---	---	---
	0	Reserved	---	---	---	---

16 Standards and legal regulations

In particular, the current version of the following national and international legal regulations apply for commissioning, technical tests and handling of safety sensors:

- Machinery Directive
- Low Voltage Directive
- Electromagnetic compatibility
- Use of Work Equipment Directive
- Directive on the restriction of the use of certain hazardous substances in electrical and electronic equipment
- OSHA
- Vibration IEC 60068-2-6
- Eye safety (measurement laser) IEC 60825-1
- Safety regulations
- Accident-prevention regulations and safety rules
- Ordinance on Industrial Safety and Health and employment protection act
- Product Safety Law (ProdSG)
- Standards for risk assessment, e.g.
  - ISO 12100
  - ISO 13849-1, -2
  - IEC 61508-1 to -7
  - IEC 62061
  - IEC 60204-1
- ISO 13849-1
- ISO 13855
- IEC 61496-3
- EN 1525
- IEC 62046

ПРОМЭЛЕКТРОНИКА / sales@prom-elec.com

17 Order guide and accessories

Scope of delivery

- 1 self-adhesive notice sign "Important notes and notes for the machine operator"
- 1 Original operating instructions "Safe implementation and operation" (PDF file on data carrier)
- 1 print document "Quick Start Guide RSL 400"

Tab. 17.1: Part numbers for RSL 420

Part no.	Article	Description
53800209	RSL420-S/CU416-5	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 3.0 m Connection: cable, 16-wire, length 5 m Ethernet: M12, 4-pin
53800210	RSL420-M/CU416-5	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 4.5 m Connection: cable, 16-wire, length 5 m Ethernet: M12, 4-pin
53800211	RSL420-L/CU416-5	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 6.5 m Connection: cable, 16-wire, length 5 m Ethernet: M12, 4-pin
53800212	RSL420-XL/CU416-5	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 8.25 m Connection: cable, 16-wire, length 5 m Ethernet: M12, 4-pin
53800213	RSL420-S/CU416-10	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 3.0 m Connection: cable, 16-wire, length 10 m Ethernet: M12, 4-pin
53800214	RSL420-M/CU416-10	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 4.5 m Connection: cable, 16-wire, length 10 m Ethernet: M12, 4-pin
53800215	RSL420-L/CU416-10	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 6.5 m Connection: cable, 16-wire, length 10 m Ethernet: M12, 4-pin
53800216	RSL420-XL/CU416-10	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 8.25 m Connection: cable, 16-wire, length 10 m Ethernet: M12, 4-pin
53800217	RSL420-S/CU416-25	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 3.0 m Connection: cable, 16-wire, length 25 m Ethernet: M12, 4-pin
53800218	RSL420-M/CU416-25	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 4.5 m Connection: cable, 16-wire, length 25 m Ethernet: M12, 4-pin
53800219	RSL420-L/CU416-25	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 6.5 m Connection: cable, 16-wire, length 25 m Ethernet: M12, 4-pin
53800220	RSL420-XL/CU416-25	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 8.25 m Connection: cable, 16-wire, length 25 m Ethernet: M12, 4-pin

Part no.	Article	Description
53800248	RSL420-S/CU411-RS4	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 3.0 m; RS4 adapter Connection: cable, 11-wire, length 0.6 m, SUB-D 15 Ethernet: M12, 4-pin
53800249	RSL420-M/CU411-RS4	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 4.5 m; RS4 adapter Connection: cable, 11-wire, length 0.6 m, SUB-D 15 Ethernet: M12, 4-pin
53800250	RSL420-L/CU411-RS4	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 6.5 m; RS4 adapter Connection: cable, 11-wire, length 0.6 m, SUB-D 15 Ethernet: M12, 4-pin
53800251	RSL420-S/CU416-300-WPU	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 3.0 m Connection: 0.3 m cable with 16-pin connector Ethernet: M12, 4-pin
53800252	RSL420-M/CU416-300-WPU	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 4.5 m Connection: 0.3 m cable with 16-pin connector Ethernet: M12, 4-pin
53800253	RSL420-L/CU416-300-WPU	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 6.5 m Connection: 0.3 m cable with 16-pin connector Ethernet: M12, 4-pin
53800254	RSL420-XL/CU416-300-WPU	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 8.25 m Connection: 0.3 m cable with 16-pin connector Ethernet: M12, 4-pin

Tab. 17.2: Part numbers for RSL 425

Part no.	Article	Description
53800267	RSL425-S/CU416-5	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 3.0 m Connection: cable, 16-wire, length 5 m Ethernet: M12, 4-pin
53800268	RSL425-M/CU416-5	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 4.5 m Connection: cable, 16-wire, length 5 m Ethernet: M12, 4-pin
53800269	RSL425-L/CU416-5	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 6.5 m Connection: cable, 16-wire, length 5 m Ethernet: M12, 4-pin
53800270	RSL425-XL/CU416-5	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 8.25 m Connection: cable, 16-wire, length 5 m Ethernet: M12, 4-pin

Part no.	Article	Description
53800271	RSL425-S/CU416-10	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 3.0 m Connection: cable, 16-wire, length 10 m Ethernet: M12, 4-pin
53800272	RSL425-M/CU416-10	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 4.5 m Connection: cable, 16-wire, length 10 m Ethernet: M12, 4-pin
53800273	RSL425-L/CU416-10	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 6.5 m Connection: cable, 16-wire, length 10 m Ethernet: M12, 4-pin
53800274	RSL425-XL/CU416-10	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 8.25 m Connection: cable, 16-wire, length 10 m Ethernet: M12, 4-pin
53800275	RSL425-S/CU416-25	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 3.0 m Connection: cable, 16-wire, length 25 m Ethernet: M12, 4-pin
53800276	RSL425-M/CU416-25	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 4.5 m Connection: cable, 16-wire, length 25 m Ethernet: M12, 4-pin
53800277	RSL425-L/CU416-25	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 6.5 m Connection: cable, 16-wire, length 25 m Ethernet: M12, 4-pin
53800278	RSL425-XL/CU416-25	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 8.25 m Connection: cable, 16-wire, length 25 m Ethernet: M12, 4-pin
53800279	RSL425-S/CU416-300-WPU	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 3.0 m Connection: 0.3 m cable with 16-pin connector Ethernet: M12, 4-pin
53800280	RSL425-M/CU416-300-WPU	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 4.5 m Connection: 0.3 m cable with 16-pin connector Ethernet: M12, 4-pin
53800281	RSL425-L/CU416-300-WPU	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 6.5 m Connection: 0.3 m cable with 16-pin connector Ethernet: M12, 4-pin

Part no.	Article	Description
53800282	RSL425-XL/CU416-300-WPU	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 8.25 m Connection: 0.3 m cable with 16-pin connector Ethernet: M12, 4-pin

Tab. 17.3: Components as spare parts

Part no.	Article	Description
Scanner units		
53800102	RSL420-S	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 3.0 m
53800106	RSL420-M	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 4.5 m
53800110	RSL420-L	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 6.5 m
53800114	RSL420-XL	1 OSSD pair; 10 field pairs; 4 IOs; protective field range max. 8.25 m
53800142	RSL425-S	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 3.0 m
53800144	RSL425-M	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 4.5 m
53800146	RSL425-L	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 6.5 m
53800148	RSL425-XL	1 OSSD pair; 10 field pairs; 4 IOs; data output for navigation, protective field range max. 8.25 m
Connection units		
53800118	CU416-5000	Connection: cable, 16-wire, length: 5 m Ethernet: M12, 4-pin
53800119	CU416-10000	Connection: cable, 16-wire, length: 10 m Ethernet: M12, 4-pin
53800120	CU416-25000	Connection: cable, 16-wire, length: 25 m Ethernet: M12, 4-pin
53800125	CU411-RS4	RS4 adapter Connection: cable, 11-wire, SUB-D 15, length: 0.6 m Ethernet: M12, 4-pin
53800180	CU416-300-WPU	Connection: cable, 16-wire, with M30 connector, length: 0.3 m Ethernet: M12, 4-pin

Tab. 17.4: Accessories

Part no.	Article	Description
Connection technology – Connection cables		
50137263	KD S-M30-16A-V1-050	Connection cable, 16-pin, 5 m
50137264	KD S-M30-16A-V1-100	Connection cable, 16-pin, 10 m
50137265	KD S-M30-16A-V1-250	Connection cable, 16-pin, 25 m
Connection technology – Connectors/sockets		
50137261	S U-M30-16A-M	Connection connector, 16-pin
50137262	D U-M30-16A-M	Connection socket, 16-pin
Connection technology – Ethernet interconnection cables		
50135080	KSS ET-M12-4A-RJ45-A-P7-020	Interconnection cable RJ45, 2 m
50135081	KSS ET-M12-4A-RJ45-A-P7-050	Interconnection cable RJ45, 5 m
50135082	KSS ET-M12-4A-RJ45-A-P7-100	Interconnection cable RJ45, 10 m
50135083	KSS ET-M12-4A-RJ45-A-P7-150	Interconnection cable RJ45, 15 m
50135084	KSS ET-M12-4A-RJ45-A-P7-300	Interconnection cable RJ45, 30 m
Connection technology – USB interconnection cables		
547822	AC-MSI-USB	USB-Mini-B interconnection cable, USB-A, 3 m
Connection technology – Adapters		
50134656	RSL400 M12 adapter	Adapter for the simple connection of an Ethernet cable to the front side of the device.
Mounting technology		
53800130	BTU800M	Laser scanner mounting system for vertical and horizontal alignment
53800132	BTF815M	Mounting bracket for floor mounting; scanning height 150 mm Mounting of safety sensor only in combination with BTU800M
53800133	BTF830M	Mounting bracket for floor mounting; scanning height 300 mm Mounting of safety sensor only in combination with BTU800M
53800134	BT840M	Mounting bracket for corner mounting on posts (chamfered corner) Direct mounting of the safety sensor
53800135	BT856M	Mounting bracket for corner mounting on posts Direct mounting of the safety sensor
53800131	BTP800M	Loop guard for optics cover Only in combination with BTU800M
53800136	BTU804MA	Mounting plate for mounting system RS4 / ROD4
53800137	BT800MA	Drilling template for adapter plate, RS4/ROD4
Cleaning fluids		
430400	Cleaning set 1	Cleaning fluid for plastic, 150 ml, cleaning cloths, 25x, soft, fuzz-free
430410	Cleaning set 2	Cleaning fluid for plastic, 1,000 ml, cleaning cloths, 100x, soft, fuzz-free

18 EC Declaration of Conformity

SMART
SENSOR
BUSINESS

Leuze electronic
the sensor people

EU-/EG-KONFORMITÄTS-ERKLÄRUNG

Hersteller:

Produktbeschreibung:
Sicherheits-Laserscanner für Personenschutz, Berührungslos wirkende Schutzeinrichtung, Sicherheitsbauteil nach 2006/42/EG Anhang IV
RSL 400/RSL 400P
Seriennummer siehe Typschild

Die alleinige Verantwortung für die Ausstellung dieser Konformitätserklärung trägt der Hersteller.

Der oben beschriebene Gegenstand der Erklärung erfüllt die einschlägigen Harmonisierungsrechts-vorschriften der Union:

Angewandte EU-/EG-Richtlinie(n):
2006/42/EG (*1)
2014/30/EU
2014/53/EU (*2)

EU/EC DECLARATION OF CONFORMITY

Manufacturer:
Leuze electronic GmbH + Co. KG
In der Braike 1, PO Box 1111
73277 Owen, Germany

Description of product:
Safety Laser Scanner for personnel protection, Active opto-electronic protective device, safety component in acc. with 2006/42/EC annex IV
RSL 400/RSL 400P
Serial no. see name plates

This declaration of conformity is issued under the sole responsibility of the manufacturer.

The object of the declaration described above is in conformity with the relevant Union harmonisation legislation:

Applied EU/EC Directive(s):
2006/42/EC (*1)
2014/30/EU
2014/53/EU (*2)

DECLARATION UE/CE DE CONFORMITE

Constructeur:

Description de produit:
Scanner laser de sécurité pour la protection des personnes, Equipement de protection électrosensible, Elément de sécurité selon 2006/42/CE annexe IV
RSL 400/RSL 400P
N° série voir plaques signalétiques

La présente déclaration de conformité est établie sous la seule responsabilité du fabricant.

L'objet de la déclaration décrit ci-dessus est conforme à la législation d'harmonisation de l'Union applicable:

Directive(s) UE/CE appliquées:
2006/42/CE (*1)
2014/30/UE
2014/53/UE (*2)

Angewandte harmonisierte Normen / Applied harmonized standards / Normes harmonisées appliquées:

EN ISO 13849-1:2015
EN 55022:2010+AC:2011
EN 62061:2005+A1:2013 (SILCL 2)
EN 61000-6-4:2007+A1:2011
EN 61496-1:2013

Angewandte technische Spezifikationen / Applied technical specifications / Spécifications techniques appliquées:

EN 61508-1/-2/-3/-4:2010 (SIL 2)
IEC 61496-3 (ed.2)

Notified Body
(*1) TÜV-SÜD PRODUCT SERVICE GmbH, Zertifizierungsstelle, Ridlerstraße 65, D-80339 München, NB 0123, Z10 15 06 68636 004
Dokumentationsbevollmächtigter ist der genannte Hersteller, Kontakt: quality@leuze.de.
Authorized for documentation is the stated manufacturer, contact: quality@leuze.de.
Autorisé pour documentation est le constructeur déclaré, contact: quality@leuze.de

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(*2) Nur für Geräte mit Funkmodul; Only for devices with radio module; Seulement pour les appareils avec module radio.

14.06.2018
Datum / Date / Date

Ulrich Balbach,
Geschäftsführer / Managing Director / Gérant

i.A. Fabien Zelenda
Quality Management Central Functions

Leuze electronic GmbH + Co. KG
In der Braike 1
D-73277 Owen
Telefon +49 (0) 7021 573-0
Telefax +49 (0) 7021 573-199
info@leuze.de
www.leuze.com

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Leuze electronic GmbH + Co. KG, Sitz Owen, Registergericht Stuttgart, HRA 230712
Persönlich haftende Gesellschafterin Leuze electronic Geschäftsführungs-GmbH,
Sitz Owen, Registergericht Stuttgart, HRB 230550
Geschäftsführer: Ulrich Balbach
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Only our current Terms and Conditions of Sale and Delivery shall apply